November 5 Math 2306 sec. 53 Fall 2018

Section 15: Shift Theorems

Theorem: (translation in *s*) Suppose $\mathscr{L} \{f(t)\} = F(s)$. Then for any real number *a*

$$\mathscr{L}\left\{ e^{at}f(t)\right\} =F(s-a).$$

For example,

$$\mathscr{L}\left\{t^{n}\right\} = \frac{n!}{s^{n+1}} \implies \mathscr{L}\left\{e^{at}t^{n}\right\} = \frac{n!}{(s-a)^{n+1}}.$$
$$\mathscr{L}\left\{\cos(kt)\right\} = \frac{s}{s^{2}+k^{2}} \implies \mathscr{L}\left\{e^{at}\cos(kt)\right\} = \frac{s-a}{(s-a)^{2}+k^{2}}.$$

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Theorem (translation in *t*) If $F(s) = \mathscr{L}{f(t)}$ and a > 0, then

$$\mathscr{L}{f(t-a)}\mathscr{U}(t-a)} = e^{-as}F(s).$$

In particular,

$$\mathscr{L}\{\mathscr{U}(t-a)\}=\frac{e^{-as}}{s}.$$

As another example,

$$\mathscr{L}\lbrace t^n\rbrace = \frac{n!}{s^{n+1}} \implies \mathscr{L}\lbrace (t-a)^n \mathscr{U}(t-a)\rbrace = \frac{n!e^{-as}}{s^{n+1}}.$$

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A Couple of Useful Results

Another formulation of this translation theorem is

(1)
$$\mathscr{L}\lbrace g(t)\mathscr{U}(t-a)\rbrace = e^{-as}\mathscr{L}\lbrace g(t+a)\rbrace.$$

 $\Im(t) = \Im((t+a) - a)$
Example: Find $\mathscr{L}\lbrace \cos t \mathscr{U}\left(t-\frac{\pi}{2}\right)\rbrace = e^{-\frac{\pi}{2}s} \mathscr{L}\left\lbrace C_{os}\left(t+\frac{\pi}{2}\right)\rbrace\right\rbrace$

Note

$$C_{\varphi}(t+\frac{\pi}{2}) = C_{1}t C_{0}s^{\pi}\lambda - S_{1}st S_{1}s^{\pi}\lambda$$

 $= C_{1}t \cdot 0 - S_{1}st \cdot 1$
 $= -S_{1}st$

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So
$$\mathcal{Y}\left\{C_{sst} \mathcal{U}\left(t-\overline{T}/2\right)\right\}^{\frac{1}{2}} = e^{-\overline{T}/2S} \mathcal{Y}\left\{G_{s}\left(t+\overline{T}/2\right)\right\}$$

 $= e^{-\overline{T}/2S} \mathcal{Y}\left\{-S_{s}t\right\}$
 $= -e^{-\overline{T}/2S} \left(\frac{1}{S^{2}+1^{2}}\right)$
 $= -\frac{e^{-\overline{T}/2S}}{S^{2}+1}$

A Couple of Useful Results

The inverse form of this translation theorem is

(2)
$$\mathscr{L}^{-1}\{e^{-as}F(s)\}=f(t-a)\mathscr{U}(t-a).$$

Example: Find
$$\mathscr{L}^{-1}\left\{\frac{e^{-2s}}{s(s+1)}\right\}$$

We need by find $f(k) = \mathscr{J}\left\{\frac{1}{s(s+1)}\right\}$
We will do partial fraction decomp
 $\frac{1}{s(s+1)} = \frac{A}{s} + \frac{B}{s+1}$

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$$\begin{vmatrix} = A(s+1) + Bs \\ S=0 \quad |= A \\ s=-1 \quad |= -B \\ \end{vmatrix} \xrightarrow{A=1} \xrightarrow{A=1} \xrightarrow{A=-1} B = -1$$

$$f(t) = \underbrace{y'}_{s(s+1)} = \underbrace{y$$

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$$\mathcal{J}^{-1}\left\{\frac{e^{2s}}{s(s+1)}\right\} = f(t-2)\mathcal{U}(t-2)$$

$$= (1 - e^{-(t-2)})U(t-2)$$

Section 16: Laplace Transforms of Derivatives and IVPs

Suppose *f* has a Laplace transform and that *f* is differentiable on $[0, \infty)$. Obtain an expression for the Laplace transform of f'(t). (Assume *f* is of exponential order *c* for some *c*.)

x

$$= 0 - f(0) e^{\circ} + 5 \int_{0}^{\infty} e^{-st} f(t) dt$$

 $= -f(0) + s \ \mathcal{L}{f(4)}$ If we call $\mathcal{L}{f(4)} = F(s)$, then $\mathcal{L}{f'(4)} = s F(s) - f(0)$

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Transforms of Derivatives

If $\mathscr{L} \{f(t)\} = F(s)$, we have $\mathscr{L} \{f'(t)\} = sF(s) - f(0)$. We can use this relationship recursively to obtain Laplace transforms for higher derivatives of *f*.

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For example

 $\mathscr{L} \{ f''(t) \} = s \mathscr{L} \{ f'(t) \} - f'(t)$ $= s \left(sF(s) - f(t) \right) - f'(t)$ $= s^2 F(s) - s f(t) - f'(t)$

Transforms of Derivatives

For y = y(t) defined on $[0, \infty)$ having derivatives y', y'' and so forth, if

 $\mathscr{L}\left\{ \mathbf{y}(t)\right\} =\mathbf{Y}(\mathbf{s}),$

then

$$\mathscr{L}\left\{\frac{dy}{dt}\right\} = sY(s) - y(0),$$
$$\mathscr{L}\left\{\frac{d^2y}{dt^2}\right\} = s^2Y(s) - sy(0) - y'(0),$$
$$\vdots$$
$$\mathscr{L}\left\{\frac{d^ny}{dt^n}\right\} = s^nY(s) - s^{n-1}y(0) - s^{n-2}y'(0) - \dots - y^{(n-1)}(0).$$

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Differential Equation

For constants *a*, *b*, and *c*, take the Laplace transform of both sides of the equation

$$ay'' + by' + cy = g(t), \quad y(0) = y_0, \quad y'(0) = y_1$$
Let $\mathcal{Y}{y(t)} = Y(s)$ and $\mathcal{Y}{g(t)} = G(s)$
Toke transform of both sides
$$\mathcal{Y}{ay'' + by' + cy} = \mathcal{Y}{g}$$

$$a\mathcal{Y}{y''} + b\mathcal{Y}{y'} + c\mathcal{Y}{z} = \mathcal{Y}{z}$$

$$a\mathcal{Y}{y''} + b\mathcal{Y}{y'} + c\mathcal{Y}{z} = \mathcal{Y}{z}$$

$$a\mathcal{Y}{y''} + b\mathcal{Y}{y'} + c\mathcal{Y}{z} = \mathcal{Y}{z}$$

$$a\mathcal{Y}{y''} + c\mathcal{Y}{z} = \mathcal{Y}{z}$$

$$a\mathcal{Y}{z} = \mathcal{Y}{z}$$

Yes is the Laploce transform of the solution
to the IVP with
$$y(0) = y_0$$
 and $y'(0) = 1$.
Let's isolate Yes).
 $as^{2}Y_{(s)} - asy(0) - ay'(0) + bsY_{(s)} - by(0) + cY_{(s)} = G(s)$
 $as^{2}Y_{(s)} - asy_{0} - ay_{1} + bsY_{(s)} - by_{0} + cY_{(s)} = G(s)$
 $as^{2}Y_{(s)} + bsY_{(s)} + cY_{(s)} = ay_{0}s + ay_{1} + by_{0} + G(s)$
 $(as^{2} + bs + c)Y_{(s)} = ay_{0}s + ay_{1} + by_{0} + G(s)$

$$Y_{(5)} = \frac{ay_0s + ay_1 + by_0}{as^2 + bs + c} + \frac{G(s)}{as^2 + bs + c}$$

 $\mathcal{Y}^{(t)} = \mathcal{I}^{(t)} \{ \mathcal{Y}^{(t)} \}$

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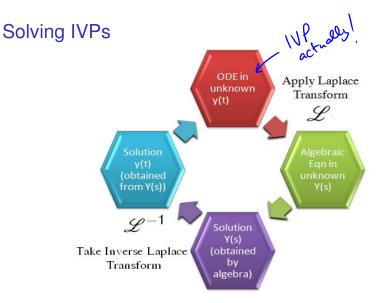


Figure: We use the Laplace transform to turn our DE into an algebraic equation. Solve this transformed equation, and then transform back.

General Form

We get

$$Y(s) = rac{Q(s)}{P(s)} + rac{G(s)}{P(s)}$$

where Q is a polynomial with coefficients determined by the initial conditions, G is the Laplace transform of g(t) and P is the **characteristic polynomial** of the original equation.

$$\mathscr{L}^{-1}\left\{\frac{Q(s)}{P(s)}\right\}$$

is called the zero input response,

and

$$\mathscr{L}^{-1}\left\{\frac{G(s)}{P(s)}\right\}$$
 is called the **zero state response**.