# September 28 Math 3260 sec. 57 Fall 2017

#### Section 4.1: Vector Spaces and Subspaces

**Definition** A *real* **vector space** is a nonempty set *V* of objects called *vectors* together with two operations called *vector addition* and *scalar multiplication* such that: For all  $\mathbf{u}, \mathbf{v}$ , and  $\mathbf{w}$  in *V*, and for any scalars *c* and *d* 

- 1. The sum  $\mathbf{u} + \mathbf{v}$  of  $\mathbf{u}$  and  $\mathbf{v}$  is in V.
- $2. \quad \mathbf{u} + \mathbf{v} = \mathbf{v} + \mathbf{u}.$

3. 
$$(\mathbf{u} + \mathbf{v}) + \mathbf{w} = \mathbf{u} + (\mathbf{v} + \mathbf{w}).$$

- 4. There exists a **zero** vector **0** in *V* such that  $\mathbf{u} + \mathbf{0} = \mathbf{u}$ .
- 5. For each vector **u** there exists a vector  $-\mathbf{u}$  such that  $\mathbf{u} + (-\mathbf{u}) = \mathbf{0}$ .
- 6. For each scalar c,  $c\mathbf{u}$  is in V.

7. 
$$c(\mathbf{u} + \mathbf{v}) = c\mathbf{u} + c\mathbf{v}$$
.

8. 
$$(c+d)\mathbf{u} = c\mathbf{u} + d\mathbf{u}$$
.

9. 
$$c(du) = d(cu) = (cd)u$$
.

#### Remarks

- V is more accurately called a *real vector space* when we assume that the relevant scalars are the real numbers.
- Property 1. is that V is closed under (a.k.a. with respect to) vector addition.
- Property 6. is that V is closed under scalar multiplication.
- A vector space has the same basic *structure* as  $\mathbb{R}^n$
- These are axioms. We assume (not "prove") that they hold for vector space V. However, they can be used to prove or disprove that a given set (with operations) is actually a vector space.

#### **Examples of Vector Spaces**

(1)  $\mathbb{P}_n$ , the set of all polynomials with real coefficients of degree at most *n* 

$$\mathbb{P}_n = \{\mathbf{p}(t) = p_0 + p_1 t + \dots + p_n t^n \mid p_0, p_1, \dots, p_n \in \mathbb{R}\}, \text{ where}$$
$$(\mathbf{p} + \mathbf{q})(t) = \mathbf{p}(t) + \mathbf{q}(t) = (p_0 + q_0) + (p_1 + q_1)t + \dots + (p_n + q_n)t^n,$$
$$(c\mathbf{p})(t) = c\mathbf{p}(t) = cp_0 + cp_1 t + \dots + cp_n t^n.$$

(2) Let *V* be the set of all differentiable, real valued functions f(x) defined for  $-\infty < x < \infty$  with the property that f(0) = 0. Vector addition and scalar multiplication in the standard way for functions—i.e.

$$(f+g)(x) = f(x) + g(x)$$
, and  $(cf)(x) = cf(x)$ .

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#### A set that is not a Vector Space

Let  $V = \left\{ \begin{bmatrix} x \\ y \end{bmatrix}, | x \le 0, y \le 0 \right\}$  with regular vector addition and scalar multiplication in  $\mathbb{R}^2$ . Note *V* is the third quadrant in the *xy*-plane.

We saw that this is not a vector space. One reason is that even if **u** is in *V*, *c***u** is not necessarily in *V*. In fact, if  $\mathbf{u} \neq \mathbf{0}$ , then *c***u** is not in *V* for any negative number *c*.



Let V be a vector space. For each **u** in V and scalar c

$$0\mathbf{u} = \mathbf{0}$$
  
 $c\mathbf{0} = \mathbf{0}$ 

-1u = -u

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**Definition:** A **subspace** of a vector space V is a subset H of V for which

- a) The zero vector is in  $H^1$
- b) *H* is closed under vector addition. (i.e.  $\mathbf{u}, \mathbf{v}$  in *H* implies  $\mathbf{u} + \mathbf{v}$  is in *H*)
- c) *H* is closed under scalar multiplication. (i.e. **u** in *H* implies *c***u** is in *H*)

Consider  $\mathbb{R}^n$  and let  $V = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p\}$  be a nonempty  $(p \ge 1)$  subset of  $\mathbb{R}^n$ . Show that *V* is a subspace.

Note 
$$\vec{O} = O\vec{v}_1 + O\vec{v}_2 + \dots + O\vec{v}_p \Rightarrow \vec{O}$$
 is in  $V$ .  
If  $\vec{u}$  and  $\vec{w}$  are in  $V$   
 $\vec{u} = c_1\vec{v}_1 + \dots + C_p\vec{v}_p$  and  $\vec{w} = d_1\vec{v}_1 + \dots + d_p\vec{v}_p$   
Then  $\vec{u} + \vec{w} = (c_1 + d_1)\vec{v}_1 + (c_2 + d_2)\vec{v}_2 + \dots + (c_p + d_p)\vec{v}_p$   
So  $\vec{u} + \vec{w}$  is in  $V$ .  
Also  $k\vec{u} = kc_1\vec{v}_1 + kc_2\vec{v}_2 + \dots + kc_p\vec{v}_p$ , for scalar  $k$   
So  $k\vec{u}$  is also  $mV$ .

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Determine which of the following is a subspace of  $\mathbb{R}^2$ .

(a) The set of all vectors of the form  $\mathbf{u} = (u_1, 0)$ .

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# Example continued

(b) The set of all vectors of the form  $\mathbf{u} = (u_1, 1)$ .

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# Definition: Linear Combination and Span

**Definition** Let V be a vector space and  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$  be a collection of vectors in V. A linear combination of the vectors is a vector **u** 

$$\mathbf{u} = c_1 \mathbf{v}_1 + c_2 \mathbf{v}_2 + \cdots + c_p \mathbf{v}_p$$

for some scalars  $c_1, c_2, \ldots, c_p$ .

**Definition** The span, Span{ $v_1, v_2, \ldots, v_p$ }, is the subet of V consisting of all linear combinations of the vectors  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ .

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#### Theorem

**Theorem:** If  $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ , for  $p \ge 1$ , are vectors in a vector space *V*, then Span{ $\mathbf{v}_1, \mathbf{v}_2, \dots, \mathbf{v}_p$ }, is a subspace of *V*.

**Remark** This is called the **subspace of** *V* **spanned by (or generated by)**  $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ . Moreover, if *H* is any subspace of *V*, a **spanning set** for *H* is any set of vectors  $\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$  such that  $H = \text{Span}\{\mathbf{v}_1, \ldots, \mathbf{v}_p\}$ .

 $M^{2\times 2}$  denotes the set of all 2 × 2 matrices with real entries. Consider the subset *H* of  $M^{2\times 2}$ 

$${\mathcal H}=\left\{\left[egin{array}{cc} {m a} & {m 0} \ {m 0} & {m b} \end{array}
ight] \mid {m a},\, {m b}\in {\mathbb R}
ight\}.$$

Show that *H* is a subspace of  $M^{2\times 2}$  by finding a spanning set. That is, show that  $H = \text{Span}\{\mathbf{v}_1, \mathbf{v}_2\}$  for some appropriate vectors.

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et 
$$\vec{u}$$
 in  $\vec{H}$  by  $\vec{u} = \begin{bmatrix} a & o \\ o & b \end{bmatrix}$ . Thun  
 $\vec{u} = \begin{bmatrix} a & o \\ o & b \end{bmatrix} = a \begin{bmatrix} 1 & o \\ o & o \end{bmatrix} + b \begin{bmatrix} o & o \\ o & 1 \end{bmatrix}$ 

$$L_{ij} = \begin{bmatrix} 1 & 0 \\ 0 & 0 \end{bmatrix} = \begin{bmatrix} 0 & 0 \\ 0 & 0 \end{bmatrix}$$

# Section 4.2: Null & Column Spaces, Linear Transformations

**Definition:** Let *A* be an  $m \times n$  matrix. The **null space** of *A*, denoted<sup>2</sup> by Nul *A*, is the set of all solutions of the homogeneous equation  $A\mathbf{x} = \mathbf{0}$ . That is

$$\operatorname{Nul} A = \{ \mathbf{x} \in \mathbb{R}^n \mid A\mathbf{x} = \mathbf{0} \}.$$

We can say that Nul *A* is the subset of  $\mathbb{R}^n$  that gets mapped to the zero vector under the linear transformation  $\mathbf{x} \mapsto A\mathbf{x}$ .

<sup>&</sup>lt;sup>2</sup>Some authors will write Null(A)—I tend to write two ells. (a) (a) (a) (a) (a) (a)

Determine Nul A where

 $A = \begin{bmatrix} 1 & 0 & 3 \\ 1 & 2 & 7 \end{bmatrix}. \quad A\vec{x} = \vec{0}$  $\begin{bmatrix} 1 & 0 & 3 & 0 \\ 1 & 2 & 7 & 0 \end{bmatrix} \xrightarrow{\operatorname{rref}} \begin{bmatrix} 1 & 0 & 3 & 0 \\ 0 & 1 & 2 & 0 \end{bmatrix} \xrightarrow{X_{2}} \begin{bmatrix} X_{1} \\ X_{2} \\ X_{3} \end{bmatrix}$  $x_1 = -3x_7$  $x_{1} = -2x_{3}$  $\chi = \begin{bmatrix} .3x_3 \\ .2x_3 \\ .2x_3 \end{bmatrix} = \chi_3 \begin{bmatrix} .3 \\ .2x_3 \\ .2x_3 \end{bmatrix}$ x3-fre NULA = Span  $\left\{ \begin{bmatrix} -3\\ -2\\ 1 \end{bmatrix} \right\}$ .

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#### Theorem

For  $m \times n$  matrix A, Nul A is a subspace of  $\mathbb{R}^n$ .

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For a given matrix, a spanning set for NulA gives an *explicit* description of this subspace. Find a spanning set for Nul A where

$$A = \begin{bmatrix} 1 & 0 & 2 & -1 \\ 1 & 2 & 6 & -5 \end{bmatrix}.$$

$$\begin{array}{c} x_{1} = \cdot 2x_{3} + X_{4} \\ x_{1} = \cdot 2x_{3} + X_{4} \\ x_{2} = \cdot 2x_{3} + 2x_{4} \\ x_{3} + X_{4} \\ x_{3} \\ x_{4} \end{bmatrix} = \begin{array}{c} x_{3} \begin{bmatrix} -2 \\ -2 \\ 1 \\ 0 \end{bmatrix} + X_{4} \begin{bmatrix} 1 \\ 2 \\ 0 \\ 1 \end{bmatrix}$$

$$\begin{array}{c} x_{1} = \cdot 2x_{3} + X_{4} \\ x_{2} = \cdot 2x_{3} + 2x_{4} \\ x_{3} + 2x_{4} \\ x_{3} \\ x_{4} - free \end{array}$$

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$$N \downarrow A = Spon \left\{ \begin{array}{c} \cdot z \\ \cdot z \\ 1 \\ 0 \\ \end{array} \right\}, \left\{ \begin{array}{c} 1 \\ 2 \\ 0 \\ 1 \\ \end{array} \right\}$$