# March 6 Math 3260 sec. 56 Spring 2018

#### Section 4.1: Vector Spaces and Subspaces

**Definition** A **vector space** is a nonempty set *V* of objects called *vectors* together with two operations called *vector addition* and *scalar multiplication* that satisfy the following ten axioms: For all  $\mathbf{u}$ ,  $\mathbf{v}$ , and  $\mathbf{w}$  in *V*, and for any scalars *c* and *d* 

- 1. The sum  $\mathbf{u} + \mathbf{v}$  of  $\mathbf{u}$  and  $\mathbf{v}$  is in V.
- $2. \quad \mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}.$

3. 
$$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w}).$$

- 4. There exists a **zero** vector **0** in V such that  $\mathbf{u} + \mathbf{0} = \mathbf{u}$ .
- 5. For each vector **u** there exists a vector  $-\mathbf{u}$  such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$ .

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- 6. For each scalar c,  $c\mathbf{u}$  is in V.
- 7.  $c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$ .
- 8.  $(c+d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$ .

9. 
$$c(d\mathbf{u}) = d(c\mathbf{u}) = (cd)\mathbf{u}$$
.

10. 1**u** = **u** 

### **Examples of Vector Spaces**

For an integer  $n \ge 0$ ,  $\mathbb{P}_n$  denotes the set of all polynomials with real coefficients of degree at most *n*. That is

$$\mathbb{P}_n = \{\mathbf{p}(t) = \mathbf{p}_0 + \mathbf{p}_1 t + \dots + \mathbf{p}_n t^n \mid \mathbf{p}_0, \mathbf{p}_1, \dots, \mathbf{p}_n \in \mathbb{R}\},\$$

where addition<sup>1</sup> and scalar multiplication are defined by

$$(\mathbf{p} + \mathbf{q})(t) = \mathbf{p}(t) + \mathbf{q}(t) = (p_0 + q_0) + (p_1 + q_1)t + \dots + (p_n + q_n)t^n$$

$$(c\mathbf{p})(t) = c\mathbf{p}(t) = cp_0 + cp_1t + \cdots + cp_nt^n.$$

 ${}^{1}\mathbf{q}(t) = q_0 + q_1t + \cdots + q_nt^n$ 

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We found that in  $\mathbb{P}_n$ , the zero vector  $\mathbf{0}(t) = \mathbf{0} + \mathbf{0}t + \cdots + \mathbf{0}t^n$ .

If  $\mathbf{p}(t) = p_0 + p_1 t + \cdots + p_n t^n$ , what is the vector  $-\mathbf{p}$ ?

$$f_{or} = -\vec{p}(t) = a_{0} + a_{1}t + \dots + a_{n}t^{n}$$

$$(\vec{p} + (-\vec{p}))(t) = \vec{p}(t) + (-\vec{p}(t))$$

$$= (p_{0} + a_{0}) + (p_{1} + a_{1})t + \dots + (p_{n} + a_{n})t^{n}$$

$$= 0 + 0t + \dots + 0t^{n}$$

$$a_{0} = -P_{0}, \quad a_{1} = -P_{1}, \dots, \quad a_{n} = -P_{n}$$

$$s_{0} = -\vec{p}(t) = -p_{0} - p_{1}t - \dots - p_{n}t^{n}$$

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### **Examples of Vector Spaces**

Let *V* be the set of all differentiable, real valued functions f(x) defined for  $-\infty < x < \infty$  with the property that

f(0) = 0.

Define vector addition and scalar multiplication in the standard way for functions—i.e.

(f+g)(x) = f(x) + g(x), and (cf)(x) = cf(x).

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Verify that properties 1. and 6. hold.

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# A set that is not a Vector Space Let $V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix}, | x \le 0, y \le 0 \right\}$ with regular vector addition and scalar multiplication in $\mathbb{R}^2$ . Note *V* is the third quadrant in the *xy*-plane.

(1) Does property 1. hold for V? Let [x] and [4] bein V so x so, y so, uso, and vso.  $\begin{bmatrix} x \\ y \end{bmatrix}_{+} \begin{bmatrix} u \\ v \end{bmatrix} = \begin{bmatrix} x+u \\ y+v \end{bmatrix}$  Note  $x \le 0 \mod u \le 0$  $\Rightarrow x+u \le 0$ similarly y+v 50. The sum is in V Vis closed under vector addition.

# A set that is not a Vector Space Let $V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix}, | x \le 0, y \le 0 \right\}$ with regular vector addition and scalar multiplication in $\mathbb{R}^2$ . Note *V* is the third quadrant in the *xy*-plane.

(2) Does property 6. hold for V? If [x] is in V and say X<0, then note that  $-2 \begin{bmatrix} x \\ b \end{bmatrix} = \begin{bmatrix} -2x \\ -zb \end{bmatrix}$  is not in V since  $-2x \ge 0$ . For example,  $\begin{bmatrix} -1 \\ -1 \end{bmatrix}$  is in V, but  $-2 \begin{bmatrix} -1 \\ -1 \end{bmatrix} = \begin{bmatrix} 2 \\ 2 \end{bmatrix}$  is not in V. V is not closed under Scalar nultiplicator. V is not a Vector space. March 2, 2018 8/37



Let V be a vector space. For each **u** in V and scalar c

$$0u = 0$$
  
 $c0 = 0$   
 $-1u = -u$ 



**Definition:** A **subspace** of a vector space V is a subset H of V for which

- a) The zero vector is in  $H^2$
- b) *H* is closed under vector addition. (i.e.  $\mathbf{u}, \mathbf{v}$  in *H* implies  $\mathbf{u} + \mathbf{v}$  is in *H*)
- c) *H* is closed under scalar multiplication. (i.e. **u** in *H* implies *c***u** is in *H*)

<sup>&</sup>lt;sup>2</sup>This is sometimes replaced with the condition that *H* is nonempty.

Consider  $\mathbb{R}^n$  and let  $V = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$  be a nonempty  $(p \ge 1)$  subset of  $\mathbb{R}^n$ . Show that *V* is a subspace.

Well show that V satisfies the 3 properties.

$$O = Ov_1 + Ov_2 + \dots + Ov_p$$
,  $O$  is in  $V$ .

(2) Suppose 
$$\vec{X}$$
,  $\vec{u}$  are in  $\vec{V}$ .  
 $\vec{X} = G$ ,  $\vec{v}_1 + G_2 \vec{v}_2 + \dots + G_p \vec{V}_p$  and  
 $\vec{u} = b_1 \vec{v}_1 + b_2 \vec{v}_2 + \dots + b_p \vec{v}_p$  for some scalars  
 $G_1, \dots, G_p, b_1, \dots, b_p$ .  
 $\vec{X} + \vec{u} = (G_1 + b_1) \vec{v}_1 + (G_2 + b_2) \vec{V}_2 + \dots + (G_p + b_p) \vec{V}_p$   
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Determine which of the following is a subspace of  $\mathbb{R}^2$ .

(a) The set of all vectors of the form  $\mathbf{u} = (u_1, 0)$ .  $\mathbf{O} = (\mathbf{o}, \mathbf{b})$  is in this set.

(a) If  $\vec{h}_{1} = (h_{1,0}) \wedge d$   $\vec{V} = (V_{1,0})$ ,  $\vec{h}_{1} + \vec{V} = (h_{1,1} + V_{1,0} + 0) = (h_{1,1} + V_{1,0})$ The set if (losed under vector edd) tion.

3 ch = (ch, co) = (ch, o) The set is closed inder scalar multiplication. The set is a subspace of R<sup>2</sup>.

### Example continued

(b) The set of all vectors of the form  $\mathbf{u} = (u_1, 1)$ .

Not a subspace. In patienter O is not in this at.

## Definition: Linear Combination and Span

**Definition** Let V be a vector space and  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$  be a collection of vectors in V. A linear combination of the vectors is a vector **u** 

$$\mathbf{u} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \cdots + c_p \mathbf{v}_p$$

for some scalars  $c_1, c_2, \ldots, c_p$ .

**Definition** The span, Span{ $v_1, v_2, \ldots, v_p$ }, is the subet of V consisting of all linear combinations of the vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ .

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#### Theorem

**Theorem:** If  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ , for  $p \ge 1$ , are vectors in a vector space *V*, then Span{ $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ }, is a subspace of *V*.

**Remark** This is called the **subspace of** *V* **spanned by (or generated by)**  $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ . Moreover, if *H* is any subspace of *V*, a **spanning set** for *H* is any set of vectors  $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$  such that  $H = \text{Span}\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ .

 $M^{2\times 2}$  denotes the set of all 2 × 2 matrices with real entries. Consider the subset *H* of  $M^{2\times 2}$ 

$${\mathcal H}=\left\{\left[egin{array}{cc} {m a} & {m 0} \ {m 0} & {m b} \end{array}
ight] \mid {m a},\, {m b}\in {\mathbb R}
ight\}.$$

Show that *H* is a subspace of  $M^{2\times 2}$  by finding a spanning set. That is, show that  $H = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$  for some appropriate vectors.

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