## January 17 Math 3260 sec. 51 Spring 2020

#### Section 1.3: Vector Equations

**Definition:** A matrix that consists of one column is called a **column vector** or simply a **vector**.

#### **Denoting Vectors:**

- Bold faced in typesetting: vector x and number x
- Arrow overscore in handwriting: vector  $\vec{x}$  and number x.



## $\mathbb{R}^2$ & Geometry

The set of vectors of the form  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  with  $x_1$  and  $x_2$  real numbers is denoted by  $\mathbb{R}^2$  (read "R two"). It's the set of all real ordered pairs.

Each vector  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}$  corresponds to a point in the Cartesian plane. We can equate them with ordered pairs written in the traditional format  $\begin{bmatrix} x_1 \\ x_2 \end{bmatrix}^{T} = (x_1, x_2)$ . This is not to be confused with a row matrix.

$$\begin{bmatrix} x_1 \\ x_2 \end{bmatrix} \neq \begin{bmatrix} x_1 & x_2 \end{bmatrix}$$

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We can identify vectors with points or with directed line segments emanating from the origin (little arrows).

### Geometry



Figure: Vectors characterized as points, and vectors characterized as directed line segments.

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# Algebraic Operations Let $\mathbf{u} = \begin{bmatrix} u_1 \\ u_2 \end{bmatrix}$ , $\mathbf{v} = \begin{bmatrix} v_1 \\ v_2 \end{bmatrix}$ , and *c* be a scalar<sup>1</sup>. Scalar Multiplication: The scalar multiple of $\mathbf{u}$

$$c\mathbf{u} = \left[ egin{array}{c} cu_1 \ cu_2 \end{array} 
ight]$$

Vector Addition: The sum of vectors u and v

$$\mathbf{u} + \mathbf{v} = \left[ \begin{array}{c} u_1 + v_1 \\ u_2 + v_2 \end{array} \right]$$

Vector Equivalence: Equality of vectors is defined by

$$\mathbf{u} = \mathbf{v}$$
 if and only if  $u_1 = v_1$  and  $u_2 = v_2$ .

<sup>&</sup>lt;sup>1</sup>A **scalar** is an element of the set from which  $u_1$  and  $u_2$  come. For our purposes, a scalar is a *real* number.

# Examples

$$\mathbf{u} = \begin{bmatrix} 4 \\ -2 \end{bmatrix}, \quad \mathbf{v} = \begin{bmatrix} -1 \\ 7 \end{bmatrix}, \text{ and } \mathbf{w} = \begin{bmatrix} -3 \\ \frac{3}{2} \end{bmatrix}$$
  
Evaluate  
(a)  $-2\mathbf{u} = -\mathbf{z} \begin{bmatrix} 4 \\ -2 \end{bmatrix} = \begin{bmatrix} -2(4) \\ -2(4) \end{bmatrix} = \begin{bmatrix} -9 \\ 4 \end{bmatrix}$   
(b)  $-2\mathbf{u} + 3\mathbf{v} = \begin{bmatrix} -9 \\ 4 \end{bmatrix} + \begin{bmatrix} -3 \\ 21 \end{bmatrix} = \begin{bmatrix} -9 - 3 \\ 4 + 21 \end{bmatrix} = \begin{bmatrix} -11 \\ 25 \end{bmatrix}$   
Is it true that  $\mathbf{w} = -\frac{3}{4}\mathbf{u}$ ? Well,  $-\frac{3}{4}\mathbf{v} = -\frac{3}{4}\begin{bmatrix} 4 \\ -2 \end{bmatrix} = \begin{bmatrix} -3 \\ \frac{3}{2} \end{bmatrix}$   
 $\mathbf{v} = -\frac{3}{4}\mathbf{v}$ .

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#### Geometry of Algebra with Vectors



Figure: Left:  $\frac{1}{2}(-4, 1) = (-2, 1/2)$ . Right: (-4, 1) + (2, 5) = (-2, 6)

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### Geometry of Algebra with Vectors

**Scalar Multiplication:** stretches or compresses a vector but can only change direction by an angle of 0 (if c > 0) or  $\pi$  (if c < 0). We'll see that  $0\mathbf{u} = (0,0)$  for any vector  $\mathbf{u}$  in  $\mathbb{R}^2$ .



**Vector Addition:** The sum  $\mathbf{u} + \mathbf{v}$  of two vectors (nonparallel and not (0,0)) is the the fourth vertex of a parallelogram whose other three vertices are  $(u_1, u_2)$ ,  $(v_1, v_2)$ , and (0,0).

### Vectors in $\mathbb{R}^n$

A vector in  $\mathbb{R}^3$  is a 3  $\times$  1 column matrix. These are ordered triples. For example

$$\mathbf{a} = \begin{bmatrix} 1\\ 3\\ -1 \end{bmatrix}, \quad \text{or} \quad \mathbf{x} = \begin{bmatrix} x_1\\ x_2\\ x_3 \end{bmatrix}$$

.

A vector in  $\mathbb{R}^n$  for  $n \ge 2$  is a  $n \times 1$  column matrix. These are ordered *n*-tuples. For example

$$\mathbf{X} = \begin{bmatrix} x_1 \\ x_2 \\ \vdots \\ x_n \end{bmatrix}$$

**The Zero Vector:** is the vector whose entries are all zeros. It will be denoted by **0** or  $\vec{0}$  and is not to be confused with the scalar 0.

#### Algebraic Properties on $\mathbb{R}^n$

For every **u**, **v**, and **w** in  $\mathbb{R}^n$  and scalars *c* and  $d^2$ 

(i) 
$$\mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}$$
 (v)  $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$   
(ii)  $(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w})$  (vi)  $(c + d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$   
(iii)  $\mathbf{u} + \mathbf{0} = \mathbf{0} + \mathbf{u} = \mathbf{u}$  (vii)  $c(d\mathbf{u}) = d(c\mathbf{u}) = (cd)\mathbf{u}$   
(iv)  $\mathbf{u} + (-\mathbf{u}) = -\mathbf{u} + \mathbf{u} = \mathbf{0}$  (viii)  $1\mathbf{u} = \mathbf{u}$   
These all follow foirly easily from our definitions, we'll  
obe the Structure. We'll see this structure again later  $l$ 

<sup>2</sup>The term  $-\mathbf{u}$  denotes  $(-1)\mathbf{u}$ .

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#### **Definition: Linear Combination**

A linear combination of vectors  $\mathbf{v}_1, \dots \mathbf{v}_p$  in  $\mathbb{R}^n$  is a vector  $\mathbf{y}$  of the form

$$\mathbf{y} = c_1 \mathbf{v}_1 + \cdots + c_p \mathbf{v}_p$$

where the scalars  $c_1, \ldots, c_p$  are often called weights.

For example, suppose we have two vectors  $\mathbf{v}_1$  and  $\mathbf{v}_2$ . Some linear combinations include

$$3\mathbf{v}_{1}, \quad -2\mathbf{v}_{1} + 4\mathbf{v}_{2}, \quad \frac{1}{3}\mathbf{v}_{2} + \sqrt{2}\mathbf{v}_{1}, \quad \text{and} \quad \mathbf{0} = 0\mathbf{v}_{1} + 0\mathbf{v}_{2}.$$
Note  $\vec{O} = \vec{O}\vec{v}_{1} + \vec{O}\vec{v}_{2}$ 

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# Example

From 
$$E_2$$
,  $C_1=1$ . Subjuste  $E_1$  and  $E_3$   
 $3C_2 = -2 - 1 = -3 \implies C_2 = -1$   
 $Z(_2 = -3 + 1 = -2 \implies C_2 = -1$   
We can solve the System to set  $C_1 = 1$ ,  $C_2 = -1$   
 $C_2 = -1$   
 $C_3 = -1$   
 $C_4 = -1$   
 $C_5 =$ 

\* Note: From the system, we have augmented  
moderix 
$$\begin{bmatrix} 1 & 3 & -2 \\ -2 & 0 & -2 \\ -1 & 2 & -3 \end{bmatrix}$$
 free  $\begin{bmatrix} 1 & 0 & 1 \\ 0 & 1 & -1 \\ 0 & 0 & 0 \end{bmatrix}$   
The system is consistent. Again, we proton  
get  $C_1 = 1$ ,  $C_2 = -1$ .

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