August 15 Math 2306 sec. 53 Fall 2018

Section 1: Concepts and Terminology

We have defined *differential equations*, and started to define certain characteristics and categories:

- Ordinary differential equations (ODEs) have one independent variable; partial differential equations (PDEs) have two or more independent variables.
- The order of an equation is equal to largest order of derivative appearing in the equation.
- ► An *n*th order equation in *normal form* looks like $\frac{d^n y}{dx^n} = f(x, y, y', ..., y^{(n-1)})$ for some function *f*.

Classifications

Linearity: An *n*th order differential equation is said to be **linear** if it can be written in the form

$$a_n(x)rac{d^n y}{dx^n} + a_{n-1}(x)rac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x)rac{dy}{dx} + a_0(x)y = g(x).$$

The key characteristics here are:

- y and any of its derivatives can only appear as themselves (to the first power),
- coefficients of y and its derivatives may depend on the independent variable, but not on y or its derivatives,
- ► if you replace y on the left side with Cy for any constant C, it factors giving you C times the original left side,
- ► if you replace y on the left with y₁ + y₂ (a sum of y's), you can distribute to get a sum of the left side with y₁ and the same left side with y₂.

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If we define the operation *L* by

$$Ly = a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y$$

then L is a linear operator in the sense that

L(Cy) = CLy for any constant C, and

$$L(y_1 + y_2) = Ly_1 + Ly_2,$$

for any pair of sufficiently differentiable functions y_1 and y_2 , y_2 , y_2 , y_3 , y_3 , y_4 , y_2 , y_3 , y_4 , y_5 , y_5 , y_1 , y_2 , y_3 , y_4 , y_5 , y_5 , y_1 , y_2 , y_3 , y_4 , y_5 ,

Examples (Linear -vs- Nonlinear)

$$a_n(x)\frac{d^n y}{dx^n} + a_{n-1}(x)\frac{d^{n-1} y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x).$$

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The following are linear.

y'' + 4y = 0Q2 (x) y" + Q, (x) y + Q. (x) y = & (x) $a_{1}(x) = 1$ $Q_{1}(x) = 0$ $G_{\alpha}(\mathbf{x}) = \mathbf{y}$ g(x) = 0

$$t^{2} \frac{d^{2}x}{dt^{2}} + 2t \frac{dx}{dt} - x = e^{t}$$

$$z^{(t)} \times + a_{1}(t) \times + a_{0}(t) \times = g | t$$

$$a_{2}(t) = t^{2}$$

$$g | t = e^{t}$$

$$a_{0}(t) = -1$$

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Examples (Linear -vs- Nonlinear)

$$a_n(x)\frac{d^n y}{dx^n} + a_{n-1}(x)\frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x).$$

The following are nonlinear.

$$\frac{d^{3}y}{dx^{3}} + \left(\frac{dy}{dx}\right)^{4} = x^{3}$$

$$y^{\prime\prime\prime} + \left(y^{\prime}\right)^{3}y^{\prime} = x^{3}$$

$$\left(\frac{dy}{dx}\right)^{4}_{1s} = nonlineor$$

$$+erm$$

$$u'' + u' = \cos u$$

Example: Classification

Identify the independent and dependent variables. Determine the order of the equation. State whether it is linear or nonlinear.

(a)
$$y''+2ty' = \cos t+y-y'''$$

 $y'''+y''+2ty'-y = \cos t$
 $y - dependent$
 $t - in dependent$
 $or den 15 = 3$

(b) $\ddot{\theta} + \frac{g}{\ell} \sin \theta = 0$ g and ℓ are constant Independent variable is time (t) O- dependent variable 2nd orden Non Dinear Sin O is a nonlinear term Q: dependent

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Solution of $F(x, y, y', ..., y^{(n)}) = 0$ (*)

Definition: A function ϕ defined on an interval¹ / and possessing at least *n* continuous derivatives on *I* is a **solution** of (*) on *I* if upon substitution (i.e. setting $y = \phi(x)$) the equation reduces to an identity.

Definition: An **implicit solution** of (*) is a relation G(x, y) = 0 provided there exists at least one function $y = \phi$ that satisfies both the differential equation (*) and this relation.

¹ The interval is called the domain of the solution or the interval of definition.

Examples:

Verify that the given function is a solution of the ODE on the indicated interval.

$$\phi(t) = 3e^{2t}, \quad I = (-\infty, \infty), \quad \frac{d^2y}{dt^2} - \frac{dy}{dt} - 2y = 0$$

$$\phi \text{ has derivatives of all orders on I.}$$

In paticular, it has at least two derivatives on I.
To finish the verification, we set $y = \phi(t)$
 $y' = \phi'(t) = 6e^{2t}$, $y'' = \phi''(t) = 12e^{2t}$
 $y'' - y' - 2y = 0$

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 $12e^{2t} - 6e^{2t} - 2(3e^{2t}) =$ $12e^{2+} - 6e^{2+} - 6e^{2+} =$ $(12-6-6)e^{2t} =$ 0 = 0 on identity. So p is a solution on I.

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Verify that the relation(left) defines and implicit solution of the differential equation (right).

$$y^2 - 2x^2y = 1$$
, $\frac{dy}{dx} = \frac{2xy}{y - x^2}$
We can show that if y satisfies the relation,
then it satisfies the ODE using implicit
differentiation.
 $y^2 - 7x^2y = 1 \implies 2y \frac{dy}{dx} - 4xy - 2x^2 \frac{dy}{dx} = 0$
Using som algebra

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It may not be possible to clearly identify the domain of definition of an implicit solution.

$$y \frac{dy}{dx} - 2xy - x^{2} \frac{dy}{dx} = 0$$

$$(y - x^{2}) \frac{dy}{dx} = 2xy \quad \text{for } y - x^{2} \neq 0$$

$$\frac{dy}{dx} = \frac{2xy}{y - x^{2}} \quad \text{this is the}$$

$$ODE$$
Hence the relation defines an implicit
so lation.

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