Sept 12 Math 2306 sec. 53 Fall 2018

Section 5: First Order Equations Models and Applications

A Classic Mixing Problem If we are tracking the amount *A* of some substance (e.g. salt) disolved in some fluid in which we know the flow rates at which fluid is entering (r_i) and leaving (r_o) a receptacle, the initial volume V(0) of fluid, and the substance concentration of the inflow c_i , then for a **well mixed** solution

$$\frac{dA}{dt}=r_i\cdot c_i-r_o\frac{A}{V}.$$

Here $V(t) = V(0) + (r_i - r_o)t$. This equation is first order linear $\frac{dA}{dt} + \frac{r_o}{V}A = r_ic_i$

There is nothing precluding one of the coefficients such as r_o , r_i or c_i from being a nonconstant function of time.

Mixing Problem w/ Non-constant Volume

A tank originally contains 500 gallons of pure water. Brine containing 2 pounds of salt per gallon is pumped in at a rate of 5 gal/min. The well mixed solution is pumped out at the rate of 10 gal/min. Set up the initial value problem governing the amount (pounds) of salt A(t) at time *t* in minutes. Determine the time interval for which the differential equation is valid.

 $\frac{dA}{dt} = r_i c_i - r_o c_o \quad \text{where} \quad C_o = \frac{A}{V}$ Here $r_i = S$ god lmin, $c_i = 2 \frac{1b}{3ad}$ $r_o = 10$ god lmin $C_o = \frac{A}{V(o) + (r_i - r_o)t} = \frac{A}{soo + (s - 10)t} = \frac{A}{soo - st}$

September 12, 2018 2 / 46

Note C is only valid until V=0
Soo-St=0 => t=100

$$\frac{dA}{dt} = 10 - (0 \quad \frac{A}{s_{00}-st} = 10 - \frac{10}{s_{00}-st} A$$

$$\frac{dA}{dt} + \frac{2}{100-t} A = 10 \quad \text{with } A(0) = 0$$
Valid for $0 \le t \le 100$

September 12, 2018 3 / 46

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Mixing Problem w/ Non-constant Volume

A tank originally contains 500 gallons of pure water. Brine containing 2 pounds of salt per gallon is pumped in at a rate of 5 gal/min. The well mixed solution is pumped out at the rate of 10 gal/min. Set up the initial value problem governing the amount of salt *A*. Determine the time interval for which the differential equation is valid.

Solving the problem is left as an exercise. The correct solution will be

$$A(t) = 10(100 - t) - rac{(100 - t)^2}{10}$$
 valid for $0 \le t < 100$

September 12, 2018 5 / 46

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A Nonlinear Modeling Problem

A population P(t) of tilapia changes at a rate jointly proportional to the current population and the difference between the constant carrying capacity¹ M of the environment and the current population. Determine the differential equation satsified by P.

Current population P, difference between Mond P P M-P $\frac{dP}{dt} \neq P(n-P)$ $\Rightarrow \frac{dP}{dt} = k P(n-P)$ for some constant k

¹The carrying capacity is the maximum number of individuals that the environment can support due to limitation of space and resources.

Logistic Differential Equation

The equation

$$\frac{dP}{dt} = kP(M-P), \quad k, M > 0$$

is called a logistic growth equation.

Solve this equation² and show that for any $P(0) \neq 0$, $P \rightarrow M$ as $t \rightarrow \infty$.

The ODE is separable $\frac{1}{P(m-P)} \frac{dP}{dt} = k = \frac{1}{P(m-P)} dP = k dt$ $\int \frac{1}{P(m-P)} dP = \int k dt$

²The partial fraction decomposition

$$\frac{1}{P(M-P)} = \frac{1}{M} \left(\frac{1}{P} + \frac{1}{M-P} \right)$$

is useful.

September 12, 2018 7 / 46

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Using the part & traction decomp $\int \frac{1}{M} \left(\frac{1}{P} + \frac{1}{M-P} \right) dP = \int k dt$ J(+++++) dP = JKM dt JnP-Jn/M-Pl = KMt+C Using log properties $l_{m}\left|\frac{P}{M-P}\right| = kMt + C$ $\left|\frac{P}{M-P}\right| = e^{kMt+C} + C + kMt$ ◆□▶ ◆□▶ ◆ □ ▶ ◆ □ ▶ ◆ □ ●

September 12, 2018

8/46

Let
$$A = e^{c}$$
 or $-e^{c}$
 $\frac{P}{M-P} = A e^{knt}$
Let $P(o) = P_{o}$, then applying this condition
 $\frac{P_{o}}{M-P_{o}} = A e^{o} = A \Rightarrow A = \frac{P_{o}}{M-P_{o}}$ this
 $\frac{P}{M-P} = A e^{kmt} \Rightarrow P = A e^{kmt} (N-P)$
 $P = A M e^{kmt} - A P e^{kmt}$

September 12, 2018 9 / 46





$$P(t) = \frac{P_{o} M e^{kmt}}{M - P_{o} + P_{o} e^{kmt}}$$
This is the solution
to the logistic
equation subject to
$$P(o) = P_{o}$$

The long time population

$$\lim_{t \to \infty} P(t) = \lim_{t \to \infty} \frac{P_0 M e}{M - P_0 + P_0 e^{kM t}} = \frac{10}{100}$$

$$\lim_{t \to \infty} \frac{P_0 M e^{kM t}}{P_0 M e^{kM t}} = \frac{100}{100}$$

September 12, 2018 11 / 46





Section 6: Linear Equations Theory and Terminology

Recall that an *n*th order linear IVP consists of an equation

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

to solve subject to conditions

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

The problem is called **homogeneous** if $g(x) \equiv 0$. Otherwise it is called nonhomogeneous.

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13/46

Theorem: Existence & Uniqueness

Theorem: If a_0, \ldots, a_n and g are continuous on an interval I, $a_n(x) \neq 0$ for each x in I, and x_0 is any point in I, then for any choice of constants y_0, \ldots, y_{n-1} , the IVP has a unique solution y(x) on I.

Put differently, we're guaranteed to have a solution exist, and it is the only one there is!

Homogeneous Equations

We'll consider the equation

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = 0$$

and assume that each a_i is continuous and a_n is never zero on the interval of interest.

Theorem: If y_1, y_2, \ldots, y_k are all solutions of this homogeneous equation on an interval *I*, then the *linear combination*

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + \cdots + c_k y_k(x)$$

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15/46

is also a solution on I for any choice of constants c_1, \ldots, c_k .

This is called the **principle of superposition**.

Corollaries

- (i) If y_1 solves the homogeneous equation, the any constant multiple $y = cy_1$ is also a solution.
- (ii) The solution y = 0 (called the trivial solution) is always a solution to a homogeneous equation.

Big Questions:

- Does an equation have any **nontrivial** solution(s), and
- since y_1 and cy_1 aren't truly *different* solutions, what criteria will be used to call solutions distinct?

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16/46

Definition: A set of functions $f_1(x)$, $f_2(x)$, ..., $f_n(x)$ are said to be **linearly dependent** on an interval *I* if there exists a set of constants $c_1, c_2, ..., c_n$ with at least one of them being nonzero such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0$$
 for all x in I.

A set of functions that is not linearly dependent on *I* is said to be **linearly independent** on *I*.