

Exam 3 Math 3260 sec. 57

Fall 2017

Name: Solutions

Your signature (required) confirms that you agree to practice academic honesty.

Signature: _____

Problem	Points
1	
2	
3	
4	
5	
6	

INSTRUCTIONS: There are 6 problems; the point values are listed with the problems. You may use a calculator with matrix capabilities. **No wifi enabled device can be used as a calculator.** There are no notes, or books allowed. **Illicit use of a smart phone, tablet, device that runs apps, or hand written notes will result in a grade of zero on this exam as well as a formal allegation of academic misconduct.** To receive full credit, you must clearly justify your answer.

(1) (15 points) Use Gram Schmidt to find an **orthogonal** basis for $\text{Col}(A)$ where $A = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 1 & -2 \\ 1 & -1 & 1 \end{bmatrix}$.

(Answers without supporting work will not be considered.)

$\vec{u}_1 \quad \vec{u}_2 \quad \vec{u}_3$

$$\vec{v}_1 = \vec{u}_1 = \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}$$

$$\vec{v}_2 = \vec{u}_2 - \frac{\vec{u}_2 \cdot \vec{v}_1}{\|\vec{v}_1\|^2} \vec{v}_1 \quad \vec{u}_2 \cdot \vec{v}_1 = 1 - 1 = 0$$

$$\|\vec{v}_1\|^2 = 1 + 1 = 2$$

$$= \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix} - 0 = \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}$$

$$\vec{v}_3 = \vec{u}_3 - \frac{\vec{u}_3 \cdot \vec{v}_1}{\|\vec{v}_1\|^2} \vec{v}_1 - \frac{\vec{u}_3 \cdot \vec{v}_2}{\|\vec{v}_2\|^2} \vec{v}_2$$

$$\vec{u}_3 \cdot \vec{v}_1 = 3 + 1 = 4$$

$$\vec{u}_3 \cdot \vec{v}_2 = 3 - 2 - 1 = 0$$

$$\|\vec{v}_2\|^2 = 1 + 1 + 1 = 3$$

$$= \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix} - \frac{4}{2} \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix} - 0$$

$$= \begin{bmatrix} 3 \\ -2 \\ 1 \end{bmatrix} - \begin{bmatrix} 2 \\ 0 \\ 2 \end{bmatrix} = \begin{bmatrix} 1 \\ -2 \\ -1 \end{bmatrix}$$

an orthogonal basis is

$$\left\{ \begin{bmatrix} 1 \\ 0 \\ 1 \end{bmatrix}, \begin{bmatrix} 1 \\ 1 \\ -1 \end{bmatrix}, \begin{bmatrix} 1 \\ -2 \\ -1 \end{bmatrix} \right\}$$

(2) (20 points) Consider the vectors in \mathbb{R}^3 , $\mathbf{u} = \begin{bmatrix} 1 \\ 1 \\ -2 \end{bmatrix}$, $\mathbf{v} = \begin{bmatrix} 2 \\ 0 \\ 1 \end{bmatrix}$, and $\mathbf{w} = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix}$.

Evaluate or otherwise answer the following. (Answers without supporting work will not be considered.)

(a) Find $\|\mathbf{u}\| = \sqrt{1+1+4} = \sqrt{6}$

(b) Evaluate $\mathbf{w} \cdot (\mathbf{u} + \mathbf{v}) = \begin{bmatrix} 3 \\ -1 \\ 1 \end{bmatrix} \cdot \begin{pmatrix} \begin{bmatrix} 3 \\ 1 \\ -1 \end{bmatrix} \end{pmatrix} = 9 - 1 - 1 = 7$

(c) Are \mathbf{u} and \mathbf{v} parallel, perpendicular, or neither? $\vec{u} \cdot \vec{v} = 2 - 2 = 0$

They are perpendicular

(d) Are \mathbf{v} and \mathbf{w} orthogonal? $\vec{v} \cdot \vec{w} = 6 + 0 + 1 = 7 \neq 0$

No.

(e) Find a unit vector in the direction of \mathbf{w} . $\|\vec{w}\|^2 = 9 + 1 + 1 = 11$

$$\frac{1}{\|\vec{w}\|} \vec{w} = \begin{bmatrix} 3/\sqrt{11} \\ -1/\sqrt{11} \\ 1/\sqrt{11} \end{bmatrix}$$

(3) (20 points) Suppose A is a 5×5 matrix whose eigenvalues are found to be

$$\lambda_1 = 0, \quad \lambda_2 = 1, \quad \lambda_3 = 2, \quad \lambda_4 = 3, \quad \text{and} \quad \lambda_5 = 4.$$

Use this information to answer the following questions.

(a) If $\mathbf{x}_3 = \begin{bmatrix} 1 \\ 0 \\ 1 \\ 0 \\ 2 \end{bmatrix}$ is an eigenvector of A corresponding to $\lambda_3 = 2$, compute $A\mathbf{x}_3$.

$$A\vec{x}_3 = 2\vec{x}_3 = \begin{bmatrix} 2 \\ 0 \\ 2 \\ 0 \\ 4 \end{bmatrix}$$

(b) Evaluate $\det(A - 4I) = 0$ since 4 is an eigenvalue

(c) If $\mathbf{x}_4 = \begin{bmatrix} 0 \\ 0 \\ 2 \\ 1 \\ 1 \end{bmatrix}$ is an eigenvector corresponding to $\lambda_4 = 3$, then $\|A\mathbf{x}_4\| =$

$$\|A\vec{x}_4\| = \|3\vec{x}_4\| = 3\|\vec{x}_4\| = 3\sqrt{4+1+1} = 3\sqrt{6}$$

- (d) Jack and Diane want to solve the equation $A\mathbf{x} = \mathbf{b}$ with this matrix and some given vector \mathbf{b} . Jack says they can solve the problem by computing A^{-1} because A has 5 different eigenvalues. Diane disagrees. She says that A doesn't have an inverse. One of them is correct. Who is correct, and how do you know?

Diane is correct. $\det(A) = 0$ since $\lambda_1 = 0$.
Hence A is not invertible.

(4) (15 points) Let $A = \begin{bmatrix} 1 & 2 \\ 2 & 1 \end{bmatrix}$.

(a) Find the characteristic polynomial of A .

$$\det(A - \lambda I) = \det \left(\begin{bmatrix} 1-\lambda & 2 \\ 2 & 1-\lambda \end{bmatrix} \right) = (1-\lambda)^2 - 4 \\ = \lambda^2 - 2\lambda - 3$$

(b) Determine the eigenvalues of A . $0 = \lambda^2 - 2\lambda - 3 = (\lambda - 3)(\lambda + 1)$

$$\Rightarrow \lambda = 3 \text{ or } \lambda = -1$$

The eigenvalues are $\lambda_1 = 3$ and $\lambda_2 = -1$

(c) For each eigenvalue, find a basis vector spanning the associated eigenspace.

$$A - 3I = \begin{bmatrix} -2 & 2 \\ 2 & -2 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & -1 \\ 0 & 0 \end{bmatrix} \quad \begin{array}{l} x_1 = x_2 \\ x_2 \text{ free} \end{array} \quad \vec{x}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$$

a basis is $\left\{ \begin{bmatrix} 1 \\ 1 \end{bmatrix} \right\}$

$$A + I = \begin{bmatrix} 2 & 2 \\ 2 & 2 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 1 \\ 0 & 0 \end{bmatrix} \quad \begin{array}{l} x_1 = -x_2 \\ x_2 \text{ free} \end{array} \quad \vec{x}_2 = \begin{bmatrix} -1 \\ 1 \end{bmatrix}$$

a basis is $\left\{ \begin{bmatrix} -1 \\ 1 \end{bmatrix} \right\}$.

(5) (20 points) Let \mathbb{P}_1 , the set of all polynomials of degree at most one, be given the inner product

$$\langle \mathbf{p}, \mathbf{q} \rangle = \mathbf{p}(-1)\mathbf{q}(-1) + \mathbf{p}(1)\mathbf{q}(1).$$

For the vectors $\mathbf{p}(t) = 1 + 2t$, $\mathbf{q}(t) = 1 - t$, and $\mathbf{r}(t) = 4t$,

(a) Evaluate $\langle \mathbf{p}, \mathbf{q} \rangle$.
$$= \vec{p}(-1)\vec{q}(-1) + \vec{p}(1)\vec{q}(1)$$
$$= (1-2)(2) + (3)(0) = (-1)(2) + 0 = -2$$

(b) Find the distance between \mathbf{q} and \mathbf{r} .
$$\|\vec{q} - \vec{r}\|^2 = (1+5)^2 + (1-5)^2$$
$$= 36 + 16 = 52$$
$$\|\vec{q} - \vec{r}\| = \sqrt{52}$$

(c) Evaluate $\|\mathbf{p}\|^2$.
$$\langle \vec{p}, \vec{p} \rangle = (\vec{p}(-1))^2 + (\vec{p}(1))^2 = (-1)^2 + (3)^2 = 10$$

(d) Find a unit vector in the direction of \mathbf{p} .

$$\vec{u} = \frac{1}{\sqrt{10}} (1+2t)$$

(e) Find a vector $\mathbf{s}(t) = s_0 + s_1 t$ in \mathbb{P}_1 that is orthogonal to \mathbf{r} .
$$\vec{r}(-1) = -4, \quad \vec{r}(1) = 4$$

$$\langle \vec{s}, \vec{r} \rangle = (s_0 - s_1)(-4) + (s_0 + s_1)(4)$$
$$= -s_0 + 4s_1 + 4s_0 + 4s_1 = 3s_0 + 8s_1 = 0 \Rightarrow s_1 = 0$$

$$s(t) = s_0 \quad \text{an example would be } \vec{s}(t) = 1$$

(6) (10 points) Find the least squares¹ best fit line to the data

x	-1	0	1	2
y	2	-4	2	3

$$y = mx + b$$

$$-m + b = 2$$

$$0m + b = -4$$

$$1m + b = 2$$

$$2m + b = 3$$

$$\begin{bmatrix} -1 & 1 \\ 0 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} \begin{bmatrix} m \\ b \end{bmatrix} = \begin{bmatrix} 2 \\ -4 \\ 2 \\ 3 \end{bmatrix}$$

$A \qquad \qquad \vec{b}$

$$A^T A = \begin{bmatrix} -1 & 0 & 1 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} -1 & 1 \\ 0 & 1 \\ 1 & 1 \\ 2 & 1 \end{bmatrix} = \begin{bmatrix} 6 & 2 \\ 2 & 4 \end{bmatrix}$$

$$A^T \vec{b} = \begin{bmatrix} -1 & 0 & 1 & 2 \\ 1 & 1 & 1 & 1 \end{bmatrix} \begin{bmatrix} 2 \\ -4 \\ 2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 3 \end{bmatrix}$$

$$A^T A \vec{x} = A^T \vec{b}$$

$$\begin{bmatrix} 6 & 2 & 6 \\ 2 & 4 & 3 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 9/10 \\ 0 & 1 & 3/10 \end{bmatrix}$$

$$m = 9/10$$

$$b = 3/10$$

$$y = \frac{9}{10}x + \frac{3}{10}$$

¹Recall that the normal equations are $A^T A \vec{x} = A^T \vec{b}$.