

Section 5.3: Diagonalization

Definition:

Two $n \times n$ matrices A and B are said to be **similar** if there exists an invertible matrix P such that

$$B = P^{-1}AP.$$

The mapping $A \mapsto P^{-1}AP$ is called a **similarity transformation**.

- ▶ If A and B are similar, they have the same characteristic equation and hence the same eigenvalues.
- ▶ If $B = P^{-1}AP$ for $n \times n$ matrices A , B , and P , then $B^k = P^{-1}A^kP$ for each integer $k \geq 1$.

Diagonalizability

Defintion:

An $n \times n$ matrix A is called **diagonalizable** if it is similar to a diagonal matrix D . That is, provided there exists a nonsingular matrix P such that $D = P^{-1}AP$ —i.e. $A = PDP^{-1}$.

Theorem:

The $n \times n$ matrix A is diagonalizable if and only if A has n linearly independent eigenvectors. In this case, the matrix P is the matrix whose columns are the n linearly independent eigenvectors of A .

Example

Diagonalize the matrix A if possible. $A = \begin{bmatrix} 1 & 3 & 3 \\ -3 & -5 & -3 \\ 3 & 3 & 1 \end{bmatrix}$

We found that the characteristic polynomial for A was $(1 - \lambda)(\lambda + 2)^2$ giving two distinct eigenvalues,

$$\lambda_1 = 1, \quad \text{and} \quad \lambda_2 = \lambda_3 = -2.$$

We found three linearly independent eigenvectors

$$\mathbf{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}, \quad \mathbf{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \quad \text{and} \quad \mathbf{v}_3 = \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

Then $D = P^{-1}AP$ where

$$D = \begin{bmatrix} 1 & 0 & 0 \\ 0 & -2 & 0 \\ 0 & 0 & -2 \end{bmatrix} \quad \text{and} \quad P = \begin{bmatrix} 1 & -1 & -1 \\ -1 & 1 & 0 \\ 1 & 0 & 1 \end{bmatrix}.$$

Example

Diagonalize the matrix A if possible. $A = \begin{bmatrix} 2 & 4 & 3 \\ -4 & -6 & -3 \\ 3 & 3 & 1 \end{bmatrix}$. (With a

little effort, it can be shown that the characteristic polynomial of A is $(1 - \lambda)(2 + \lambda)^2$.)

From the characteristic poly, the eigen values are $\lambda_1 = 1$ and $\lambda_2 = \lambda_3 = -2$.

Solve $(A - 1I)\vec{x} = \vec{0}$

$$A - 1I = \begin{bmatrix} 1 & 4 & 3 \\ -4 & -7 & -3 \\ 3 & 3 & 0 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & -1 \\ 0 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} x_1 = x_3 \\ x_2 = -x_3 \\ x_3 \text{-free} \end{array}$$

$$\vec{x} = x_2 \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}. \quad \text{Let } \vec{v}_1 = \begin{bmatrix} 1 \\ -1 \\ 1 \end{bmatrix}.$$

$$\text{Solve } (A - (-2)I) \vec{x} = \vec{0}$$

$$A + 2I = \begin{bmatrix} 4 & 4 & 3 \\ -4 & -4 & -3 \\ 3 & 3 & 3 \end{bmatrix} \xrightarrow{\text{ref}} \begin{bmatrix} 1 & 1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix} \begin{array}{l} x_1 = -x_2 \\ x_2 \text{-free} \\ x_3 = 0 \end{array}$$

$$\vec{x} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}. \quad \text{Let } \vec{v}_2 = \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}.$$

There are only two linearly independent
eigenvectors. A is not diagonalizable.

Sufficient Condition for Diagonalizability

Recall: Eigenvectors corresponding to different eigenvalues are linearly independent.

Theorem:

If the $n \times n$ matrix A has n distinct eigenvalues, then A is diagonalizable.

Remark

This is a *sufficiency* condition, not a *necessity* condition. This means that if a matrix has n different eigenvalues, it's guaranteed to be diagonalizable. If it has repeated eigenvalues, it may or may not be diagonalizable.

More on Diagonalizability

Theorem:

Let A be an $n \times n$ matrix with distinct eigenvalues $\lambda_1, \dots, \lambda_p$.

- (a) The geometric multiplicity of λ_k is less than or equal to the algebraic multiplicity of λ_k .
- (b) The matrix is diagonalizable if and only if the sum of the geometric multiplicities is n .
- (c) If A is diagonalizable, and \mathcal{B}_k is a basis for the eigenspace for λ_k , then the collection (union) of bases $\mathcal{B}_1, \dots, \mathcal{B}_p$ is a basis for \mathbb{R}^n .

Remark: The union of the bases referred to in part (c) is called an **eigenvector basis** of \mathbb{R}^n for the matrix A . This is what was called an **eigenbasis** in the 3Blue 1Brown video.

Example

Diagonalize the matrix if possible. $A = \begin{bmatrix} 8 & -6 \\ 9 & -7 \end{bmatrix}$.

Characteristic polynomial: $\lambda^2 - \lambda - 2 = (\lambda - 2)(\lambda + 1)$

$$\lambda_1 = 2 \quad \lambda_2 = -1.$$

For $\lambda_1 = 2$, eigenvectors are $\vec{x} = x_2 \begin{bmatrix} 1 \\ 1 \end{bmatrix}$

let $\vec{v}_1 = \begin{bmatrix} 1 \\ 1 \end{bmatrix}$.

For $\lambda_2 = -1$, $\vec{x} = x_2 \begin{bmatrix} 2/3 \\ 1 \end{bmatrix}$. We can

Choose $\vec{v}_2 = \begin{bmatrix} 2 \\ 3 \end{bmatrix}$ letting $x_2 = 3$.

A is diagonalizable.

$$\text{Set } P = [\vec{v}_1 \ \vec{v}_2] = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \quad \det(P) = 3 - 2 = 1$$

$$P^{-1} = \frac{1}{1} \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} = \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix}$$

$$\begin{aligned} D &= P^{-1} A P = \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix} \begin{bmatrix} 8 & -6 \\ 9 & -7 \end{bmatrix} \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \\ &= \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix} \end{aligned}$$

Example Continued...

Find A^6 where $A = \begin{bmatrix} 8 & -6 \\ 9 & -7 \end{bmatrix}$.

$$\text{Since } D = P^{-1}AP \Rightarrow A = PDP^{-1}$$

$$\text{and } A^6 = PD^6P^{-1}$$

$$D = \begin{bmatrix} 2 & 0 \\ 0 & -1 \end{bmatrix}, \quad D^6 = \begin{bmatrix} 2^6 & 0 \\ 0 & (-1)^6 \end{bmatrix} = \begin{bmatrix} 64 & 0 \\ 0 & 1 \end{bmatrix}$$

$$A^6 = \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 64 & 0 \\ 0 & 1 \end{bmatrix} \begin{bmatrix} 3 & -2 \\ -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 1 & 2 \\ 1 & 3 \end{bmatrix} \begin{bmatrix} 192 & -128 \\ -1 & 1 \end{bmatrix}$$

$$= \begin{bmatrix} 190 & -126 \\ 189 & -125 \end{bmatrix}$$

$$\underbrace{\begin{bmatrix} 8 & -6 \\ 9 & -7 \end{bmatrix} \begin{bmatrix} 8 & -6 \\ 9 & -7 \end{bmatrix} \cdots \begin{bmatrix} 8 & -6 \\ 9 & -7 \end{bmatrix}}_6$$