#### October 9 Math 2306 sec 54 Fall 2015

#### **Section 4.6: Variation of Parameters**

Solve the ODE

$$x^2y'' + xy' - 4y = \ln x,$$

given that  $y_c = c_1 x^2 + c_2 x^{-2}$  is the complementary solution.

$$y_1: x^2$$
,  $y_2: x^{-2}$ 

Stendard form:
$$y'' + \frac{1}{x}y' - \frac{4}{x^2}y = \frac{\ln x}{x^2}$$

$$W: \begin{vmatrix} x^2 & x^{-2} \\ 2x & -2x^{-3} \end{vmatrix}$$

$$g(x) = \frac{\ln x}{x^2}$$

$$= \chi^{2}(-2\chi^{-3}) - 2\chi(\chi^{-2}) = -4\chi^{-1} = -\frac{4}{\chi}$$

$$u_{1} = \int \frac{\partial^{2} \partial}{\partial x} dx = \int \frac{-x^{2}}{\sqrt{x^{2}}} \int \frac{\partial^{2} \partial}{\partial x} dx$$

$$= \frac{1}{4} \left[ \frac{-x^{2}}{\sqrt{x^{2}}} \int \frac{\partial^{2} \partial}{\partial x} dx \right]$$

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$$= \frac{1}{4} \left[ \frac{\partial^{2} \partial}{\partial x} + \frac{\partial^{$$

$$U_{2}: \int \frac{y_{1} g}{w} dx = \int \frac{x^{2} \left(\frac{\int h_{x}}{x^{2}}\right)}{-4/x} dx =$$

$$: -\frac{1}{4} \int x \ln x dx \qquad \ln x dx = \frac{1}{4} dx$$

$$= -\frac{1}{4} \left[\frac{x^{2}}{2} \ln x - \frac{1}{4} x^{2}\right]$$

$$= -\frac{1}{4} \left[\frac{x^{2}}{2} \ln x - \frac{1}{4} x^{2}\right]$$

$$= \frac{1}{4} \left[ \frac{-x^{2}}{2} \int_{0x} - \frac{x^{2}}{4} \right] x^{2} - \frac{1}{4} \left[ \frac{x^{2}}{2} \int_{0x} - \frac{x^{2}}{4} \right] x^{2}$$

$$= -\frac{1}{8} \int_{0x} - \frac{1}{16} - \frac{1}{8} \int_{0x} + \frac{1}{16}$$

$$= -\frac{2}{8} \int_{0x} = -\frac{1}{4} \int_{0x} x$$

The general solution to the ODE is 
$$y = C_1 x^2 + C_2 x^2 - \frac{1}{4} \ln x$$
.

#### Solve the IVP

$$x^{2}y'' + xy' - 4y = \ln x, \quad y(1) = -1, \quad y'(1) = 0$$
From before
$$y = C_{1} x^{2} + C_{2} x^{2} - \frac{1}{4} \ln x$$

$$y' = 2C_{1} x - 2C_{2} x^{3} - \frac{1}{4} \cdot \frac{1}{x}$$

$$y(1) = C_{1} (1)^{2} + C_{2} (1)^{2} - \frac{1}{4} \ln x = -1 \implies C_{1} + C_{2} = -1$$

$$y'(1) = 2C_1(1) - 2C_2(1) - \frac{1}{4} + \frac{1}{4} = 0 \implies 2C_1 - 2C_2 = \frac{1}{4}$$



$$\frac{2C_{1} + 2C_{2} = -2}{2C_{1} - 2C_{2} = \frac{1}{4}}$$

$$\frac{C_{2} = -1 - C_{1}}{4C_{1} = -\frac{7}{4}} \Rightarrow C_{1} = -\frac{7}{16}$$

$$= -1 + \frac{7}{16} = -\frac{9}{16}$$

The solution to the IVP is
$$y = -\frac{7}{16} x^2 - \frac{9}{16} x^2 - \frac{1}{4} \ln x$$

# Section 4.9: Solving a System by Elimination

Consider the pair of differential equations

$$\frac{dx}{dt} + y = t$$
$$x - 2\frac{dy}{dt} = 1$$

This is a **linear system of differential equations**. It is linear in each of the two dependent variables (x and y). A **solution** would consist of a pair of functions (x(t), y(t)) that satisfied both equations simultaneously.

## Linear System: IVP

A first order, constant coefficient system IVP has the form

$$\frac{dx}{dt} = a_{11}x + a_{12}y + f(t), \quad x(t_0) = x_0$$

$$\frac{dy}{dt} = a_{21}x + a_{22}y + g(t), \quad y(t_0) = y_0$$

If f(t) = g(t) = 0, the system is homogeneous. Otherwise it is nonhomogeneous.

NOTE: there are two initial conditions, one for each dependent variable. Hence, the solution to the ODE part of the problem must be a 2-parameter family.

In general, for m dependent variables each satisfying an  $n^{th}$  order DE, there will be mn parameters. Here, m = 2 and n = 1.

## **Operator Notation**

We'll introduce the following **operator** notation that will allow us to manipulate the system as though it were *algebraic*. Define the operator *D* and the operator notation via

$$Dy = \frac{dy}{dt}, \quad D^2y = D(Dy) = \frac{d^2y}{dt^2}, \quad D^3y = D(D^2y) = \frac{d^3y}{dt^3}, \quad \cdots$$

## Example:

Write the system of equations using the operator notation.

$$\frac{dx}{dt} + y = t$$
$$x - 2\frac{dy}{dt} = 1$$

$$Dx + y = t$$

$$x - 2Dy = 1$$

## Example:

Write the system of equations using the operator notation.

$$\frac{d^2x}{dt^2} + 2x - \frac{dy}{dt} = \cos 2t$$
$$3\frac{dy}{dt} + \frac{dx}{dt} = -x + 4y - te^t$$

$$D^{2}x + 2x - Dy = Cor2t$$

$$3Dy + Dx = -x + 4y - te^{t}$$

$$7h^{15}$$
  $(D^2+2) \times - Dy = G_52t$   
 $(D^2+2) \times + (3D-4)y = -te^t$ 

# Solving a System by Elimination

**Remark:** The current method is for linear systems with constant coefficients only.

- ▶ Write the system using the operator notation. Line up like variables so that the system appears as an algebraic system.
- ► Eliminate variables using standard operations. Keep in mind that "multiplication" by *D* is differentiation.
- ▶ Obtain an equation (or equations) in each variable separately, and solve using any applicable method.
- Use back substitution as needed to obtain solutions for all dependent variables.

# Solve the System by Elimination

$$\frac{dx}{dt} = 4x + 7y$$

$$\frac{dy}{dt} = x - 2y$$

$$Dx = 4x + 7y \Rightarrow Dx - 4x - 7y = 0$$

$$Dx = 4x + 7y \Rightarrow -x + Dy + 2y = 0$$

$$(D-4) \times -7 = 0$$
  
-  $\times + (D+2) = 0$ 

$$(D-4) \times - 7 = 0$$
  
-  $(D-4) \times + (D-4)(D+2) = (D-4) \cdot 0 = 0$ 

$$-7y + (D-4)(D+2)y = 0$$

$$[-7 + D^{2}-4D+2D-8]y = 0$$

$$(D^{2}-2D-15)y = 0 \Rightarrow y''-2y'-15y = 0$$

$$2^{n}t \text{ order linear constant (seeff. egn. (see 4.3))}$$

$$m^{2}-2m-15=0 \Rightarrow (m-5)(m+3)=0$$

$$m=5, m_{2}=-3$$

$$y=C, e+C_{2}e$$

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Were not done. Le 87:11 x (4). need to find we'll pick this yo on Monday.