

## Section 15: Shift Theorems

### Theorem (translation in $s$ )

Suppose  $\mathcal{L}\{f(t)\} = F(s)$ . Then for any real number  $a$

$$\mathcal{L}\{e^{at}f(t)\} = F(s - a).$$

### Theorem (translation in $t$ )

If  $F(s) = \mathcal{L}\{f(t)\}$  and  $a > 0$ , then

$$\mathcal{L}\{f(t - a)\mathcal{U}(t - a)\} = e^{-as}F(s).$$

Recall that the unit step function was defined as

$$\mathcal{U}(t - a) = \begin{cases} 0, & 0 \leq t < a \\ 1, & t \geq a \end{cases} \quad \text{for } a > 0$$

## A Couple of Useful Results

Another formulation of this translation theorem is

$$(1) \quad \mathcal{L}\{g(t)\mathcal{U}(t-a)\} = e^{-as}\mathcal{L}\{g(t+a)\}.$$

Since  $g(t) = g((t+a)-a)$

Example: Find  $\mathcal{L}\{\cos t \mathcal{U}(t - \frac{\pi}{2})\} = e^{-\frac{\pi}{2}s} \mathcal{L}\{\cos(t + \frac{\pi}{2})\}$

Note  $\cos(t + \frac{\pi}{2}) = \cos t \cos \frac{\pi}{2} - \sin t \sin \frac{\pi}{2}$

$$= \cos t (0) - \sin t (1)$$
$$= -\sin t$$

$$\begin{aligned} \text{So } \mathcal{L}\left\{\cos t \mathcal{U}\left(t - \frac{\pi}{2}\right)\right\} &= e^{-\frac{\pi}{2}s} \mathcal{L}\left\{\cos\left(t + \frac{\pi}{2}\right)\right\} \\ &= e^{-\frac{\pi}{2}s} \mathcal{L}\{-\sin t\} \\ &= -e^{-\frac{\pi}{2}s} \mathcal{L}\{\sin t\} \\ &= -e^{-\frac{\pi}{2}s} \left(\frac{1}{s^2 + 1}\right) \\ &= -\frac{e^{-\frac{\pi}{2}s}}{s^2 + 1} \end{aligned}$$

## A Couple of Useful Results

The inverse form of this translation theorem is

$$(2) \quad \mathcal{L}^{-1}\{e^{-as}F(s)\} = f(t-a)\mathcal{U}(t-a).$$

where  $f(t) = \mathcal{L}^{-1}\{F(s)\}$

Example: Find  $\mathcal{L}^{-1}\left\{\frac{e^{-2s}}{s(s+1)}\right\}$

we need to find  $\mathcal{L}^{-1}\left\{\frac{1}{s(s+1)}\right\}$ . Do a partial

fraction decomp

$$\frac{1}{s(s+1)} = \frac{A}{s} + \frac{B}{s+1} \Rightarrow 1 = A(s+1) + Bs$$

set  $s=0$      $1 = A(1)$      $A=1$   
 $s=-1$      $1 = B(-1)$      $B=-1$

$$\begin{aligned} \text{so } \mathcal{L}^{-1}\left\{\frac{1}{s(s+1)}\right\} &= \mathcal{L}^{-1}\left\{\frac{1}{s}\right\} - \mathcal{L}^{-1}\left\{\frac{1}{s+1}\right\} \\ &= 1 - e^{-t} \quad \leftarrow \text{this is } f(t) \end{aligned}$$

$$\text{so } \mathcal{L}^{-1}\left\{\frac{e^{-2s}}{s(s+1)}\right\} = (1 - e^{-(t-2)})u(t-2)$$

↑  
this is  $f(t-2)u(t-2)$

## Section 16: Laplace Transforms of Derivatives and IVPs

Suppose  $f$  has a Laplace transform and that  $f$  is differentiable on  $[0, \infty)$ . Obtain an expression for the Laplace transform of  $f'(t)$ . (Assume  $f$  is of exponential order  $c$  for some  $c$ .)

$$\mathcal{L}\{f'(t)\} = \int_0^{\infty} e^{-st} f'(t) dt$$

Integrate by parts

$$u = e^{-st} \quad dv = f'(t) dt$$

$$= e^{-st} f(t) \Big|_0^{\infty} - \int_0^{\infty} -s e^{-st} f(t) dt \quad du = -s e^{-st} dt \quad v = f(t)$$

$$= (0 - e^0 f(0)) + s \int_0^{\infty} e^{-st} f(t) dt$$

$$= s \mathcal{L}\{f(t)\} - f(0)$$

## Transforms of Derivatives

If  $\mathcal{L}\{f(t)\} = F(s)$ , we have  $\mathcal{L}\{f'(t)\} = sF(s) - f(0)$ . We can use this relationship recursively to obtain Laplace transforms for higher derivatives of  $f$ .

For example

$$\begin{aligned}\mathcal{L}\{f''(t)\} &= s\mathcal{L}\{f'(t)\} - f'(0) \\ &= s(sF(s) - f(0)) - f'(0) \\ &= s^2F(s) - sf(0) - f'(0)\end{aligned}$$

## Transforms of Derivatives

For  $y = y(t)$  defined on  $[0, \infty)$  having derivatives  $y'$ ,  $y''$  and so forth, if

$$\mathcal{L}\{y(t)\} = Y(s),$$

then

$$\mathcal{L}\left\{\frac{dy}{dt}\right\} = sY(s) - y(0),$$

$$\mathcal{L}\left\{\frac{d^2y}{dt^2}\right\} = s^2Y(s) - sy(0) - y'(0),$$

$\vdots$

$$\mathcal{L}\left\{\frac{d^ny}{dt^n}\right\} = s^nY(s) - s^{n-1}y(0) - s^{n-2}y'(0) - \dots - y^{(n-1)}(0).$$



## Differential Equation

For constants  $a$ ,  $b$ , and  $c$ , take the Laplace transform of both sides of the equation

$$ay'' + by' + cy = g(t), \quad y(0) = y_0, \quad y'(0) = y_1$$

We'll take the transform of both sides of the ODE

$$\mathcal{L}\{ay'' + by' + cy\} = \mathcal{L}\{g(t)\}.$$

$$\text{Let } \mathcal{L}\{y(t)\} = Y(s) \text{ and } \mathcal{L}\{g(t)\} = G(s)$$

$$a\mathcal{L}\{y''\} + b\mathcal{L}\{y'\} + c\mathcal{L}\{y\} = \mathcal{L}\{g\}$$

$$a(s^2Y(s) - sy(0) - y'(0)) + b(sY(s) - y(0)) + cY(s) = G(s)$$

Let's isolate  $Y(s)$ .

$$as^2 Y(s) - asy(0) - ay'(0) + bsY(s) - by(0) + cY(s) = G(s)$$

$$(as^2 + bs + c)Y(s) - ay_0s - ay_1 - by_0 = G(s)$$

$$(as^2 + bs + c)Y(s) = ay_0s + ay_1 + by_0 + G(s)$$

The ODE is  $ay'' + by' + cy = g(t)$

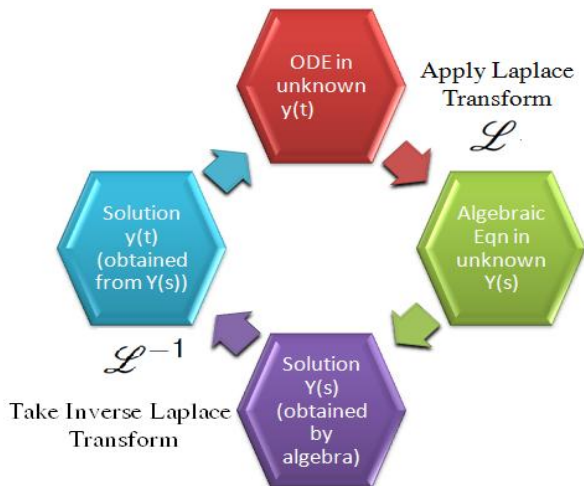
So  $as^2 + bs + c$  is the characteristic polynomial

$$Y(s) = \frac{ay_0s + ay_1 + by_0}{as^2 + bs + c} + \frac{G(s)}{as^2 + bs + c}$$

The solution to the IVP is

$$y(t) = \mathcal{L}^{-1}\{Y(s)\}$$

# Solving IVPs



**Figure:** We use the Laplace transform to turn our DE into an algebraic equation. Solve this transformed equation, and then transform back.

## General Form

We get

$$Y(s) = \frac{Q(s)}{P(s)} + \frac{G(s)}{P(s)}$$

where  $Q$  is a polynomial with coefficients determined by the initial conditions,  $G$  is the Laplace transform of  $g(t)$  and  $P$  is the **characteristic polynomial** of the original equation.

$\mathcal{L}^{-1} \left\{ \frac{Q(s)}{P(s)} \right\}$  is called the **zero input response**,

and

$\mathcal{L}^{-1} \left\{ \frac{G(s)}{P(s)} \right\}$  is called the **zero state response**.