# March 16 Math 3260 sec. 55 Spring 2020

#### Section 4.4: Coordinate Systems

**Definition:** (Coordinate Vectors) Let  $\mathcal{B} = {\mathbf{b}_1, ..., \mathbf{b}_n}$  be an ordered basis of the vector space *V*. For each **x** in *V* we define the **coordinate vector of x relative to the basis**  $\mathcal{B}$  to be the unique vector ( $c_1, ..., c_n$ ) in  $\mathbb{R}^n$  where these entries are the weights  $\mathbf{x} = c_1 \mathbf{b}_1 + \cdots + c_n \mathbf{b}_n$ .

We'll use the notation

$$\begin{bmatrix} C_1 \\ C_2 \\ \vdots \\ C_n \end{bmatrix} = [\mathbf{x}]_{\mathcal{B}}.$$

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### Coordinates in $\mathbb{R}^n$

**Change of Coordinates in**  $\mathbb{R}^n$ : Let  $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$  be an ordered basis of  $\mathbb{R}^n$ . Then the change of coordinate mapping  $\mathbf{x} \mapsto [\mathbf{x}]_{\mathcal{B}}$  is the linear transformation defined by

$$[\mathbf{x}]_{\mathcal{B}} = P_{\mathcal{B}}^{-1}\mathbf{x}$$

where the matrix

$$P_{\mathcal{B}} = [\mathbf{b}_1 \quad \mathbf{b}_2 \quad \cdots \quad \mathbf{b}_n].$$

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# Theorem: Coordinate Mapping

Let  $\mathcal{B} = {\mathbf{b}_1, ..., \mathbf{b}_n}$  be an ordered basis for a vector space *V*. Then the coordinate mapping  $\mathbf{x} \mapsto [\mathbf{x}]_{\mathcal{B}}$  is a **one to one** mapping of *V* **onto**  $\mathbb{R}^n$ .

**Remark:** When such a mapping exists, we say that *V* is **isomorphic** to  $\mathbb{R}^n$ . Properties of subsets of *V*, such as linear dependence, can be discerned from the coordinate vectors in  $\mathbb{R}^n$ .

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# Example

Use coordinate vectors to determine if the set  $\{p, q, r\}$  is linearly dependent or independent in  $\mathbb{P}_2$ .

$$\mathbf{p}(t) = 1 - 2t^2$$
,  $\mathbf{q}(t) = 3t + t^2$ ,  $\mathbf{r}(t) = 1 + t$ 

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# Section 4.5: Dimension of a Vector Space

**Theorem:** If a vector space *V* has a basis  $\mathcal{B} = {\mathbf{b}_1, ..., \mathbf{b}_n}$ , then any set of vectors in *V* containing *more than n vectors* is linearly dependent.

We saw an example of this before: a set of p vectors in  $\mathbb{R}^n$  is linearly dependent if p > n.

Why is the set  $\{1 + t, 1 - 2t, 2 + 4t\}$  linearly dependent in  $\mathbb{P}_1$ ?

### Dimension

**Corollary:** If vector space *V* has a basis  $\mathcal{B} = {\mathbf{b}_1, ..., \mathbf{b}_n}$ , then every basis of *V* consist of exactly *n* vectors.

- What this says is that the number of basis elements for a given vector space is fixed.
- This number can be used, unambiguously, as a characteristic of the vector space. This leads to the definition of **dimension**.

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# Dimension of a Vector Space

**Definition:** If V is spanned by a finite set, then V is called **finite** dimensional.

In this case, the dimension of V

 $\dim V =$  the number of vectors in any basis of V.

The dimension of the vector space  $\{\boldsymbol{0}\}$  containing only the zero vector is defined to be zero—i.e.

 $dim\{\boldsymbol{0}\}=0.$ 

If V is not spanned by a finite set<sup>1</sup>, then V is said to be **infinite** dimensional.

 $<sup>^{1}</sup>C^{0}(\mathbb{R})$  is an example of an infinite dimensional vector space  $\mathbb{P} \to \mathbb{R} \to \mathbb{R} \to \mathbb{R}$ 

## Examples

(a) Find dim( $\mathbb{R}^n$ ).

# Examples

(b) Determine dim Col A where 
$$A = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 0 & -1 \end{bmatrix}$$
.

# Some Geometry in $\mathbb{R}^3$

The subspaces of  $\mathbb{R}^3$  of various dimensions are:

- **Zero:** One point, the origin.
- **One:** Any line through the origin, e.g. Span{**u**}.
- ► **Two:** Any plane that contains the origin, e.g. Span{**u**, **v**}.
- Three: All of  $\mathbb{R}^3$

**Note:** It is assumed that vectors  $\mathbf{u}$  and  $\mathbf{v}$  are linearly independent, nonzero vectors.

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Subspaces and Dimension

**Theorem:** Let H be a subspace of a finite dimensional vector space V. Then H is finite dimensional and

 $\dim H \leq \dim V$ .

Moreover, any linearly independent subset of H can be expanded if needed to form a basis for H.

We already knew that if we had a spanning set, we could obtain a basis (by getting rid of duplicating vectors).

This says if we start with a linearly independent set, we can add linearly independent vectors as needed , until we get a spanning set.

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## Subspaces and Dimension

**Theorem:** Let *V* be a vector space with dim V = p where  $p \ge 1$ . Any linearly independent set in *V* containing exactly *p* vectors is a basis for *V*. Similarly, any spanning set consisting of exactly *p* vectors in *V* is necessarily a basis for *V*.

**That is:** If a set of *p* vectors in a *p*-dimensional vectors space *V* (1) spans *V*, it is **automatically** linearly independent.

(2) is linearly independent, it **automatically** spans V.

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### **Column and Null Spaces**

**Theorem:** Let *A* be an  $m \times n$  matrix. Then

dim Nul*A* = the number of free variables in the equation  $A\mathbf{x} = \mathbf{0}$ , and dim Col*A* = the number of pivot positions in *A*.

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## Example

Find the dimensions of the null and columns spaces of the matrix A.

$$A = \begin{bmatrix} 1 & 1 & 1 & 0 \\ -3 & 1 & -7 & -1 \\ 3 & 0 & 6 & 1 \end{bmatrix} \quad \rightsquigarrow \quad \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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