Exam I Math 3260 sec. 58

Fall 2017

Name: _____

Solut.ons

Your signature (required) confirms that you agree to practice academic honesty.

Signature: _____

Problem	Points
1	
2	
3	
4	
5	
6	
7	
8	

INSTRUCTIONS: There are 8 problems; the point values are listed with the problems. You may use a calculator with matrix capabilities. No wifi enabled device can be used as a calculator. There are no notes, or books allowed. Illicit use of a smart phone, tablet, device that runs apps, or hand written notes will result in a grade of zero on this exam as well as a formal allegation of academic misconduct. To receive full credit, you must clearly justify your answer.

(1) (15 points) Solve the linear system by using row reduction on the associated augmented matrix. Show each step in the row reduction process—i.e. do this one by hand and show all of your work. Give your answer in parametric or vector parametric form, your choice.

In vector paradoic for
$$\vec{X} = \begin{bmatrix} 2 \\ -1 \\ 1 \end{bmatrix}$$

(2) (15 points) The matrices A and B shown below are row equivalent. Use this to find the solution set of the given system of equations.

$$A = \begin{bmatrix} -2 & 2 & -3 & -2 & -8 \\ 3 & -3 & 3 & 1 & 10 \\ 2 & -2 & 2 & 0 & 4 \end{bmatrix} \qquad B = \begin{bmatrix} 1 & -1 & 0 & 0 & 6 \\ 0 & 0 & 1 & 0 & -4 \\ 0 & 0 & 0 & 1 & 4 \end{bmatrix}$$

$$-2x_1 + 2x_2 - 3x_3 - 2x_4 = -8$$

$$3x_1 - 3x_2 + 3x_3 + x_4 = 10$$

$$2x_1 - 2x_2 + 2x_3 = 4$$

$$x_1 = 6 + x_2$$

$$x_2 - fre$$

$$x_3 = -4$$

$$x_1 = 4$$

$$x_2 - fre$$

$$x_3 = -4$$

$$x_1 = 4$$

$$x_2 - fre$$

$$x_3 = -4$$

$$x_1 = 4$$

(3) (15 points) Find the standard matrix for the linear transformation $T : \mathbb{R}^4 \longrightarrow \mathbb{R}^3$ defined by

$$T(x_1, x_2, x_3, x_4) = (x_4, -x_3, x_1)$$

(4) (5 points) Suppose the homogeneous equation $A\mathbf{x} = \mathbf{0}$ has the two nontrivial solutions \mathbf{u} and \mathbf{v} . Show that every vector in Span $\{\mathbf{u}, \mathbf{v}\}$ also solves the homogeneous equation.

Suppose
$$\frac{1}{2}$$
 is in Space $\frac{1}{2}$, $\frac{1}{2}$. Then $\frac{1}{2} = c, \frac{1}{2} + c_2 \frac{1}{2}$
for some scalenes C_1 and c_2 . Using prepenties
of Matrix multiplication
 $A\frac{1}{2} = A(c, \frac{1}{2} + c_2 \frac{1}{2})$
 $= c, A\frac{1}{2} + c_2 A\frac{1}{2}$
 $= c, O + c_2 O = O$
Hence $\frac{1}{2}$ solver the homoseneous equation.

(5) (5 points) Suppose that the vector \mathbf{u}_1 solves the nonhomogeneous equation $A\mathbf{x} = \mathbf{b}_1$ and that the vector \mathbf{u}_2 solves the nonhomogeneous equation $A\mathbf{x} = \mathbf{b}_2$. Show that the vector $\mathbf{u}_1 + \mathbf{u}_2$ solves the nonhomogeneous equation $A\mathbf{x} = \mathbf{b}_1 + \mathbf{b}_2$.

(6) (15 points) Consider the set of vectors $\{v_1, v_2, v_3\}$.

$$\mathbf{v}_1 = \begin{bmatrix} 1\\2\\0 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -2\\-4\\0 \end{bmatrix}, \quad \mathbf{v}_3 = \begin{bmatrix} 1\\1\\1 \end{bmatrix}$$

(a) Is the set $\{\mathbf{v}_1,\mathbf{v}_2\}$ linearly dependent or linearly independent? (Justify)

They are
$$lin_{i}$$
 dependent, $N \cdot t_{i} = -2\overline{v}_{i}$.
So $2\overline{v}_{i} + \overline{v}_{2} = \overline{O}$.

(b) Is the vector $\mathbf{b} = (0, 0, 1)$ in Span $\{\mathbf{v}_1, \mathbf{v}_2\}$? (Justify)

No. If
$$\vec{b} = (c, 0, 1)$$
 in optimity, $v_2 j : (substrip)$
No. If $\vec{b} = (c, \vec{v}_1 + (c_2\vec{v}_2 + then \begin{bmatrix} 0\\ 0\\ 1 \end{bmatrix}) = \begin{bmatrix} 0\\ c_1 0 + c_2 0 \end{bmatrix}$
which is false

(c) Is the set $\{v_1, v_2, v_3\}$ linearly dependent or linearly independent? (Justify)

(7) (20 points) Use the given matrices to evaluate each expression. If an expression does not exist, state why it does not exist.

$$A = \begin{bmatrix} 2 & 1 \\ 2 & 2 \end{bmatrix}, \quad B = \begin{bmatrix} -1 & 1 \\ 0 & 2 \\ 3 & -4 \end{bmatrix}, \quad C = \begin{bmatrix} 0 & 1 & -1 \\ -1 & 2 & 3 \end{bmatrix}$$

(a) 3C
$$= \begin{bmatrix} 0 & 3 & -3 \\ -3 & 6 & 9 \end{bmatrix}$$

(b) AC
$$= \begin{bmatrix} 2 & 1 \\ 2 & 2 \end{bmatrix} \begin{bmatrix} 0 & 1 & -1 \\ -3 & 6 & 9 \end{bmatrix} = \begin{bmatrix} -1 & 9 & 1 \\ -2 & 6 & 9 \end{bmatrix}$$

(d) Ax where
$$x = \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix}$$
 Under At require \vec{x} in \mathbb{R}^2

(e)
$$C^{T} + B = \begin{bmatrix} 0 & -1 \\ 1 & 2 \\ -1 & 3 \end{bmatrix} + \begin{bmatrix} -1 & 1 \\ 0 & 2 \\ 3 & -4 \end{bmatrix} = \begin{bmatrix} -1 & 0 \\ 1 & 4 \\ 2 & -1 \end{bmatrix}$$

(8) (10 points) The homogeneous equation $A\mathbf{x} = \mathbf{0}$ is always consistent because it always has the trivial solution. Let

$$A = \begin{bmatrix} 1 & b \\ c & d \end{bmatrix}, \text{ for some real numbers } b, c, \text{ and } d.$$

Determine whether the homogeneous equation $A\mathbf{x} = \mathbf{0}$ has one solution or infinitely many solutions

(a) If
$$d = bc - 1$$
.

$$\begin{bmatrix} 1 & b & 0 \\ c & d & 0 \end{bmatrix} - cR_{1} + R_{2} \Rightarrow R_{2}$$

$$\begin{bmatrix} 1 & b & 0 \\ 0 & d - cb & 0 \end{bmatrix}$$

$$\begin{bmatrix} 1 & b & 0 \\ 0 & d - cb & 0 \end{bmatrix} \Rightarrow \quad X_{1}z = X_{2}z = 0$$

$$\begin{bmatrix} 1 & b & 0 \\ 0 & d - cb & 0 \end{bmatrix} \Rightarrow \quad X_{1}z = X_{2}z = 0$$

$$\begin{bmatrix} 1 & b & 0 \\ 0 & d - cb & 0 \end{bmatrix} \Rightarrow \quad X_{1}z = X_{2}z = 0$$

$$\begin{bmatrix} 1 & b & 0 \\ 0 & d - cb & 0 \end{bmatrix} \Rightarrow \quad X_{1}z = X_{2}z = 0$$

$$\begin{bmatrix} 0 & 0 \\ 0 & -1 & 0 \end{bmatrix} \Rightarrow \quad X_{1}z = X_{2}z = 0$$

(b) If
$$d = bc$$
. In this case, the above is
 $\begin{bmatrix} 1 & 5 & 0 \\ 0 & 0 & 0 \end{bmatrix}$
The system would have infinitely mong
Solutions.