

## Section 7.5: Trigonometric Equations

In this section, we wish to consider **conditional** equations involving trigonometric functions. Our goal will be to find a **solution set**.

Some examples of trigonometric equations include

$$2 \cos(x) - 1 = 0, \quad \sin \theta \cos \theta + \sin \theta = 0, \quad 2 \tan^2 x - \tan x - 1 = 0,$$

$$\csc 2\theta = \sec 2\theta, \quad \tan^2(3x) = 3, \quad \text{and so forth.}$$

We'll use trigonometric identities, our knowledge of some trig values, and inverse trigonometric functions as needed.

## A General Observation

When solving more complicated trigonometric equations, we will try to rewrite the problem in the form of **one or more** equations that look like

$$\text{One Trig Function} = \text{One Number}$$

We typically determine solution(s) in one period, and then extend those solutions if required.

## Solutions on an Indicated Interval

(a) Find all solutions of the equation  $\sec^2(x) + \tan(x) = 1$  on the interval  $0 \leq x < 2\pi$ .

$$\sec^2 x + \tan x = 1$$

$$\tan^2 x + 1 = \sec^2 x$$

$$\tan^2 x + 1 + \tan x = 1$$

subtract 1

$$\tan^2 x + \tan x = 0$$

$$\tan x (\tan x + 1) = 0$$

By the zero product property

$$\tan x = 0 \quad \text{or} \quad \tan x + 1 = 0$$

$$\tan x = 0 \quad \text{or} \quad \tan x = -1$$

$$x = 0 \quad \text{or} \quad x = \pi$$

$\tan \frac{\pi}{4} = 1$ ,  $\frac{\pi}{4}$  is the reference angle

$\tan x = -1$  in quad II and IV

We get 2 solutions

$$x = \frac{3\pi}{4} \quad \text{or} \quad x = \frac{7\pi}{4}$$

The solution set is

$$\left\{ 0, \pi, \frac{3\pi}{4}, \frac{7\pi}{4} \right\}$$

## Solutions on an Indicated Interval

(b) Find all solutions of the equation  $\cos^2(2x) = \frac{1}{4}$  on the interval  $0 \leq x < 2\pi$ .

We'll solve for  $2x$  first, then divide by 2.

$$\text{For } 0 \leq x < 2\pi, \quad 2 \cdot 0 \leq 2x < 2(2\pi)$$

$$0 \leq 2x < 4\pi$$

So  $2x$  will be in 2 full rotations.

$$\cos^2(2x) = \frac{1}{4} \Rightarrow \cos(2x) = \frac{1}{2} \quad \text{or} \quad \cos(2x) = -\frac{1}{2}$$

The reference angle will be  $\frac{\pi}{3}$  for all solutions  $2x$ .

$$\cos(2x) = \frac{1}{2} \quad (\text{solutions in 2 rotations, quad I + IV})$$

$$2x = \frac{\pi}{3}, \quad 2x = \frac{5\pi}{3}, \quad 2x = \frac{7\pi}{3}, \quad 2x = \frac{11\pi}{3}$$

$$x = \frac{\pi}{6}, \quad x = \frac{5\pi}{6}, \quad x = \frac{7\pi}{6}, \quad x = \frac{11\pi}{6}$$

$$\cos(2x) = -\frac{1}{2} \quad (\text{2 rotations, quads II and III})$$

$$2x = \frac{2\pi}{3}, \quad 2x = \frac{4\pi}{3}, \quad 2x = \frac{8\pi}{3}, \quad 2x = \frac{10\pi}{3}$$

$$x = \frac{2\pi}{6}, \quad x = \frac{4\pi}{6}, \quad x = \frac{8\pi}{6}, \quad x = \frac{10\pi}{6}$$

The solution set is

$$\left\{ \frac{\pi}{6}, \frac{5\pi}{6}, \frac{7\pi}{6}, \frac{11\pi}{6}, \frac{2\pi}{6}, \frac{4\pi}{6}, \frac{8\pi}{6}, \frac{10\pi}{6} \right\}$$



## Solutions on an Indicated Interval

(c) Find all solutions of the equation  $\sin^2(3x) + 3\sin(3x) - 4 = 0$  on the interval  $0 \leq x < 2\pi$ .

$$\text{If } 0 \leq x < 2\pi, \text{ then } 3 \cdot 0 \leq 3x < 3(2\pi)$$

$$0 \leq 3x < 6\pi$$

we went  $3x$  in 3 full rotations

$$\sin^2(3x) + 3\sin(3x) - 4 = 0$$

$$u^2 + 3u - 4 = 0$$

$$(u + 4)(u - 1) = 0$$

$$(\sin(3x) + 4)(\sin(3x) - 1) = 0$$

$$\sin(3x) + 4 = 0 \quad \text{or} \quad \sin(3x) - 1 = 0$$

$$\sin(3x) = -4 \quad \text{or} \quad \sin(3x) = 1$$

$$-1 \leq \sin \theta \leq 1$$

for all real  $\theta$

no solutions

In one rotation, there is  
one solution

$$3x = \frac{\pi}{2}$$

In 3 rotations we get

$$3x = \frac{\pi}{2}, \quad 3x = \frac{5\pi}{2}, \quad 3x = \frac{9\pi}{2}$$

$$x = \frac{\pi}{6}, \quad x = \frac{5\pi}{6}, \quad x = \frac{9\pi}{6}$$

The solution set is

$$\left\{ \frac{\pi}{6}, \frac{5\pi}{6}, \frac{9\pi}{6} \right\}$$

## Using Inverse Trigonometric Functions

Find all solutions of the equation  $4 \sin \theta = 1$ . Express answers exactly in terms of the inverse sine.

$$4 \sin \theta = 1 \Rightarrow \sin \theta = \frac{1}{4}$$

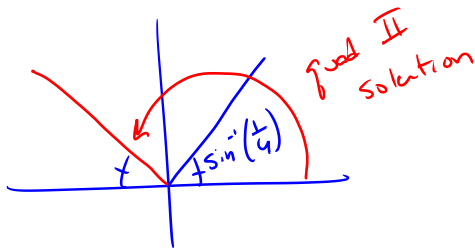
We'll get the solutions in one rotation, then add  $2\pi n$  for integers  $n$ .

In one rotation, there are 2 solutions.

One is  $\sin^{-1}\left(\frac{1}{4}\right)$  a quadrant I answer

We need to find the quadrant II solution.

The second solution has  $\sin^{-1}\left(\frac{1}{4}\right)$  as its reference angle.



From the diagram, the quad II answer

$$\text{is } \pi - \sin^{-1}\left(\frac{1}{4}\right)$$

The basic solutions are

$$\sin^{-1}\left(\frac{1}{4}\right) \text{ and } \pi - \sin^{-1}\left(\frac{1}{4}\right)$$

All solutions are given by

$$\theta = \sin^{-1}\left(\frac{1}{4}\right) + 2\pi n, \text{ or}$$

$$\theta = \pi - \sin^{-1}\left(\frac{1}{4}\right) + 2\pi n \quad \text{for } n \text{ any integer}$$