

# Exam 2 Math 3260 sec. 51

Spring 2020

Name: \_\_\_\_\_ **Solutions** \_\_\_\_\_

Your signature (required) confirms that you agree to practice academic honesty.

Signature: \_\_\_\_\_

Problem	Points
1	
2	
3	
4	
5	
6	
7	

**INSTRUCTIONS:** There are 7 problems worth 20 points each. Do any 5 problems (I'll count your best 5). **No calculator use is allowed, and no calculator use is needed. Use of a textbook, notes, calculator or smart device is strictly prohibited. Illicit use of any additional resource will result in a grade of zero on this exam as well as a formal allegation of academic misconduct.** Show all of your work on the paper provided to receive full credit.

1. Find bases for  $\text{Nul}(A)$  and  $\text{Col}(A)$ .  $A$  and the rref of  $A$  are given.

$$A = \begin{bmatrix} -2 & 2 & -3 & -2 & -8 \\ 3 & -3 & 3 & 1 & 10 \\ 2 & -2 & 2 & 0 & 4 \end{bmatrix}$$

$$\text{rref}(A) = \begin{bmatrix} 1 & -1 & 0 & 0 & 6 \\ 0 & 0 & 1 & 0 & -4 \\ 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$

If  $A\vec{x} = \vec{0}$ ,  $x_1 = x_2 - 6x_5$   
 $x_3 = 4x_5$   
 $x_4 = -4x_5$   
 $x_2, x_5$  - free

A Basis for :

$\text{Nul } A$  is  $\left\{ \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} 6 \\ 0 \\ 4 \\ -4 \\ -1 \end{bmatrix} \right\}$

$\vec{x} = x_2 \begin{bmatrix} 1 \\ -1 \\ 0 \\ 0 \\ 0 \end{bmatrix} + x_5 \begin{bmatrix} -6 \\ 0 \\ 4 \\ -4 \\ 1 \end{bmatrix}$

$\text{Col } A$  is  $\left\{ \begin{bmatrix} -2 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} -3 \\ 3 \\ 2 \end{bmatrix}, \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} \right\}$

Pivot columns are 1, 3, 4

View vectors in  $\mathbb{R}^n$  as  $n \times 1$  matrices. For vectors  $\mathbf{u}$  and  $\mathbf{v}$  in  $\mathbb{R}^n$ , the matrix product  $\mathbf{u}^T \mathbf{v}$  is a  $1 \times 1$  matrix (called the scalar product) that is usually written as a number without brackets. The matrix product  $\mathbf{u} \mathbf{v}^T$  is an  $n \times n$  matrix (called the outer product).

2. Consider the following vectors.

$$\mathbf{u} = \begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} a \\ b \\ c \end{bmatrix}, \quad \text{and} \quad \mathbf{x} = \begin{bmatrix} 3 \\ -2 \end{bmatrix} \quad (a, b, c \text{ are real numbers}).$$

(a) Compute  $\mathbf{u}^T \mathbf{v}$ .

$$\begin{array}{ccc} \vec{u}^T & \vec{v} & \\ 1 \times 3 & 3 \times 1 & \\ & & 1 \times 1 \end{array} \quad = \quad [2 \ -2 \ 3] \begin{bmatrix} a \\ b \\ c \end{bmatrix} = 2a - 2b + 3c$$

(b) Compute  $\mathbf{u} \mathbf{v}^T$ .

$$\begin{array}{ccc} \vec{u} & \vec{v}^T & \\ 3 \times 1 & 1 \times 3 & \\ & & 3 \times 3 \end{array} \quad = \quad \begin{bmatrix} 2 \\ -2 \\ 3 \end{bmatrix} [a \ b \ c] = \begin{bmatrix} 2a & 2b & 2c \\ -2a & -2b & -2c \\ 3a & 3b & 3c \end{bmatrix}$$

(c) Compute the  $2 \times 2$  matrix  $\mathbf{x} \mathbf{x}^T$ .

$$\begin{array}{ccc} \vec{x} & \vec{x}^T & \\ 2 \times 1 & 1 \times 2 & \\ & & 2 \times 2 \end{array} \quad = \quad \begin{bmatrix} 3 \\ -2 \end{bmatrix} [3 \ -2] = \begin{bmatrix} 9 & -6 \\ -6 & 4 \end{bmatrix}$$

(d) Determine whether  $\mathbf{x} \mathbf{x}^T$  is singular or nonsingular. If nonsingular, compute its inverse.

$$\det(\vec{x} \vec{x}^T) = 9(4) - (-6)^2 = 36 - 36 = 0$$

$\vec{x} \vec{x}^T$  is singular

3. Answer each short computational problem. Here,  $I_n$  is the  $n \times n$  identity matrix.

(a) Suppose  $A$ ,  $B$ , and  $C$  are  $n \times n$  invertible matrices. Does the equation

$$C^{-1}(X + A)B^{-1} = I_n$$

have a solution  $X$ ? If so, find it.

$$C^{-1}(X+A)B^{-1} = I \Rightarrow C \tilde{C}^{-1}(X+A) \tilde{B}^{-1} B = C I B$$

$$X + A = CB \Rightarrow \boxed{X = CB - A}$$

(b) Suppose  $A$  and  $B$  are  $3 \times 3$  matrices with  $\det(A) = -2$  and  $\det(B) = 5$ . Evaluate each of

(i)  $\det(A^3) = \underline{(-2)^3 = -8}$

(ii)  $\det(B^T A) = \underline{5(-2) = -10}$

(iii)  $\det(A^{-1}B) = \underline{\frac{1}{2}(5) = \frac{5}{2}}$

(iv)  $\det(B^{-1}AB) = \underline{\frac{1}{5}(-2)5 = -2}$

(c) Suppose  $\det \begin{bmatrix} a & b & c \\ d & e & f \\ g & h & i \end{bmatrix} = 4$ . Evaluate each determinant.

$$\det \begin{bmatrix} a & b & c \\ d & e & f \\ 3g & 3h & 3i \end{bmatrix} = \underline{12} \quad 3R_3 \rightarrow R_3$$

$$\det \begin{bmatrix} g & h & i \\ d & e & f \\ a & b & c \end{bmatrix} = \underline{-4} \quad R_1 \leftrightarrow R_3$$

$$\det \begin{bmatrix} a & b & c \\ d+2a & e+2b & f+2c \\ g & h & i \end{bmatrix} = \underline{4} \quad 2R_1 + R_2 \rightarrow R_2$$

4. Determine the values of the parameter  $s$  for which the system of equations has a unique solution. For those values of  $s$  use Cramer's rule to obtain the solutions  $X$  and  $Y$ .

$$\begin{aligned} sX - 2sY &= 1 \\ 3X + 12sY &= -1 \end{aligned} \quad \begin{matrix} \begin{bmatrix} s & -2s \\ 3 & 12s \end{bmatrix} \begin{bmatrix} X \\ Y \end{bmatrix} = \begin{bmatrix} 1 \\ -1 \end{bmatrix} \\ A \qquad \qquad \qquad \underline{b}$$

$$\det(A) = 12s^2 + 6s = 6s(2s+1) \quad \det(A) = 0 \text{ if } s=0 \text{ or } s = -\frac{1}{2}$$

There is a unique solution if  $s \neq 0$  and  $s \neq -\frac{1}{2}$ .

$$\det(A_1(\underline{b})) = \begin{vmatrix} 1 & -2s \\ -1 & 12s \end{vmatrix} = 12s - 2s = 10s$$

$$\det(A_2(\underline{b})) = \begin{vmatrix} s & 1 \\ 3 & -1 \end{vmatrix} = -s - 3 = -(s+3)$$

$$\text{For } s \neq 0 \text{ and } s \neq -\frac{1}{2} \quad X = \frac{10s}{6s(2s+1)} = \frac{5}{3(2s+1)}$$

$$Y = \frac{-(s+3)}{6s(2s+1)}$$

5. Show that the linear transformation is invertible, and find a formula for  $T^{-1}$ .  $T: \mathbb{R}^2 \rightarrow \mathbb{R}^2$  where  $T(x_1, x_2) = (5x_1 + 4x_2, 2x_1 + 2x_2)$ .

$$\text{Standard matrix } A = [T(\underline{e}_1) \ T(\underline{e}_2)] = \begin{bmatrix} 5 & 4 \\ 2 & 2 \end{bmatrix}$$

$$\det(A) = 10 - 8 = 2 \neq 0 \quad T^{-1} \text{ exists.}$$

$$A^{-1} = \frac{1}{2} \begin{bmatrix} 2 & -4 \\ -2 & 5 \end{bmatrix} = \begin{bmatrix} 1 & -2 \\ -1 & \frac{5}{2} \end{bmatrix}$$

$$T^{-1}(\underline{x}) = A^{-1} \underline{x} = \begin{bmatrix} 1 & -2 \\ -1 & \frac{5}{2} \end{bmatrix} \begin{bmatrix} x_1 \\ x_2 \end{bmatrix} = \begin{bmatrix} x_1 - 2x_2 \\ -x_1 + \frac{5}{2}x_2 \end{bmatrix}$$

$$\overline{T}^{-1}(x_1, x_2) = \left( x_1 - 2x_2, -x_1 + \frac{5}{2}x_2 \right)$$

6. Find a basis for each subspace of the indicated vector space.

- (a) The set of vectors in  $\mathbb{R}^3$  that are on the plane  $x + 2y - 5z = 0$ . (Hint: Think of the equation as a homogeneous linear system.)

$$x = -2y + 5z, \quad y, z \text{ - free}$$

$$\vec{x} = y \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix} + z \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix}$$

$$\text{A basis is } \left\{ \begin{bmatrix} -2 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} 5 \\ 0 \\ 1 \end{bmatrix} \right\}$$

- (b) The set of matrices in  $M^{2 \times 2}$  of the form  $\begin{bmatrix} a & b \\ 0 & 2b \end{bmatrix}$ .

$$\begin{bmatrix} a & b \\ 0 & 2b \end{bmatrix} = a \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} + b \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix}$$

$$\text{A basis is } \left\{ \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix}, \begin{bmatrix} 0 & 1 \\ 0 & 2 \end{bmatrix} \right\}$$

7. Recall that  $\mathbb{P}_n$  denotes the vectors space consisting of all polynomials of degree at most  $n$ .

Consider the linear transformation  $T : \mathbb{P}_2 \rightarrow \mathbb{R}^2$  defined by  $T(\mathbf{p}) = \begin{bmatrix} 2\mathbf{p}(0) \\ -\mathbf{p}(0) \end{bmatrix}$ .

(a) Evaluate  $T(\mathbf{p}_1)$  if  $\mathbf{p}_1(t) = 2 + t - t^2$

$$\vec{p}_1(0) = 2 \quad T(\vec{p}_1) = \begin{bmatrix} 4 \\ -2 \end{bmatrix}$$

(b) Evaluate  $T(\mathbf{p}_2)$  if  $\mathbf{p}_2(t) = 2t$

$$\vec{p}_2(0) = 0 \quad T(\vec{p}_2) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

(c) Evaluate  $T(\mathbf{p}_3)$  if  $\mathbf{p}_3(t) = 4t^2 + 2t - 3$

$$\vec{p}_3(0) = -3 \quad T(\vec{p}_3) = \begin{bmatrix} -6 \\ 3 \end{bmatrix}$$

(d) Find a vector  $\mathbf{u}$  in  $\mathbb{R}^2$  that spans the range of  $T$ .

$$T(\vec{p}) = \vec{p}(0) \begin{bmatrix} 2 \\ -1 \end{bmatrix} \quad \text{we can take } \vec{u} = \begin{bmatrix} 2 \\ -1 \end{bmatrix}$$

(e) Find any vector  $\mathbf{p}$  in  $\mathbb{P}_2$  that is in the kernel of  $T$

$$\text{Using part (b) above } T(\vec{p}_2) = \begin{bmatrix} 0 \\ 0 \end{bmatrix}$$

$$\text{So we can choose } \vec{p} = \vec{p}_2 = 2t$$