## Sept 12 Math 2306 sec. 53 Fall 2018

## Section 5: First Order Equations Models and Applications

A Classic Mixing Problem If we are tracking the amount $A$ of some substance (e.g. salt) disolved in some fluid in which we know the flow rates at which fluid is entering $\left(r_{i}\right)$ and leaving $\left(r_{0}\right)$ a receptacle, the initial volume $V(0)$ of fluid, and the substance concentration of the inflow $c_{i}$, then for a well mixed solution

$$
\frac{d A}{d t}=r_{i} \cdot c_{i}-r_{o} \frac{A}{V} .
$$

Here $V(t)=V(0)+\left(r_{i}-r_{0}\right) t$. This equation is first order linear

$$
\frac{d A}{d t}+\frac{r_{0}}{V} A=r_{i} c_{i}
$$

There is nothing precluding one of the coefficeints such as $r_{0}, r_{i}$ or $c_{i}$ from being a nonconstant function of time.

Mixing Problem w/ Non-constant Volume
A tank originally contains 500 gallons of pure water. Brine containing 2 pounds of salt per gallon is pumped in at a rate of $5 \mathrm{gal} / \mathrm{min}$. The well mixed solution is pumped out at the rate of $10 \mathrm{gal} / \mathrm{min}$. Set up the initial value problem governing the amount (pounds) of salt $A(t)$ at time $t$ in minutes. Determine the time interval for which the differential equation is valid.

$$
\frac{d A}{d t}=r_{i} c_{i}-r_{0} c_{0} \text { where } C_{0}=\frac{A}{V}
$$

Here $r_{i}: S$ ad/ min, $c_{i}=2 \frac{\mathrm{lb}}{\mathrm{gal}}$
$S_{0}=10 \mathrm{ge} / \mathrm{min}$

$$
C_{0}=\frac{A}{v(0)+\left(r_{i}-r_{0}\right) t}=\frac{A}{500+(s-10) t}=\frac{A}{s 00-s t}
$$

Note co is orly valid until $V=0$

$$
\begin{gathered}
500-s t=0 \Rightarrow t=100 \\
\frac{d A}{d t}=10-10 \frac{A}{500-5 t}=10-\frac{10}{500-5 t} A \\
\frac{d A}{d t}+\frac{2}{100-t} A=10 \text { with } A(0)=0
\end{gathered}
$$

valid for $0 \leq t<100$

## Mixing Problem w/ Non-constant Volume

A tank originally contains 500 gallons of pure water. Brine containing 2 pounds of salt per gallon is pumped in at a rate of $5 \mathrm{gal} / \mathrm{min}$. The well mixed solution is pumped out at the rate of $10 \mathrm{gal} / \mathrm{min}$. Set up the initial value problem governing the amount of salt $A$. Determine the time interval for which the differential equation is valid.

Solving the problem is left as an exercise. The correct solution will be

$$
A(t)=10(100-t)-\frac{(100-t)^{2}}{10} \quad \text { valid for } \quad 0 \leq t<100
$$

A Nonlinear Modeling Problem

A population $P(t)$ of tilapia changes at a rate jointly proportional to the current population and the difference between the constant carrying capacity ${ }^{1} \mathrm{M}$ of the environment and the current population. Determine the differential equation satsified by $P$.

Current population $P$, difference between $M$ and $P$

$$
\begin{gathered}
P \quad M-P \\
\frac{d P}{d t} \propto P(M-P) \\
\Rightarrow \quad \frac{d P}{d t}=k P(M-P) \text { for some constant } k
\end{gathered}
$$

${ }^{1}$ The carrying capacity is the maximum number of individuals that the environment can support due to limitation of space and resources.

## Logistic Differential Equation

The equation

$$
\frac{d P}{d t}=k P(M-P), \quad k, M>0
$$

is called a logistic growth equation.
Solve this equation ${ }^{2}$ and show that for any $P(0) \neq 0, P \rightarrow M$ as $t \rightarrow \infty$.
The ODE is separable

$$
\frac{1}{P(m-P)} \frac{d P}{d t}=k \Rightarrow \frac{1}{P(m-P)} d P=k d t
$$

$$
\int \frac{1}{P(m-P)} d P=\int k d t
$$

${ }^{2}$ The partial fraction decomposition

$$
\frac{1}{P(M-P)}=\frac{1}{M}\left(\frac{1}{P}+\frac{1}{M-P}\right)
$$

is useful.

Using the parted fraction deconp

$$
\begin{aligned}
\int \frac{1}{M}\left(\frac{1}{P}+\frac{1}{M-P}\right) d P & =\int k d t \\
\int\left(\frac{1}{P}+\frac{1}{M-P}\right) d P & =\int k M d t \\
\ln P-\ln |M-P| & =k M t+C
\end{aligned}
$$

Using $\log$ properties

$$
\begin{aligned}
\ln \left|\frac{P}{M-P}\right| & =k M t+C \\
\left|\frac{P}{M-P}\right| & =e^{k M t+C}=e^{C} e^{k M t}
\end{aligned}
$$

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Let $A=e^{c}$ or $-e^{c}$

$$
\frac{p}{m-p}=A e^{k M t}
$$

Let $P(0)=P_{0}$, then applying this condition

$$
\begin{aligned}
& \frac{P_{0}}{M-P_{0}}=A e^{0}=A \Rightarrow A=\frac{P_{0}}{M-P_{0}} \text { souths } \\
& \frac{P}{M-P}=A e^{k M t} \Rightarrow P=A e^{k M t}(M-P) \\
& P=A M e^{k M t}-A P e^{k M t}
\end{aligned}
$$

$$
\begin{gathered}
P+A P e^{k m t}=A M e^{k M t} \\
\left(1+A e^{k m t}\right) P=A M e^{k m t} \\
P=\frac{A M e^{k M t}}{1+A e^{k m t}}
\end{gathered}
$$

using $A=\frac{P_{0}}{M-P_{0}}$

$$
P=\frac{\frac{P_{0}}{M-P_{0}} M e^{k M t}}{1+\frac{P_{0}}{M-P_{0}} e^{k M t}} \cdot\left(\frac{M-P_{0}}{M-P_{0}}\right)
$$

$$
P(t)=\frac{P_{0} M e^{k M t}}{M-P_{0}+P_{0} e^{k M t}}
$$

This is the solution to the logistic equation subject to

$$
P(0)=P_{0}
$$

The long time population

$$
\begin{aligned}
& \lim _{t \rightarrow \infty} P(t)=\lim _{t \rightarrow \infty} \frac{P_{0} M e^{k M t}}{M-P_{0}+P_{0} e^{k n t}}=\frac{\infty}{\infty} \\
& \begin{array}{l}
\text { by aide } \\
l^{\prime 1+} \operatorname{cofl}_{\text {rue }}
\end{array}=\lim _{t \rightarrow \infty} \frac{P_{0} M \text { hmM } e^{k M t}}{P_{0} k \cdot M e^{k M t}}
\end{aligned}
$$

$$
=\lim _{t \rightarrow \infty} M=M
$$

The limit is $M$ as expected.

## Section 6: Linear Equations Theory and Terminology

Recall that an $n^{\text {th }}$ order linear IVP consists of an equation

$$
a_{n}(x) \frac{d^{n} y}{d x^{n}}+a_{n-1}(x) \frac{d^{n-1} y}{d x^{n-1}}+\cdots+a_{1}(x) \frac{d y}{d x}+a_{0}(x) y=g(x)
$$

to solve subject to conditions

$$
y\left(x_{0}\right)=y_{0}, \quad y^{\prime}\left(x_{0}\right)=y_{1}, \quad \ldots, \quad y^{(n-1)}\left(x_{0}\right)=y_{n-1} .
$$

The problem is called homogeneous if $g(x) \equiv 0$. Otherwise it is called nonhomogeneous.

## Theorem: Existence \& Uniqueness

Theorem: If $a_{0}, \ldots, a_{n}$ and $g$ are continuous on an interval $I$, $a_{n}(x) \neq 0$ for each $x$ in $I$, and $x_{0}$ is any point in $I$, then for any choice of constants $y_{0}, \ldots, y_{n-1}$, the IVP has a unique solution $y(x)$ on $I$.

Put differently, we're guaranteed to have a solution exist, and it is the only one there is!

## Homogeneous Equations

We'll consider the equation

$$
a_{n}(x) \frac{d^{n} y}{d x^{n}}+a_{n-1}(x) \frac{d^{n-1} y}{d x^{n-1}}+\cdots+a_{1}(x) \frac{d y}{d x}+a_{0}(x) y=0
$$

and assume that each $a_{i}$ is continuous and $a_{n}$ is never zero on the interval of interest.

Theorem: If $y_{1}, y_{2}, \ldots, y_{k}$ are all solutions of this homogeneous equation on an interval $l$, then the linear combination

$$
y(x)=c_{1} y_{1}(x)+c_{2} y_{2}(x)+\cdots+c_{k} y_{k}(x)
$$

is also a solution on I for any choice of constants $c_{1}, \ldots, c_{k}$.
This is called the principle of superposition.

## Corollaries

(i) If $y_{1}$ solves the homogeneous equation, the any constant multiple $y=c y_{1}$ is also a solution.
(ii) The solution $y=0$ (called the trivial solution) is always a solution to a homogeneous equation.

## Big Questions:

- Does an equation have any nontrivial solution(s), and
- since $y_{1}$ and $c y_{1}$ aren't truly different solutions, what criteria will be used to call solutions distinct?


## Linear Dependence

Definition: A set of functions $f_{1}(x), f_{2}(x), \ldots, f_{n}(x)$ are said to be linearly dependent on an interval $l$ if there exists a set of constants $c_{1}, c_{2}, \ldots, c_{n}$ with at least one of them being nonzero such that

$$
c_{1} f_{1}(x)+c_{2} f_{2}(x)+\cdots+c_{n} f_{n}(x)=0 \quad \text { for all } \quad x \text { in } I .
$$

A set of functions that is not linearly dependent on / is said to be linearly independent on $I$.

