October 26 Math 2306 sec. 57 Fall 2017

Section 15: Shift Theorems

Theorem: (Translation in *s*) Suppose $\mathscr{L} \{f(t)\} = F(s)$. Then for any real number *a*

$$\mathscr{L}\left\{\boldsymbol{e}^{\boldsymbol{a}t}\boldsymbol{f}(t)\right\}=\boldsymbol{F}(\boldsymbol{s}-\boldsymbol{a}).$$

For example,

$$\mathscr{L}\left\{t^{n}\right\} = \frac{n!}{s^{n+1}} \implies \mathscr{L}\left\{e^{at}t^{n}\right\} = \frac{n!}{(s-a)^{n+1}}.$$
$$\mathscr{L}\left\{\cos(kt)\right\} = \frac{s}{s^{2}+k^{2}} \implies \mathscr{L}\left\{e^{at}\cos(kt)\right\} = \frac{s-a}{(s-a)^{2}+k^{2}}.$$

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The Unit Step Function

Let $a \ge 0$. The unit step function $\mathscr{U}(t-a)$ is defined by

$$\mathscr{U}(t-a) = \left\{ egin{array}{cc} 0, & 0 \leq t < a \ 1, & t \geq a \end{array}
ight.$$

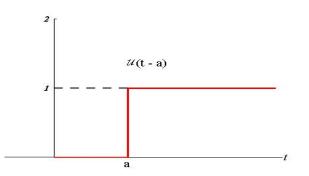


Figure: We can use the unit step function to provide convenient expressions for piecewise defined functions.

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Translation in t

Given a function f(t) for $t \ge 0$, and a number a > 0

$$f(t-a)\mathscr{U}(t-a) = \begin{cases} 0, & 0 \le t < a \\ f(t-a), & t \ge a \end{cases}$$

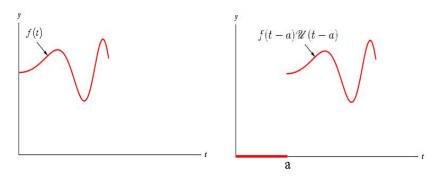


Figure: The function $f(t - a) \mathcal{U}(t - a)$ has the graph of *f* shifted *a* units to the right with value of zero for *t* to the left of *a*.

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Theorem (translation in *t*) If $F(s) = \mathscr{L}{f(t)}$ and a > 0, then

$$\mathscr{L}{f(t-a)}\mathscr{U}(t-a)} = e^{-as}F(s).$$

In particular,

$$\mathscr{L}\{\mathscr{U}(t-a)\}=\frac{e^{-as}}{s}.$$

As another example,

$$\mathscr{L}{t^n} = \frac{n!}{s^{n+1}} \implies \mathscr{L}{(t-a)^n}\mathscr{U}(t-a) = \frac{n!e^{-as}}{s^{n+1}}.$$

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Find
$$\mathscr{L}\{\mathscr{U}(t-a)\}$$

 $\mathscr{U}[t-a] = \begin{cases} 0, 0 \le t : a \\ 1, t \ge a \end{cases}$
 $\mathfrak{M} = \int_{0}^{a} e^{st} \mathscr{U}[t-a] dt$
 $= \int_{0}^{a} e^{st} \cdot 0 dt + \int_{0}^{\infty} e^{st} \cdot 1 dt$
 $= \int_{0}^{\infty} e^{st} dt$
 $= \int_{a}^{\infty} e^{st} dt$
 $= \int_{0}^{\infty} e^{st} dt$
 $= \int_{0}^{\infty} e^{st} dt$
 $= \int_{0}^{\infty} e^{st} dt$
 $= \int_{0}^{\infty} e^{s(\tau+a)} d\tau$
 $= \int_{0}^{\infty} e^{s(\tau+a)} d\tau$

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Note
$$e^{-S(z+a)}$$
 - $sz - sa$ - sz - sa
= e = $e \cdot e$

$$= \int_{0}^{\infty} e^{-\alpha s} e^{-s\tau} d\tau$$

$$= e^{-\alpha s} \int_{e}^{\infty} e^{-s\tau} d\tau$$

$$= e^{-\alpha s} \chi \{ | \} = \frac{e^{\alpha s}}{s}$$

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Example

Find the Laplace transform $\mathscr{L} \{h(t)\}$ where

$$h(t) = \begin{cases} 1, & 0 \le t < 1 \\ t, & t \ge 1 \end{cases}$$

(a) First write *h* in terms of unit step functions.

$$h(t) = 1 - 1u(t - 1) + tu(t - 1)$$

$$= 1 + (t - i) U(t - i)$$

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Note if f(t) = t then f(t-1) = t-1

so $(t-1)\mathcal{U}(t-1) = f(t-1)\mathcal{U}(t-1)$ for f(t) = t.

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Example Continued...

(b) Now use the fact that $h(t) = 1 + (t-1)\mathcal{U}(t-1)$ to find $\mathcal{L}\{h\}$.

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A Couple of Useful Results

Another formulation of this translation theorem is

(1)
$$\mathscr{L}{g(t)\mathscr{U}(t-a)} = e^{-as}\mathscr{L}{g(t+a)}.$$

Note $g(t) = g(t+\alpha - \alpha)$ Example: Find $\mathscr{L}\left\{\cos t \mathscr{U}\left(t - \frac{\pi}{2}\right)\right\} = e^{-\frac{\pi}{2}S} \mathcal{L}\left\{C_{or}\left(t + \frac{\pi}{2}\right)\right\}$

$$C_{os}(t+\frac{\pi}{2}) = C_{oc}t C_{os}\frac{\pi}{2} - S_{in}t S_{in}\frac{\pi}{2}$$
$$= -S_{in}t$$
$$\forall \{C_{os}t \mathcal{U}(t-\frac{\pi}{2})\} = e^{-\frac{\pi}{2}S} \Re \{-S_{in}t\}$$

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 $= - e^{-\frac{\pi}{3}s} \left(\frac{1}{s^3+1}\right)$ -е t $S^2 + 1$

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A Couple of Useful Results

The inverse form of this translation theorem is

(2)
$$\mathscr{L}^{-1}\lbrace e^{-as}F(s)\rbrace = f(t-a)\mathscr{U}(t-a).$$
 $\mathscr{U}\lbrace f(t)\rbrace = \nabla(s)$

Example: Find
$$\mathscr{L}^{-1}\left\{\frac{e^{-2s}}{s(s+1)}\right\}$$
: $\int_{c}^{1}\left\{\frac{-2s}{e} - \frac{1}{s(s+1)}\right\}$
we need $\int_{c}^{1}\left\{\frac{1}{s(s+1)}\right\}$ Particle freedrooms
 $\frac{1}{s(s+1)} = \frac{A}{s} + \frac{B}{s+1} \Rightarrow 1 = A(s+1) + Bs$
set $s = 0$, $A = 1$
 $= \frac{1}{5} - \frac{1}{5+1}$ $s = -1$

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$$y' \{ \frac{1}{\delta(s_{\tau_1})} \} = g' \{ \frac{1}{5} - \frac{1}{5_{\tau_1}} \} = g' \{ \frac{1}{5} - \chi' \{ \frac{1}{5_{\tau_1}} \}$$

= $1 - e^{t}$

$$\int_{-\infty}^{\infty} \frac{e^{2s}}{s(s+1)} = \left(1 - e^{(t-2)}\right) \mathcal{U}(t-2)$$

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Section 16: Laplace Transforms of Derivatives and IVPs

Suppose *f* has a Laplace transform and that *f* is differentiable on $[0, \infty)$. Obtain an expression for the Laplace transform of f'(t). (Assume *f* is of exponential order *c* for some *c*.)

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Transforms of Derivatives

If $\mathscr{L} \{f(t)\} = F(s)$, we have $\mathscr{L} \{f'(t)\} = sF(s) - f(0)$. We can use this relationship recursively to obtain Laplace transforms for higher derivatives of *f*.

For example

 $\mathscr{Z} \{ t''(t) \} = \mathcal{Z} \{ t'(t) \} - \mathcal{Z} \{ t(t) \} - \mathcal{Z} \{ t($

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Transforms of Derivatives

For y = y(t) defined on $[0, \infty)$ having derivatives y', y'' and so forth, if

 $\mathscr{L}\left\{ \mathbf{y}(t)\right\} =\mathbf{Y}(\mathbf{s}),$

then

$$\mathscr{L}\left\{\frac{dy}{dt}\right\} = sY(s) - y(0),$$
$$\mathscr{L}\left\{\frac{d^2y}{dt^2}\right\} = s^2Y(s) - sy(0) - y'(0),$$
$$\vdots$$
$$\mathscr{L}\left\{\frac{d^ny}{dt^n}\right\} = s^nY(s) - s^{n-1}y(0) - s^{n-2}y'(0) - \dots - y^{(n-1)}(0).$$

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Differential Equation

For constants *a*, *b*, and *c*, take the Laplace transform of both sides of the equation

$$ay'' + by' + cy = g(t), \quad y(0) = y_0, \quad y'(0) = y_1$$

$$\begin{cases} ay'' + by' + cy \\ = & \chi \{g, le_1\} \end{cases}$$

$$Let \quad \chi \{y\} = & Y(s) \\ & \chi \{g\} = & G(s) \end{cases}$$

$$a\chi \{y''\} + b\chi \{y'\} + c\chi \{y\} = & \chi \{g\} \\ = & \chi \{g\} = & G(s) \end{cases}$$

$$a\chi \{y''\} + b\chi \{y'\} + c\chi \{y\} = & \chi \{g\} \\ = & \chi \{g\} = & G(s) \end{cases}$$

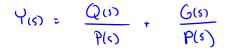
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Let
$$Q(s) = ay_0 s + ay_1 + by_0 \rightarrow a$$

 $P(s) = as^2 + bs + C$

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It should be that the solution

$$y(t) = y' \{Y_{(5)}\} = \tilde{y}' \{\frac{Q_{(5)}}{P_{(5)}} + \frac{G_{(5)}}{P_{(5)}}\}$$

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Solving IVPs

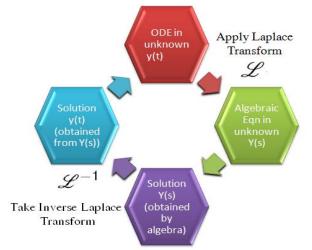


Figure: We use the Laplace transform to turn our DE into an algebraic equation. Solve this transformed equation, and then transform back.

General Form

We get

$$Y(s) = rac{Q(s)}{P(s)} + rac{G(s)}{P(s)}$$

where Q is a polynomial with coefficients determined by the initial conditions, G is the Laplace transform of g(t) and P is the **characteristic polynomial** of the original equation.

$$\mathscr{L}^{-1}\left\{\frac{Q(s)}{P(s)}\right\}$$

is called the zero input response,

and

$$\mathscr{L}^{-1}\left\{\frac{G(s)}{P(s)}\right\}$$
 is called the **zero state response**.