

## Section 11: Linear Mechanical Equations

We can consider the application of an external driving force (with or without damping). Assume a time dependent force  $f(t)$  is applied to the system. The ODE governing displacement becomes

$$m \frac{d^2 x}{dt^2} = -\beta \frac{dx}{dt} - kx + f(t), \quad \beta \geq 0.$$

Divide out  $m$  and let  $F(t) = f(t)/m$  to obtain the nonhomogeneous equation

$$\frac{d^2 x}{dt^2} + 2\lambda \frac{dx}{dt} + \omega^2 x = F(t)$$

## Forced Undamped Motion and Resonance

Consider the case  $F(t) = F_0 \cos(\gamma t)$  or  $F(t) = F_0 \sin(\gamma t)$ , and  $\lambda = 0$ .  
Two cases arise

$$(1) \quad \gamma \neq \omega, \quad \text{and} \quad (2) \quad \gamma = \omega.$$

Taking the sine case, the DE is

$$x'' + \omega^2 x = F_0 \sin(\gamma t)$$

with complementary solution

$$x_c = c_1 \cos(\omega t) + c_2 \sin(\omega t).$$

$$x'' + \omega^2 x = F_0 \sin(\gamma t)$$

Suppose  $\gamma \neq \omega$

Note that

$$x_c = c_1 \cos(\omega t) + c_2 \sin(\omega t).$$

Using the method of undetermined coefficients, the **first guess** to the particular solution is

$$x_p = A \cos(\gamma t) + B \sin(\gamma t) \quad \text{will this form work?}$$

Yes it will!

The displacement will look like

$$x = c_1 \cos(\omega t) + c_2 \sin(\omega t) + A \cos(\gamma t) + B \sin(\gamma t)$$

$$x'' + \omega^2 x = F_0 \sin(\gamma t)$$

Suppose  $\gamma = \omega$

Note that

$$x_c = c_1 \cos(\omega t) + c_2 \sin(\omega t).$$

Using the method of undetermined coefficients, the **first guess** to the particular solution is

$$x_p = A \cos(\gamma t) + B \sin(\gamma t) = A \cos(\omega t) + B \sin(\omega t)$$

Will this work? No, it duplicates  $x_c$ .

$$x_p = At \cos(\omega t) + Bt \sin(\omega t).$$

Then

$$x_p = c_1 \cos(\omega t) + c_2 \sin(\omega t) + At \cos(\omega t) + Bt \sin(\omega t)$$

# Forced Undamped Motion and Resonance

For  $F(t) = F_0 \sin(\gamma t)$  starting from rest at equilibrium:

$$\text{Case (1): } x'' + \omega^2 x = F_0 \sin(\gamma t), \quad x(0) = 0, \quad x'(0) = 0$$

$$x(t) = \frac{F_0}{\omega^2 - \gamma^2} \left( \sin(\gamma t) - \frac{\gamma}{\omega} \sin(\omega t) \right)$$

**If  $\gamma \approx \omega$ , the amplitude of motion could be rather large!**

## Pure Resonance

$$\text{Case (2): } x'' + \omega^2 x = F_0 \sin(\omega t), \quad x(0) = 0, \quad x'(0) = 0$$

$$x(t) = \frac{F_0}{2\omega^2} \sin(\omega t) - \frac{F_0}{2\omega} t \cos(\omega t)$$

**Note that the amplitude,  $\alpha$ , of the second term is a function of  $t$ :**

$$\alpha(t) = \frac{F_0 t}{2\omega}$$

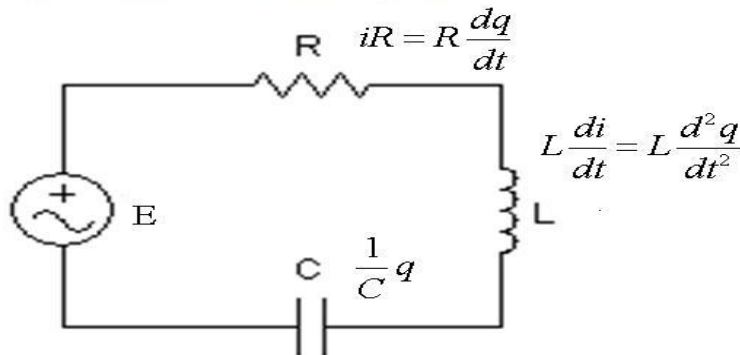
**which grows without bound!**

► Forced Motion and Resonance Applet

Choose "Elongation diagram" to see a plot of displacement. Try exciting frequencies close to  $\omega$ .

## Section 12: LRC Series Circuits

Potential Drops Across Components:



**Figure:** Kirchhoff's Law: The charge  $q$  on the capacitor satisfies  $Lq'' + Rq' + \frac{1}{C}q = E(t)$ .

This is a second order, linear, constant coefficient nonhomogeneous (if  $E \neq 0$ ) equation.

## LRC Series Circuit (Free Electrical Vibrations)

$$L \frac{d^2 q}{dt^2} + R \frac{dq}{dt} + \frac{1}{C} q = 0$$

If the applied force  $E(t) = 0$ , then the **electrical vibrations** of the circuit are said to be **free**. These are categorized as

**overdamped** if

$$R^2 - 4L/C > 0,$$

**critically damped** if

$$R^2 - 4L/C = 0,$$

**underdamped** if

$$R^2 - 4L/C < 0.$$

*Handwritten notes:*  
← 2 real roots  
← 1 repeated root  
↑ complex conjugate



## Steady and Transient States

Given a nonzero applied voltage  $E(t)$ , we obtain an IVP with nonhomogeneous ODE for the charge  $q$

$$Lq'' + Rq' + \frac{1}{C}q = E(t), \quad q(0) = q_0, \quad q'(0) = i_0.$$

From our basic theory of linear equations we know that the solution will take the form

$$q(t) = q_c(t) + q_p(t).$$

The function of  $q_c$  is influenced by the initial state ( $q_0$  and  $i_0$ ) and will decay exponentially as  $t \rightarrow \infty$ . Hence  $q_c$  is called the **transient state charge** of the system.

## Steady and Transient States

Given a nonzero applied voltage  $E(t)$ , we obtain an IVP with nonhomogeneous ODE for the charge  $q$

$$Lq'' + Rq' + \frac{1}{C}q = E(t), \quad q(0) = q_0, \quad q'(0) = i_0.$$

From our basic theory of linear equations we know that the solution will take the form

$$q(t) = q_c(t) + q_p(t).$$

The function  $q_p$  is independent of the initial state but depends on the characteristics of the circuit ( $L$ ,  $R$ , and  $C$ ) and the applied voltage  $E$ .  $q_p$  is called the **steady state charge** of the system.

## Example

An LRC series circuit has inductance 0.5 h, resistance 10 ohms, and capacitance  $4 \cdot 10^{-3}$  f. Find the steady state current of the system if the applied force is  $E(t) = 5 \cos(10t)$ .

We're asked for steady state current. This

is  $\frac{dq_p}{dt}$ , i.e.  $i_p$ .

The ODE is  $Lq'' + Rq' + \frac{1}{C}q = E$ . where

$$L = \frac{1}{2}, R = 10, C = 4 \cdot 10^{-3} \text{ so } \frac{1}{C} = \frac{1}{4 \cdot 10^{-3}} = \frac{10^3}{4} = 250$$

We have

$$\frac{1}{2}q'' + 10q' + 250q = 5 \cos(10t)$$

In standard form

$$q'' + 20q' + 500q = 10 \cos(10t)$$

Let's find  $q_c$ :  $r^2 + 20r + 500 = 0$

$$r^2 + 20r + 100 - 100 + 500 = 0$$

$$(r+10)^2 + 400 = 0$$

$$(r+10)^2 = -400$$

$$r+10 = \pm 20i$$

$$r = -10 \pm 20i$$

$q_c$  will be

$$q_c = c_1 e^{-10t} \cos(20t) + c_2 e^{-10t} \sin(20t)$$

Now find  $g_p$  given  $g(t) = 10 \cos(10t)$

Using undetermined coefficients,

$$g_p = A \cos(10t) + B \sin(10t)$$

This is correct

Substitute

$$g_p' = -10A \sin(10t) + 10B \cos(10t)$$

$$g_p'' = -100A \cos(10t) - 100B \sin(10t)$$

$$g_p'' + 20g_p' + 500g_p = 10 \cos(10t)$$

$$-100A \cos(10t) - 100B \sin(10t) + 20(-10A \sin(10t) + 10B \cos(10t)) \\ + 500(A \cos(10t) + B \sin(10t)) = 10 \cos(10t)$$

Collect  $\cos(10t)$  and  $\sin(10t)$

$$\cos(10t)(400A + 200B) + \sin(10t)(-200A + 400B) = \\ 10 \cos(10t) + 0 \cdot \sin(10t)$$

Matching gives

$$400A + 200B = 10$$

$$-200A + 400B = 0$$

$$\begin{aligned} 400A + 200B &= 10 \\ -400A + 800B &= 0 \end{aligned}$$

---

$$1000B = 10 \Rightarrow B = \frac{10}{1000} = \frac{1}{100}$$

$$200A = 400B \Rightarrow A = 2B = 2\left(\frac{1}{100}\right) = \frac{2}{100}$$

So

$$i_p = 0.02 \cos(10t) + 0.01 \sin(10t)$$

The steady state current

$$\frac{di_p}{dt} = -10(0.02) \sin(10t) + 10(0.01) \cos(10t)$$

$$\Rightarrow \hat{i}_p = 0.1 \cos(10t) - 0.2 \sin(10t)$$