

Section 4.6: Rank

Remarks

- ▶ We can naturally associate three vector spaces with an $m \times n$ matrix A . $\text{Row } A$ and $\text{Nul } A$ are subspaces of \mathbb{R}^n and $\text{Col } A$ is a subspace of \mathbb{R}^m .
- ▶ Careful! The rows of the rref do span $\text{Row } A$. But we go back to the columns in the original matrix to get vectors that span $\text{Col } A$. (Get a basis for $\text{Col } A$ from A itself!)
- ▶ Careful Again! Just because the first three rows of the rref span $\text{Row } A$ **does not mean** the first three rows of A span $\text{Row } A$. (Get a basis for $\text{Row } A$ from the rref!)

Remarks

- ▶ Row operations preserve row space, but change linear dependence relations of rows. Row operations change column space, but preserve linear dependence relations of columns.
- ▶ Another way to obtain a basis for Row A is to take the transpose A^T and do row operations. We have the following relationships:

$$\text{Col } A = \text{Row } A^T \quad \text{and} \quad \text{Row } A = \text{Col } A^T.$$

- ▶ The dimension of the null space is called the **nullity**.

Rank

Definition: The **rank** of a matrix A (denoted $\text{rank } A$) is the dimension of the column space of A .

Theorem: For $m \times n$ matrix A , $\dim \text{Col } A = \dim \text{Row } A = \text{rank } A$.
Moreover

$$\text{rank } A + \dim \text{Nul } A = n.$$

Note: This theorem states the rather obvious fact that

$$\left\{ \begin{array}{c} \text{number of} \\ \text{pivot columns} \end{array} \right\} + \left\{ \begin{array}{c} \text{number of} \\ \text{non-pivot columns} \end{array} \right\} = \left\{ \begin{array}{c} \text{total number} \\ \text{of columns} \end{array} \right\}.$$

Examples

(1) A is a 5×4 matrix with $\text{rank } A = 4$. What is $\dim \text{Nul } A$?

$$\text{Here } n = 4$$

$$\text{rank } A + \dim \text{Nul } A = n$$

$$4 + \dim \text{Nul } A = 4$$

$$\dim \text{Nul } A = 0$$

What does this mean about the
equation $A\vec{x} = \vec{0}$?

It has only the trivial solution.

Examples

(2) Suppose A is 7×5 and $\dim \text{Col } A = 2$. Determine the nullity¹ of A , the rank A^T , and the nullity of A^T .

$$\text{For } A, n=5. \quad \text{rank } A + \dim \text{Nul } A = 5$$

$$\begin{aligned} \text{rank} &= \dim \text{Col } A & 2 + \dim \text{Nul } A = 5 &\Rightarrow \text{nullity of } A \\ & & &\text{is } 3. \end{aligned}$$

$$\begin{aligned} \text{Col}(A^T) &= \text{row}(A) \\ \dim \text{Col}(A^T) &= \dim \text{Row}(A) = \dim \text{Col}(A) = 2 \end{aligned}$$

$$A^T \text{ is } 5 \times 7 \text{ so its "n" is } 7$$

$$\text{rank } A^T + \text{nullity } A^T = 7$$

$$2 + \text{nullity } A^T = 7 \Rightarrow \text{nullity of } A^T \text{ is } 5.$$

¹Nullity is another name for $\dim \text{Nul } A$.

Addendum to Invertible Matrix Theorem

Let A be an $n \times n$ matrix. The following are equivalent to the statement that A is invertible.

- (m) The columns of A form a basis for \mathbb{R}^n
- (n) $\text{Col } A = \mathbb{R}^n$
- (o) $\dim \text{Col } A = n$
- (p) $\text{rank } A = n$
- (q) $\text{Nul } A = \{\mathbf{0}\}$
- (r) $\dim \text{Nul } A = 0$

Section 6.1: Inner Product, Length, and Orthogonality

Recall: A vector \mathbf{u} in \mathbb{R}^n can be considered an $n \times 1$ matrix. It follows that \mathbf{u}^T is a $1 \times n$ matrix

$$\mathbf{u}^T = [u_1 \ u_2 \ \cdots \ u_n].$$

Definition: For vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n we define the **inner product** of \mathbf{u} and \mathbf{v} (also called the **dot product**) by the **matrix product**

$$\mathbf{u}^T \mathbf{v} = [u_1 \ u_2 \ \cdots \ u_n] \begin{bmatrix} v_1 \\ v_2 \\ \vdots \\ v_n \end{bmatrix} = u_1 v_1 + u_2 v_2 + \cdots + u_n v_n.$$

Note that this product produces a scalar. It is sometimes called a *scalar product*.

Theorem (Properties of the Inner Product)

We'll use the notation $\mathbf{u} \cdot \mathbf{v} = \mathbf{u}^T \mathbf{v}$.

Theorem: For \mathbf{u} , \mathbf{v} and \mathbf{w} in \mathbb{R}^n and real scalar c

(a) $\mathbf{u} \cdot \mathbf{v} = \mathbf{v} \cdot \mathbf{u}$

(b) $(\mathbf{u} + \mathbf{v}) \cdot \mathbf{w} = \mathbf{u} \cdot \mathbf{w} + \mathbf{v} \cdot \mathbf{w}$

(c) $c(\mathbf{u} \cdot \mathbf{v}) = (c\mathbf{u}) \cdot \mathbf{v} = \mathbf{u} \cdot (c\mathbf{v})$

(d) $\mathbf{u} \cdot \mathbf{u} \geq 0$, with $\mathbf{u} \cdot \mathbf{u} = 0$ if and only if $\mathbf{u} = \mathbf{0}$.

The Norm

The property $\mathbf{u} \cdot \mathbf{u} \geq 0$ means that $\sqrt{\mathbf{u} \cdot \mathbf{u}}$ always exists as a real number.

Definition: The **norm** of the vector \mathbf{v} in \mathbb{R}^n is the nonnegative number denoted and defined by

$$\|\mathbf{v}\| = \sqrt{\mathbf{v} \cdot \mathbf{v}} = \sqrt{v_1^2 + v_2^2 + \cdots + v_n^2}$$

where v_1, v_2, \dots, v_n are the components of \mathbf{v} .

As a directed line segment, the norm is the same as the **length**.

Norm and Length

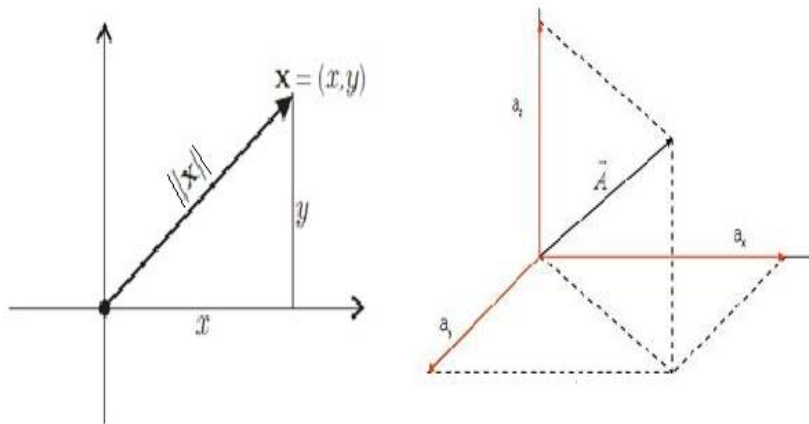


Figure: In \mathbb{R}^2 or \mathbb{R}^3 , the norm corresponds to the classic geometric property of length.

Unit Vectors and Normalizing

Theorem: For vector \mathbf{v} in \mathbb{R}^n and scalar c

$$\|c\mathbf{v}\| = |c|\|\mathbf{v}\|.$$

Definition: A vector \mathbf{u} in \mathbb{R}^n for which $\|\mathbf{u}\| = 1$ is called a **unit vector**.

Remark: Given any nonzero vector \mathbf{v} in \mathbb{R}^n , we can obtain a unit vector \mathbf{u} in the same direction as \mathbf{v}

$$\mathbf{u} = \frac{\mathbf{v}}{\|\mathbf{v}\|}.$$

This process, of dividing out the norm, is called **normalizing** the vector \mathbf{v} .

Example

Show that $\mathbf{v}/\|\mathbf{v}\|$ is a unit vector.

$$\frac{\vec{v}}{\|\vec{v}\|} = \frac{1}{\|\vec{v}\|} \vec{v} \quad \text{so}$$

$$\left\| \frac{1}{\|\vec{v}\|} \vec{v} \right\| = \left| \frac{1}{\|\vec{v}\|} \right| \|\vec{v}\|$$

but $\|\vec{v}\| > 0$

$$= \frac{1}{\|\vec{v}\|} \|\vec{v}\|$$

$$= \frac{\|\vec{v}\|}{\|\vec{v}\|} = 1$$

Example

Find a unit vector in the direction of $\mathbf{v} = (1, 3, 2)$.

$$\|\vec{v}\|^2 = 1^2 + 3^2 + 2^2 = 1 + 9 + 4 = 14$$

A unit vector in the direction of \vec{v} is

$$\frac{1}{\|\vec{v}\|} \vec{v} = \frac{1}{\sqrt{14}} \begin{bmatrix} 1 \\ 3 \\ 2 \end{bmatrix} = \begin{bmatrix} \frac{1}{\sqrt{14}} \\ \frac{3}{\sqrt{14}} \\ \frac{2}{\sqrt{14}} \end{bmatrix}$$

Distance in \mathbb{R}^n

Definition: For vectors \mathbf{u} and \mathbf{v} in \mathbb{R}^n , the **distance between \mathbf{u} and \mathbf{v}** is denoted and defined by

$$\text{dist}(\mathbf{u}, \mathbf{v}) = \|\mathbf{u} - \mathbf{v}\|.$$

Example: Find the distance between $\mathbf{u} = (4, 0, -1, 1)$ and $\mathbf{v} = (0, 0, 2, 7)$.

$$\bar{\mathbf{u}} - \bar{\mathbf{v}} = (4, 0, -1, 1) - (0, 0, 2, 7) = (4, 0, -3, -6)$$

$$\text{dist}(\bar{\mathbf{u}}, \bar{\mathbf{v}}) = \sqrt{4^2 + 0^2 + (-3)^2 + (-6)^2} = \sqrt{16 + 9 + 36} = \sqrt{61}$$

Orthogonality

Definition: Two vectors are **\mathbf{u}** and **\mathbf{v}** **orthogonal** if $\mathbf{u} \cdot \mathbf{v} = 0$.

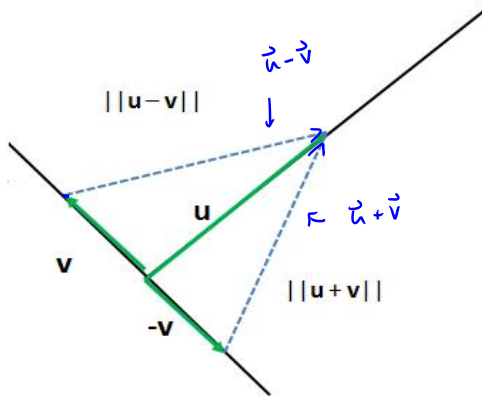


Figure: Note that two vectors are perpendicular if $\|\mathbf{u} - \mathbf{v}\| = \|\mathbf{u} + \mathbf{v}\|$

Orthogonal and Perpendicular

Show that $\|\mathbf{u} - \mathbf{v}\| = \|\mathbf{u} + \mathbf{v}\|$ if and only if $\mathbf{u} \cdot \mathbf{v} = 0$.

Note

$$\begin{aligned}\|\vec{u} - \vec{v}\|^2 &= (\vec{u} - \vec{v}) \cdot (\vec{u} - \vec{v}) = (\vec{u} - \vec{v}) \cdot \vec{u} - (\vec{u} - \vec{v}) \cdot \vec{v} \\ &= \vec{u} \cdot \vec{u} - \vec{v} \cdot \vec{u} - \vec{u} \cdot \vec{v} + \vec{v} \cdot \vec{v} \\ &= \|\vec{u}\|^2 - 2\vec{u} \cdot \vec{v} + \|\vec{v}\|^2\end{aligned}$$

Similarly

$$\begin{aligned}\|\vec{u} + \vec{v}\|^2 &= (\vec{u} + \vec{v}) \cdot (\vec{u} + \vec{v}) \\ &= \|\vec{u}\|^2 + 2\vec{u} \cdot \vec{v} + \|\vec{v}\|^2\end{aligned}$$

Note: If $\|\vec{u} - \vec{v}\|^2 = \|\vec{u} + \vec{v}\|^2$ then $\|\vec{u} - \vec{v}\| = \|\vec{u} + \vec{v}\|$

If $\|\vec{u} - \vec{v}\| = \|\vec{u} + \vec{v}\|$, then $\|\vec{u} - \vec{v}\|^2 = \|\vec{u} + \vec{v}\|^2$

So

$$\cancel{\|\vec{u}\|^2} - 2\vec{u} \cdot \vec{v} + \cancel{\|\vec{v}\|^2} = \cancel{\|\vec{u}\|^2} + 2\vec{u} \cdot \vec{v} + \cancel{\|\vec{v}\|^2}$$

$$\Rightarrow 0 = 4\vec{u} \cdot \vec{v} \Rightarrow \vec{u} \cdot \vec{v} = 0$$

If $\vec{u} \cdot \vec{v} = 0$, then

$$\|\vec{u} - \vec{v}\|^2 = \|\vec{u}\|^2 - 2 \cdot 0 + \|\vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$$

and

$$\|\vec{u} + \vec{v}\|^2 = \|\vec{u}\|^2 + 2 \cdot 0 + \|\vec{v}\|^2 = \|\vec{u}\|^2 + \|\vec{v}\|^2$$

Hence $\|\vec{u} + \vec{v}\| = \|\vec{u} - \vec{v}\|$.