

Section 2.1: Matrix Operations

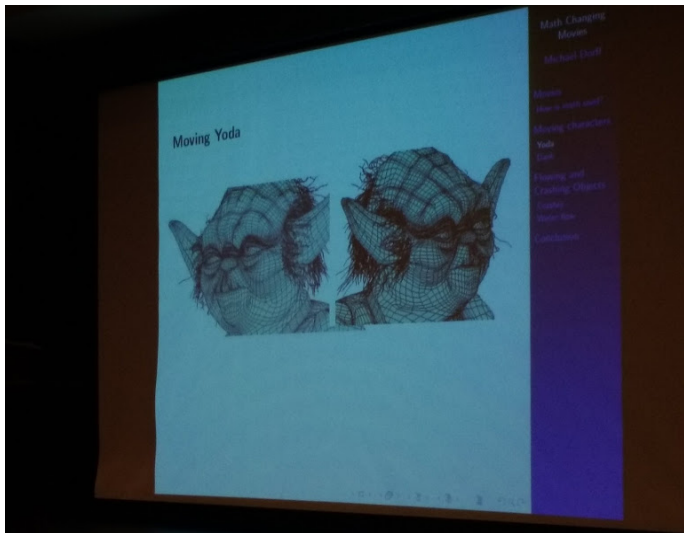
- ▶ We defined scalar multiplication and matrix addition. If A and B are $m \times n$ and c is a scalar.

$$c[a_{ij}] = [ca_{ij}], \quad \text{and} \quad [a_{ij}] + [b_{ij}] = [a_{ij} + b_{ij}]$$

- ▶ We defined matrix multiplication: If A is $m \times n$ and B is $n \times p$, then AB is defined and the product is $m \times p$.

$$AB = [Ab_1 \quad Ab_2 \quad \cdots \quad Ab_p] = \left[\sum_{k=1}^n a_{ik} b_{kj} \right]$$

Matrix Multiplication & Graphics



Moving Yoda

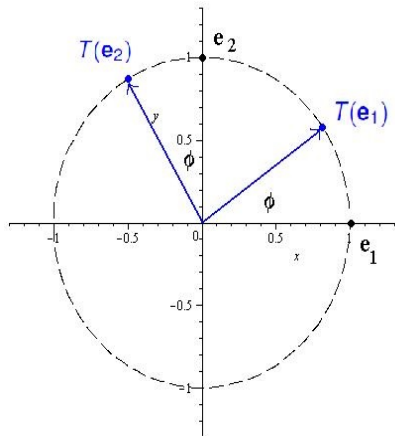
- ▶ We can move Yoda using matrix multiplication.
- ▶ Store information about the vertices in a 53756×3 matrix V , where row i of V contains the x , y , and z coordinates of the i th vertex.
- ▶ Yoda can be rotated by θ radians about the y -axis by multiplying V with R , where

$$R = \begin{pmatrix} \cos(\theta) & 0 & -\sin(\theta) \\ 0 & 1 & 0 \\ \sin(\theta) & 0 & \cos(\theta) \end{pmatrix}$$

- Movie
- Movie
- Michael Eick
- Movie
- How it works
- Moving characters
- Yoda
- Gen
- Flipping and
- Cloning Objects
- Center
- Warp Box
- Conclusion

A Slide from Class on February 3; Rotation in \mathbb{R}^2

Let $T : \mathbb{R}^2 \rightarrow \mathbb{R}^2$ be the rotation transformation that rotates each point in \mathbb{R}^2 counter clockwise about the origin through an angle ϕ .



Using some basic trigonometry, the points on the unit circle

$$T(\mathbf{e}_1) = (\cos \phi, \sin \phi)$$

$$\begin{aligned} T(\mathbf{e}_2) &= (\cos(90^\circ + \phi), \sin(90^\circ + \phi)) \\ &= (-\sin \phi, \cos \phi) \end{aligned}$$

$$\text{So } A = \begin{bmatrix} \cos \phi & -\sin \phi \\ \sin \phi & \cos \phi \end{bmatrix}.$$

Theorem: Properties

The $m \times n$ **zero matrix** has a zero in each entry. We'll denote this matrix as O (or $O_{m,n}$ if the size is not clear from the context).

Theorem: Let A , B , and C be matrices of the same size and r and s be scalars. Then

$$(i) \quad A + B = B + A$$

$$(iv) \quad r(A + B) = rA + rB$$

$$(ii) \quad (A + B) + C = A + (B + C)$$

$$(v) \quad (r + s)A = rA + sA$$

$$(iii) \quad A + O = A$$

$$(vi) \quad r(sA) = (rs)A$$

Theorem: Properties-Matrix Product

Let A be an $m \times n$ matrix. Let r be a scalar and B and C be matrices for which the indicated sums and products are defined. Then

$$(i) \quad A(BC) = (AB)C$$

$$(ii) \quad A(B + C) = AB + AC$$

$$(iii) \quad (B + C)A = BA + CA$$

$$(iv) \quad r(AB) = (rA)B = A(rB), \text{ and}$$

$$(v) \quad I_m A = A = A I_n$$

Caveats!

(1) Matrix multiplication **does not** commute! In general $AB \neq BA$.

For example, we found $\begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} \begin{bmatrix} 4 & 1 \\ -1 & 2 \end{bmatrix} = \begin{bmatrix} 2 & 5 \\ -3 & 6 \end{bmatrix}$ whereas

$$\begin{bmatrix} 4 & 1 \\ -1 & 2 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix} = \begin{bmatrix} 4 & 11 \\ -1 & 4 \end{bmatrix}$$

(2) The zero product property **does not** hold! That is, if $AB = O$, one **cannot** conclude that one of the matrices A or B is a zero matrix.

(3) There is no *cancelation law*. That is, $AB = CB$ **does not** imply that A and C are equal.

$$A = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix}, B = \begin{bmatrix} 0 & 0 \\ 3 & 0 \end{bmatrix}, C = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix}$$

Compute the products AB , CB , and BB .

The products

$$AB = \begin{bmatrix} 0 & 1 \\ 0 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix}, \quad \text{and}$$

$$CB = \begin{bmatrix} 0 & 1 \\ 1 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 3 & 0 \\ 0 & 0 \end{bmatrix}.$$

So $AB = CB$ whereas $A \neq C$. And

$$BB = \begin{bmatrix} 0 & 0 \\ 3 & 0 \end{bmatrix} \begin{bmatrix} 0 & 0 \\ 3 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}.$$

Even though B is not the zero matrix, the product BB is the zero matrix.

Matrix Powers

Positive Integer Powers: If A is square—meaning A is an $n \times n$ matrix for some $n \geq 2$, then the product AA is defined. For positive integer k , we'll define

$$A^k = AA^{k-1}.$$

Zero Power: We define $A^0 = I_n$, where I_n is the $n \times n$ identity matrix.

Transpose

Definition: Let $A = [a_{ij}]$ be an $m \times n$ matrix. The **transpose** of A is the $n \times m$ matrix denoted and defined by

$$A^T = [a_{ji}].$$

For example, if

$$A = \begin{bmatrix} a & b & c \\ d & e & f \end{bmatrix}, \quad \text{then} \quad A^T = \begin{bmatrix} a & d \\ b & e \\ c & f \end{bmatrix}.$$

Example

$$A = \begin{bmatrix} 5 & 5 \\ -1 & 4 \end{bmatrix}, \quad B = \begin{bmatrix} 2 & 0 & 3 \\ -1 & 1 & 4 \end{bmatrix}$$

Compute A^T , B^T , the transpose of the product $(AB)^T$, and the product $B^T A^T$.

$$A^T = \begin{bmatrix} 5 & -1 \\ 5 & 4 \end{bmatrix} \quad B^T = \begin{bmatrix} 2 & -1 \\ 0 & 1 \\ 3 & 4 \end{bmatrix}$$

$$AB = \begin{bmatrix} 5 & 5 \\ -1 & 4 \end{bmatrix} \begin{bmatrix} 2 & 0 & 3 \\ -1 & 1 & 4 \end{bmatrix} = \begin{bmatrix} 5 & 5 & 35 \\ -6 & 4 & 13 \end{bmatrix}$$

*2x2 2x3
↖
match*

$$(AB)^T = \begin{bmatrix} 5 & -6 \\ 5 & 4 \\ 35 & 13 \end{bmatrix}$$

$$B^T A^T = \begin{bmatrix} 2 & -1 \\ 0 & 1 \\ 3 & 4 \end{bmatrix} \begin{bmatrix} 5 & -1 \\ 5 & 4 \end{bmatrix} = \begin{bmatrix} 5 & -6 \\ 5 & 4 \\ 35 & 13 \end{bmatrix}$$

3×2 2×2
match

Theorem: Properties-Matrix Transposition

Let A and B be matrices such that the appropriate sums and products are defined, and let r be a scalar. Then

$$(i) (A^T)^T = A$$

$$(ii) (A + B)^T = A^T + B^T$$

$$(iii) (rA)^T = rA^T$$

$$(iv) (AB)^T = B^T A^T$$

works with more than 2

$$\text{e.g. } (ABCD)^T = D^T C^T B^T A^T$$