January 11 Math 3260 sec. 56 Spring 2018

Section 1.1: Systems of Linear Equations

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We had the following theorem on linear systems:

Theorem: A linear system of equations has exactly one of the following:

- i No solution, or
- ii Exactly one solution, or
- iii Infinitely many solutions.

We use the terms:

Consistent if it has at least one solution, and **Inconsistent** if it has no solution.

Also recall...

Given a linear system, we can equate two matrices with it. The coefficient matrix, and the augmented matrix. For example

has coefficient matrix

$$\left[\begin{array}{rrrr} 1 & 2 & -1 \\ 2 & 0 & 1 \\ 1 & 1 & 1 \end{array}\right]$$

and augmented matrix

$$\begin{bmatrix} 1 & 2 & -1 & -4 \\ 2 & 0 & 1 & 7 \\ 1 & 1 & 1 & 6 \end{bmatrix}$$

Legitimate Operations for Solving a System

We can perform three basic operation without changing the solution set of a system. These are

- swap the order of any two equations (swap),
- multiply an equation by any nonzero constant (scale), and
- replace an equation with the sum of itself and a nonzero multiple of any other equation (replace).

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We said that two systems with the same solution set are called equivalent.

Some Operation Notation

Notation

Swap equations *i* and *j*:

$$Ei \leftrightarrow Ej$$

Scale equation i by k:

kEi
ightarrow Ei

Replace equation j with the sum of itself and k times equation i:

 $\textit{kEi} + \textit{Ej} \rightarrow \textit{Ej}$

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Solve the following system of equations by *elimination*. Keep tabs on the augmented matrix at each step.

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$$x_{1} + 2x_{2} - x_{3} = -4$$

$$2x_{1} + x_{3} = 7$$

$$x_{1} + x_{2} + x_{3} = 6$$

$$x_{2} + x_{3} = 6$$

$$x_{1} + x_{2} + x_{3} = 6$$

$$x_{2} + x_{3} = 6$$

$$x_{1} + x_{2} + x_{3} = 6$$

$$x_{2} + x_{3} = 6$$

$$x_{1} + x_{2} + x_{3} = 6$$

$$x_{2} + x_{3} = 6$$

$$x_{1} + x_{2} + x_{3} = 15$$

$$x_{1} + x_{2} + x_{3} = 6$$

$$x_{2} + x_{3} = 6$$

$$x_{1} + x_{2} + x_{3} = 6$$

$$x_{2} + x_{3} = 15$$

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$$x_{1} + x_{2} + x_{3} = 6$$

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$$\begin{array}{rcl} D_{\bullet} & -E_{1}+ & E_{3} & = & E_{3} \\ x_{1} & + & 2x_{2} & - & x_{3} & = & - & 4 \\ & - & 4x_{2} & + & 3x_{3} & = & 1S \\ & - & x_{2} & + & 2x_{3} & = & 1D \end{array}$$

$$\begin{bmatrix} 1 & 2 & -1 & -4 \\ 0 & -4 & 3 & 15 \\ 0 & -1 & 2 & 10 \end{bmatrix}$$

Let
$$s$$
 swop $E_2 \leftarrow E_3$
 $X_1 + 2X_2 - X_3 = -4$
 $-X_2 + 2X_3 = 10$
 $-4 \times 2 + 3 \times 3 = 15$

$$\begin{bmatrix} 1 & 2 & -1 & -4 \\ 0 & -1 & 2 & 10 \\ 0 & -4 & 3 & 15 \end{bmatrix}$$

$$D_{0} - 4.E_{2} + E_{3} \rightarrow E_{3}$$

$$X_{1} + 2X_{2} - X_{3} = -4$$

$$-X_{2} + 2X_{3} = 10$$

$$-5 \times 3 = -25$$

$$\begin{bmatrix} 1 & 2 & -1 & -4 \\ 0 & -1 & 2 & 10 \\ 0 & 0 & -5 & -25 \end{bmatrix}$$

$$\begin{array}{c} \text{Timolly, lettr Scale} \\ -E_2 \rightarrow E_2 \quad \text{and} \quad \exists E_3 \rightarrow E_3 \\ \hline X_1 + 2X_2 - X_3 = -4 \\ X_2 - 2X_3 = -10 \\ X_3 = 5 \\ \hline X_3 = 5 \\ \hline \\ \text{Wow X_3 is known.} \\ \hline \\ \text{Wow X_3 is known.} \\ \hline \\ \text{with Some cubstitution,} \\ \hline \\ \text{we get X_2 and } \text{Max}, \end{array}$$

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From Eqn 2 $X_2 = -10 + 2X_3 = -10 + 2 \cdot 5 = 0$ From Eqn 1 $X_1 = -4 - 2X_2 + X_3 = -4 - 0 + 5 = 1$

The solution is $x_1 = 1, x_2 = 0, x_3 = 5,$ We could write this as (1, 0, 5).

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We used the legitimate equation operations to solve the system by eliminating some variables and then substituting. Our augmented matrix after so many steps looked like

$$\left[\begin{array}{rrrrr}1&2&-1&-4\\0&1&2&-10\\0&0&1&5\end{array}\right]$$

The operations on the equations correspond to changes to the rows of the matrix. This suggests that we can do operations on the rows of matrix to get desired (legitimate) changes to the equations.

Elementary Row Operations

If any sequence of the following operations are performed on a matrix, the resulting matrix is **row equivalent**.

- i Replace a row with the sum of itself and a multiple of another row (**replacement**).
- ii Interchange any two rows (row swap).
- iii Multiply a row by any nonzero constant (scaling).

Theorem: If the augmented matrices of two linear systems are row equivalent, then the systems have the same solution set. (i.e. The systems are equivalent!)

A key here is structure!

Consider the following augmented matrix. Determine if the associated system is consistent or inconsistent. If it is consistent, determine the solution set.

3 rows -> 3 egns 4 columns -> 3 variableir (a) $\begin{vmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{vmatrix}$ The system is $|x_{1} + 0x_{2} + 0x_{3} = 3$ 0x, +1x2 + 0x3 = 1 0×1 + 0×2 + 1×3 = -2 it. x.=3 Obvio usly X2=1 X2=-2 Solution

(b)
$$\begin{bmatrix} 1 & 0 & 2 & -5 \\ 0 & 1 & -1 & 4 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

 $4 \text{ colump} \rightarrow 3 \text{ variabler}$
 $1 \text{ tready } cs$
 $1 \text{ is ready } cs$
 $1 \text{ is always } false.$
The system is inconsistent /

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(c)
$$\begin{bmatrix} 1 & 0 & -2 & -4 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

 $(x_1 + 0x_1 - 2x_3 = -4)$
 $(x_1 + 1x_2 + 1x_3 = 4)$
 $(x_2 + 0x_3 + 0x_3 = 0)$
The last equation is $\begin{bmatrix} 0 = 0 \\ 0 = 0 \\ 0 \end{bmatrix}$ which
is always true!
The 1st two can be stated as
 $(x_1 = -4 + 2x_3)$
 $(x_2 = 4 - x_3)$
 $(x_3 - is ong real number)$

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We state this as sis "free" we call X, and X2 basic Variables. This system is consistent with infinitely many solutions,