

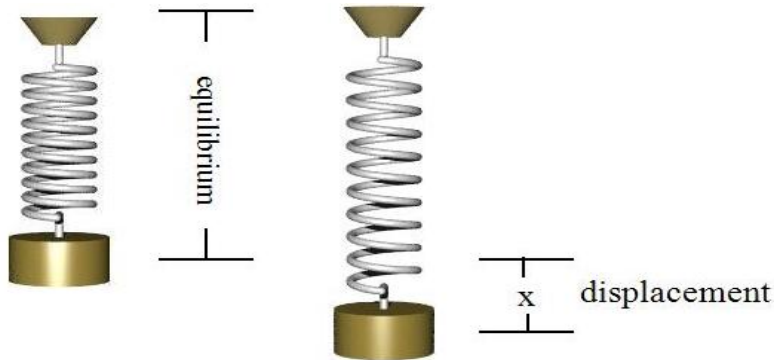
Section 11: Linear Mechanical Equations

Simple Harmonic Motion

We consider a flexible spring from which a mass is suspended. In the absence of any damping forces (e.g. friction, a dash pot, etc.), and free of any external driving forces, any initial displacement or velocity imparted will result in **free, undamped motion**—a.k.a. **simple harmonic motion**.

▶ Harmonic Motion gif

Building an Equation: Hooke's Law



At equilibrium, displacement $x(t) = 0$.

$$\text{Hooke's Law: } F_{\text{spring}} = k x$$

Figure: In the absence of any displacement, the system is at equilibrium. Displacement $x(t)$ is measured from equilibrium $x = 0$.

Building an Equation: Hooke's Law

Newton's Second Law: $F = ma$ Force = mass times acceleration

$$a = \frac{d^2x}{dt^2} \implies F = m \frac{d^2x}{dt^2}$$

Hooke's Law: $F = kx$ Force exerted by the spring is proportional to displacement

The force imparted by the spring opposes the direction of motion.

$$m x'' + kx = 0 \implies x'' + \frac{k}{m} x = 0$$

$$m \frac{d^2x}{dt^2} = -kx \implies x'' + \omega^2 x = 0 \quad \text{where} \quad \omega = \sqrt{\frac{k}{m}}$$

Convention We'll Use: Up will be positive ($x > 0$), and down will be negative ($x < 0$). This orientation is arbitrary and follows the convention in Trench.


Obtaining the Spring Constant (US Customary Units)

If an object with weight W pounds stretches a spring δx feet¹ from its length with no mass attached, then by Hooke's law we compute the spring constant via the equation

$$W = k\delta x.$$

The units for k in this system of measure are lb/ft.

$$W = k\delta x \quad \Rightarrow \quad k = \frac{W}{\delta x} \quad \frac{\text{lb}}{\text{ft}}$$

¹Note that $\delta x = w/\text{mass equilibrium} - w/\text{no mass equilibrium}$. 

Obtaining the Spring Constant (US Customary Units)

Note also that Weight = mass \times acceleration due to gravity. Hence if we know the weight of an object, we can obtain the mass via

$$W = mg.$$

We typically take the approximation $g = 32 \text{ ft/sec}^2$. The units for mass are $\text{lb sec}^2/\text{ft}$ which are called slugs.

$$W = mg \Rightarrow m = \frac{W}{g} \frac{\text{lb}}{\text{ft/sec}^2} \text{ slugs}$$

Obtaining the Spring Constant (SI Units)

In SI units, the weight would be expressed in Newtons (N). The appropriate units for displacement would be meters (m). In these units, the spring constant would have units of N/m.

It is customary to describe an object by its mass in kilograms. When we encounter such a description, we deduce the weight in Newtons

$$W = mg \quad \text{taking the approximation} \quad g = 9.8 \text{ m/sec}^2.$$

Obtaining the Spring Constant: *Displacement in Equilibrium*

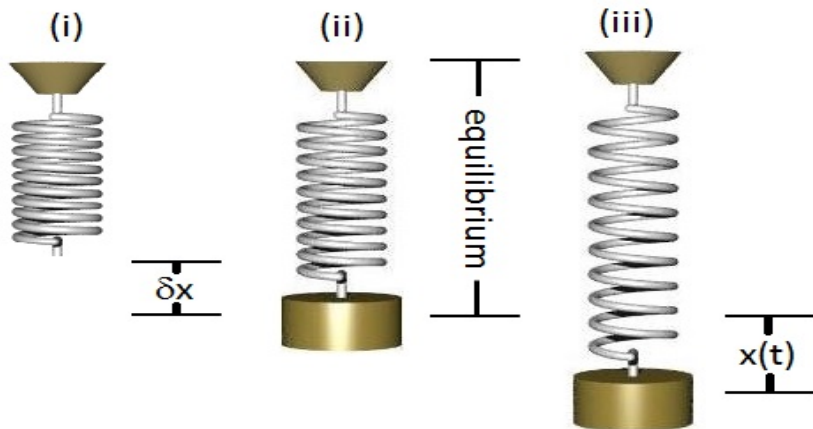


Figure: The displacement in equilibrium δx is the difference between spring only length, and spring-mass equilibrium length.

Obtaining the Spring Constant: *Displacement in Equilibrium*

If an object stretches a spring δx units from its length (with no object attached), we may say that it stretches the spring δx units *in equilibrium*. Applying Hooke's law with the weight as force, we have

$$W = mg = k\delta x. \quad \frac{mg}{m\delta x} = \frac{k\delta x}{m\delta x} \Rightarrow \frac{g}{\delta x} = \frac{k}{m}$$

We observe that the value ω can be deduced from δx by

$$\omega^2 = \frac{k}{m} = \frac{g}{\delta x}.$$

Provided that values for δx and g are used in appropriate units, ω is in units of per second.

Simple Harmonic Motion

$$mx'' + kx = 0$$

$$x'' + \omega^2 x = 0, \quad x(0) = x_0, \quad x'(0) = x_1 \quad (1)$$

Here, x_0 and x_1 are the initial position (relative to equilibrium) and velocity, respectively. The solution is

$$x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t)$$

called the **equation of motion**.

Caution: The phrase *equation of motion* is used differently by different authors. Some, including Trench, use this phrase to refer the ODE of which (1) would be the example here. Others use it to refer to the **solution** to the associated IVP.

$$x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t)$$

Characteristics of the system include

- ▶ the period $T = \frac{2\pi}{\omega}$,
- ▶ the frequency $f = \frac{1}{T} = \frac{\omega}{2\pi}$
- ▶ the circular (or angular) frequency ω , and
- ▶ the amplitude or maximum displacement $A = \sqrt{x_0^2 + (x_1/\omega)^2}$

← footnote, not square

²Various authors call f the natural frequency and others use this term for ω .

Amplitude and Phase Shift

We can formulate the solution in terms of a single sine (or cosine) function. Letting

$$x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t) = A \sin(\omega t + \phi)$$

requires

$$A = \sqrt{x_0^2 + (x_1/\omega)^2},$$

and the **phase shift** ϕ must be defined by

$$\sin \phi = \frac{x_0}{A}, \quad \text{with} \quad \cos \phi = \frac{x_1}{\omega A}.$$

Example

An object stretches a spring 6 inches in equilibrium. Assuming no driving force and no damping, set up the differential equation describing this system.

No driving and no damping means simple harmonic motion. So displacement x satisfies

$$m x'' + kx = 0 \Rightarrow x'' + \omega^2 x = 0 \quad \text{with } \omega^2 = \frac{k}{m}$$

We need to know ω^2 . We do know displacement in equilibrium $\delta x = 6$ inches. We can use

$$\omega^2 = \frac{g}{\delta x}$$

$$\delta x = 6 \text{ in} = \frac{1}{2} \text{ ft}, \text{ so take } g = 32 \text{ ft/sec}^2.$$

$$\omega^2 = \frac{32 \text{ ft/sec}^2}{1/2 \text{ ft}} = 64 \frac{1}{\text{sec}^2}$$

The ODE is

$$x'' + 64x = 0$$

Example

A 4 pound weight stretches a spring 6 inches. The mass is released from a position 4 feet above equilibrium with an initial downward velocity of 24 ft/sec. Find the equation of motion, the period, amplitude, phase shift, and frequency of the motion. (Take $g = 32 \text{ ft/sec}^2$.)

The $\delta x = 6 \text{ in}$, but we'll compute m and k given

W . The displacement x will satisfy

$$m x'' + k x = 0, \text{ i.e. } x'' + \omega^2 x = 0.$$

Find the spring constant, $W = k \delta x$

$$k = \frac{W}{\delta x} = \frac{4 \text{ lb}}{\frac{1}{2} \text{ ft}} = 8 \frac{\text{lb}}{\text{ft}}$$

Find the mass $W = mg \Rightarrow m = \frac{W}{g} = \frac{4 \text{ lb}}{32 \frac{\text{ft}}{\text{sec}^2}} = \frac{1}{8} \text{ slugs}$

Then $\omega^2 = \frac{k}{m} = \frac{8 \frac{\text{lb}}{\text{ft}}}{\frac{1}{8} \text{ slugs}} = 64 \frac{1}{\text{sec}^2}$

The ODE is $x'' + 64x = 0$. The initial conditions are $x(0) = 4$ and $x'(0) = -24$.

The characteristic equation is (using r , not m)

$$r^2 + 64 = 0 \Rightarrow r^2 = -64$$

$$r = \pm \sqrt{-64} \Rightarrow r = \pm 8i \quad \alpha = 0, \beta = 8$$

$$x(t) = c_1 \cos(8t) + c_2 \sin(8t)$$

Apply the initial conditions.

$$x'(t) = -8c_1 \sin(8t) + 8c_2 \cos(8t)$$

$$x(0) = c_1 \cos(0) + c_2 \sin(0) = 4 \Rightarrow c_1 = 4$$

$$x'(0) = -8c_1 \sin(0) + 8c_2 \cos(0) = -24 \Rightarrow 8c_2 = -24$$

$$c_2 = -3$$

The equation of motion is

$$x(t) = 4 \cos(8t) - 3 \sin(8t)$$

Here $\omega = 8$. So the period is

$$T = \frac{2\pi}{\omega} = \frac{2\pi}{8} = \frac{\pi}{4}.$$

The frequency $f = \frac{1}{T} = \frac{4}{\pi}$

The amplitude $A = \sqrt{4^2 + (-3)^2} = 5$

The phase shift ϕ satisfies

$$\sin \phi = \frac{x_0}{A} = \frac{4}{5} \quad \text{and} \quad \cos \phi = \frac{x_1}{A} = \frac{-3}{5}$$

$\sin \phi > 0$ and $\cos \phi < 0$ so ϕ is a quadrant II angle. We can use the inverse cosine function to find ϕ , the smallest positive

$$\phi = \cos^{-1}\left(\frac{-3}{5}\right) \approx 2.21$$

That's about 127°