

Section 5: First Order Equations Models and Applications

A Classic Mixing Problem A tank originally contains 500 gallons of pure water. Brine containing 2 pounds of salt per gallon is pumped in at a rate of 5gal/min. The well mixed solution is pumped out at the same rate. Find the amount of salt $A(t)$ in pounds at the time t . Find the concentration of the mixture in the tank at $t = 5$ minutes.

A Classic Mixing Problem

From considering rate of increase and rate of decrease of the amount of salt at time t , we obtained the first order linear equation

$$\frac{dA}{dt} = r_i \cdot c_i - r_o \frac{A}{V} \implies \frac{dA}{dt} + \frac{r_o}{V} A = r_i c_i,$$

where r_i is the rate of inflow of fluid, c_i is the concentration of salt in the incoming fluid, r_o is the rate of outflow of fluid, and $V(t)$ is the volume of the mixture in the tank. If the initial volume is $V(0)$, then

$$V(t) = V(0) + (r_i - r_o)t.$$

If we know the starting amount of salt $A(0)$, we can solve an IVP to find the amount of salt at all future times.

Solve the Mixing Problem

A tank originally contains 500 gallons of pure water. Brine containing 2 pounds of salt per gallon is pumped in at a rate of 5 gal/min. The well mixed solution is pumped out at the same rate. Find the amount of salt $A(t)$ in pounds at the time t . Find the concentration of the mixture in the tank at $t = 5$ minutes.

We determined

$$r_i = r_o = 5 \text{ gal/min}, \quad c_i = 2 \text{ lb/gal}, \quad \text{and} \quad A(0) = 0.$$

This gives us the IVP

$$\frac{dA}{dt} + \frac{5}{500}A = 10, \quad A(0) = 0.$$

Solve $\frac{dA}{dt} + \frac{1}{100} A = 10$, $A(0) = 0$

1st order linear in standard form: $P(t) = \frac{1}{100}$

Get the integrating factor $\mu = e^{\int P(t) dt} = e^{\int \frac{1}{100} dt} = e^{\frac{1}{100} t}$

$$\frac{d}{dt} \left[e^{\frac{1}{100} t} A \right] = 10 e^{\frac{1}{100} t}$$

$$\int \frac{d}{dt} \left[e^{\frac{1}{100} t} A \right] dt = \int 10 e^{\frac{1}{100} t} dt$$

$$e^{\frac{1}{100} t} A = 10 \left(\frac{1}{\frac{1}{100}} \right) e^{\frac{1}{100} t} + C$$

$$e^{\frac{1}{100}t} A = 1000 e^{\frac{1}{100}t} + C$$

$$A = \frac{1000 e^{\frac{1}{100}t} + C}{e^{\frac{1}{100}t}}$$

$$A(t) = 1000 + C e^{-\frac{1}{100}t}$$

using $A(0) = 0$

$$A(0) = 1000 + C e^0 = 1000 + C = 0$$

$$C = -1000$$

So the amount of salt

$$A = 1000 - 1000 e^{-\frac{1}{100}t}$$

The concentration C_n in the tank

$$C_n = \frac{A}{V}$$

At $t = 5$ min

$$C_n = \frac{A(5)}{V} = \frac{1000 - 1000 e^{-\frac{1}{100} \cdot 5}}{500} \approx 0.1 \frac{\text{lb}}{\text{gal}}$$

$$r_i \neq r_o$$

Suppose that instead, the mixture is pumped out at 10 gal/min. Determine the differential equation satisfied by $A(t)$ under this new condition.

$$\text{Here } V(t) = V(0) + (r_i - r_o)t = 500 + (5 - 10)t$$

$$C_o = \frac{A}{V} = \frac{A}{500 - 5t}$$

$$\frac{dA}{dt} + \frac{10}{500 - 5t} A = 10$$

$$\frac{dA}{dt} + \frac{2}{100 - t} A = 10$$

Valid
for $0 < t < 100$

A Nonlinear Modeling Problem

A population $P(t)$ of tilapia changes at a rate jointly proportional to the current population and the difference between the constant carrying capacity¹ M of the environment and the current population. Determine the differential equation satisfied by P .

$$\frac{dP}{dt} \propto \underset{P}{\text{Population}} \text{ and } \underset{M-P}{\text{difference between } M \text{ and Population}}$$

$$\frac{dP}{dt} = kP(M-P)$$

¹The carrying capacity is the maximum number of individuals that the environment can support due to limitation of space and resources.

Logistic Differential Equation

The equation

$$\frac{dP}{dt} = kP(M - P), \quad k, M > 0$$

is called a **logistic growth equation**.

Solve this equation² and show that for any $P(0) \neq 0$, $P \rightarrow M$ as $t \rightarrow \infty$.

Call $P(0) = P_0$

The ODE is separable

$$\frac{1}{P(M-P)} \frac{dP}{dt} = k \Rightarrow \int \frac{1}{P(M-P)} dP = \int k dt$$

²The partial fraction decomposition

$$\frac{1}{P(M-P)} = \frac{1}{M} \left(\frac{1}{P} + \frac{1}{M-P} \right)$$

is useful.

$$\int \frac{1}{M} \left(\frac{1}{P} + \frac{1}{M-P} \right) dP = \int k dt$$

mult. by
M

$$\int \left(\frac{1}{P} + \frac{1}{M-P} \right) dP = \int k M dt$$

$$\ln|P| - \ln|M-P| = kMt + C$$

$$\ln \left| \frac{P}{M-P} \right| = kMt + C$$

$$\left| \frac{P}{M-P} \right| = e^{kMt+C} = e^C e^{kMt}$$

Letting $A = e^c$ or $A = -e^c$ to absorb any sign

$$* \quad \frac{P}{M-P} = A e^{knt} \quad \text{using } P(0) = P_0$$

$$\frac{P_0}{M-P_0} = A e^0 \Rightarrow A = \frac{P_0}{M-P_0}$$

Solve * for P

$$P = A e^{knt} (M-P) = A M e^{knt} - P A e^{knt}$$

$$P + P A e^{knt} = A M e^{knt}$$

$$P(1 + A e^{knt}) = A M e^{knt}$$

$$P = \frac{A M e^{k M t}}{1 + A e^{k M t}}$$

Using $A = \frac{P_0}{M - P_0}$

$$P = \frac{\frac{P_0}{M - P_0} M e^{k M t}}{1 + \frac{P_0}{M - P_0} e^{k M t}} \cdot \left(\frac{M - P_0}{M - P_0} \right) \text{ Clear fractions}$$

$$P(t) = \frac{P_0 M e^{k M t}}{M - P_0 + P_0 e^{k M t}}$$

The general solution to the logistic equation
is

$$P(t) = \frac{P_0 M e^{knt}}{M - P_0 + P_0 e^{knt}}$$

Take $t \rightarrow \infty$ to determine P in the long time.

$$\lim_{t \rightarrow \infty} P(t) = \lim_{t \rightarrow \infty} \frac{P_0 M e^{knt}}{M - P_0 + P_0 e^{knt}} = \frac{\infty}{\infty}$$

Use l'Hopital's rule

$$= \lim_{t \rightarrow \infty} \frac{P_0 M k M e^{kMt}}{P_0 k M e^{kMt}}$$

$$= \lim_{t \rightarrow \infty} M = M$$

Section 6: Linear Equations Theory and Terminology

Recall that an n^{th} order linear IVP consists of an equation

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$$

to solve subject to conditions

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

The problem is called **homogeneous** if $g(x) \equiv 0$. Otherwise it is called **nonhomogeneous**.

Theorem: Existence & Uniqueness

Theorem: If a_0, \dots, a_n and g are continuous on an interval I , $a_n(x) \neq 0$ for each x in I , and x_0 is any point in I , then for any choice of constants y_0, \dots, y_{n-1} , the IVP has a unique solution $y(x)$ on I .

Put differently, we're guaranteed to have a solution exist, and it is the only one there is!

Homogeneous Equations

We'll consider the equation

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = 0$$

and assume that each a_i is continuous and a_n is never zero on the interval of interest.

Theorem: If y_1, y_2, \dots, y_k are all solutions of this homogeneous equation on an interval I , then the *linear combination*

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + \cdots + c_k y_k(x)$$

is also a solution on I for any choice of constants c_1, \dots, c_k .

This is called the **principle of superposition**.

Corollaries

- (i) If y_1 solves the homogeneous equation, then any constant multiple $y = cy_1$ is also a solution.
- (ii) The solution $y = 0$ (called the trivial solution) is always a solution to a homogeneous equation.

Big Questions:

- ▶ Does an equation have any **nontrivial** solution(s), and
- ▶ since y_1 and cy_1 aren't truly *different* solutions, what criteria will be used to call solutions distinct?

Linear Dependence

Definition: A set of functions $f_1(x), f_2(x), \dots, f_n(x)$ are said to be **linearly dependent** on an interval I if there exists a set of constants c_1, c_2, \dots, c_n with at least one of them being nonzero such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0 \quad \text{for all } x \text{ in } I.$$

A set of functions that is not linearly dependent on I is said to be **linearly independent** on I .

If all c 's must be zero to get all terms to cancel, the functions are linearly independent.

Example: A linearly Dependent Set

The functions $f_1(x) = \sin^2 x$, $f_2(x) = \cos^2 x$, and $f_3(x) = 1$ are linearly dependent on $I = (-\infty, \infty)$.

Consider $c_1 f_1(x) + c_2 f_2(x) + c_3 f_3(x) = 0$ for all x in $(-\infty, \infty)$

$$c_1 \sin^2 x + c_2 \cos^2 x + c_3 \cdot 1 = 0$$

Take $c_1 = c_2 = 1$, $c_3 = -1$ (not all zero)

$$1 \cdot \sin^2 x + 1 \cdot \cos^2 x + (-1) \cdot 1 =$$

$$\sin^2 x + \cos^2 x - 1 =$$

$$(\sin^2 x + \cos^2 x) - 1 =$$

$$1 - 1 = 0$$

Example: A linearly Independent Set

The functions $f_1(x) = \sin x$ and $f_2(x) = \cos x$ are linearly independent on $I = (-\infty, \infty)$.

Consider $c_1 f_1(x) + c_2 f_2(x) = 0$ for all x in $(-\infty, \infty)$

$$* \quad c_1 \sin x + c_2 \cos x = 0$$

If this holds for all x , it holds if $x=0$.

$$c_1 \sin 0 + c_2 \cos 0 = 0 \Rightarrow c_2 \cdot 1 = 0 \Rightarrow c_2 = 0.$$

This holds when $x = \pi/2$ giving

$$c_1 \sin \pi/2 = 0 \Rightarrow c_1 \cdot 1 = 0 \Rightarrow c_1 = 0$$

* only holds if $c_1 = c_2 = 0$.

Determine if the set is Linearly Dependent or Independent

$$I = (-\infty, \infty)$$

$$f_1(x) = x^2, \quad f_2(x) = 4x, \quad f_3(x) = x - x^2$$

$$c_1 f_1(x) + c_2 f_2(x) + c_3 f_3(x) = 0 \quad \text{for all } x$$

$$c_1 x^2 + c_2 (4x) + c_3 (x - x^2) = 0$$

$$(c_1 - c_3) x^2 + (c_3 + 4c_2) x = 0$$

Consider $c_1 = c_3 = 4$ and $c_2 = -1$ \leftarrow not all zero

$$\begin{aligned} (4-4)x^2 + (4+4(-1))x &= \\ 0 + 0 &= 0 \end{aligned}$$

They are linearly dependent!

Definition of Wronskian

Let f_1, f_2, \dots, f_n possess at least $n - 1$ continuous derivatives on an interval I . The **Wronskian** of this set of functions is the determinant

$$W(f_1, f_2, \dots, f_n)(x) = \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f_1' & f_2' & \cdots & f_n' \\ \vdots & \vdots & \vdots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}.$$

(Note that, in general, this Wronskian is a function of the independent variable x .)

Determinants

If A is a 2×2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then its determinant

$$\det(A) = ad - bc.$$

If A is a 3×3 matrix $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$, then its determinant

$$\det(A) = a_{11} \det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$$

Determine the Wronskian of the Functions

$$f_1(x) = \sin x, \quad f_2(x) = \cos x$$

2-functions \Rightarrow 2x2 matrix

$$f_1'(x) = \cos x$$

$$f_2'(x) = -\sin x$$

$$W(f_1, f_2)(x) = \begin{vmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{vmatrix}$$

$$= \sin x (-\sin x) - \cos x (\cos x)$$

$$= -\sin^2 x - \cos^2 x$$

$$= -(\sin^2 x + \cos^2 x)$$

$$= -1$$

So $W(f_1, f_2)(x) = -1$

for $f_1(x) = \sin x$, $f_2(x) = \cos x$