April 1 Math 3260 sec. 51 Spring 2024

Section 4.5: Dimension of a Vector Space

Theorem:

If a vector space *V* has a basis $\mathcal{B} = \{\mathbf{b}_1, \dots, \mathbf{b}_n\}$, then any set of vectors in *V* containing *more than n vectors* is linearly dependent.

This extends our result in \mathbb{R}^n that said that a set with more vectors than entries in each vector had to be linearly dependent.

For example,

$$\left\{ \begin{bmatrix} 1\\2\\3 \end{bmatrix}, \begin{bmatrix} 2\\10\\0 \end{bmatrix}, \begin{bmatrix} -1\\0\\4 \end{bmatrix}, \begin{bmatrix} 3\\6\\8 \end{bmatrix} \right\}$$

is linearly dependent because there are 4 vectors from $\mathbb{R}^3_{\mathbb{R}}$.

Example

Recall that a basis for \mathbb{P}_3 is $\{1, t, t^2, t^3\}$.

Is the set below linearly dependent or linearly independent?

$$\{1+t, 2t-3t^3, 1+t+t^2, 1+t+t^2+t^3, 2-t+2t^3\}$$

A basis has 4 vectors. This
set has 5 vectors. Since 579
the set is lin. dependent.

All Bases are the same Size

Our theorem gives the immediate corollary:

Corollary:

If vector space *V* has a basis $\mathcal{B} = {\mathbf{b}_1, ..., \mathbf{b}_n}$, then every basis of *V* consist of exactly *n* vectors.

Remark: This makes sense. If one basis had more vectors than another basis, it couldn't be linearly independent.

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Dimension Consider a vector space *V*.

Definition:

If V is spanned by a finite set, then V is called **finite dimensional**. In this case, the dimension of V

dim V = the number of vectors in any basis of V.

The dimension of the vector space $\{\mathbf{0}\}$ containing only the zero vector is defined to be zero—i.e.

 $\dim\{\mathbf{0}\}=\mathbf{0}.$

If V is not spanned by a finite set^a, then V is said to be **infinite** dimensional.

 ${}^{a}C^{0}(\mathbb{R})$ is an example of an infinite dimensional vector space.

Examples

(a) Determine dim (\mathbb{R}^n) . = \checkmark

(b) Determine dim Col(A) where $A = \begin{bmatrix} 1 & 1 & 3 \\ 0 & 0 & -1 \end{bmatrix}$.

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Some Geometry in \mathbb{R}^3

We can describe all of the subspaces of \mathbb{R}^3 geometrically. The subspace(s) of dimension

- (a) zero: is just the origin (one point), (0, 0, 0).
- (b) one: are lines through the origin. Span{u} where u is not the zero vector.
- (c) two: are planes that contain the origin and two other, noncolinear points. Span{u, v} with {u, v} linearly independent.
- (d) three: is all of \mathbb{R}^3 .

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Subspaces and Dimension

Theorem:

Let H be a subspace of a finite dimensional vector space V. Then H is finite dimensional and

 $\dim H \leq \dim V.$

Moreover, any linearly independent subset of H can be expanded if needed to form a basis for H.

Remark: We said before that we can take a spanning set and remove extra vectors to get a basis. This follow up statement says if we start with a linearly independent set, we can add to it as needed to get a basis.

Subspaces and Dimension

Theorem:

Let *V* be a vector space with dim V = p where $p \ge 1$. Any linearly independent set in *V* containing exactly *p* vectors is a basis for *V*. Similarly, any spanning set consisting of exactly *p* vectors in *V* is necessarily a basis for *V*.

Remark: this connects two properties **spanning** and **linear independence**. If dim V = p and a set contains p vectors then

- ► linear independence ⇒ spanning
- spanning \implies linear independence

Again, this is **IF** the number of vectors matches the dimension of the vector space.

Column and Null Spaces

Theorem:

Let *A* be an $m \times n$ matrix. Then

dim Nul A = the number of free variables in the equation $A\mathbf{x} = \mathbf{0}$,

and

dim Col A = the number of pivot positions in A.

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Example

A matrix *A* is show along with its rref. Find the dimensions of the null space and column space of *A*.

$$A = \begin{bmatrix} 1 & 1 & 1 & 0 \\ -3 & 1 & -7 & -1 \\ 3 & 0 & 6 & 1 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 2 & 0 \\ 0 & 1 & -1 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

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Example

A matrix A along with its rref is shown.

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & -2 & 0 & 3 \\ 0 & 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(a) Find a basis for Row A and state dim Row A. Using the nonzero rows of the met, a basis for Row(A) is $\begin{cases} \begin{pmatrix} 0 \\ -2 \\ 0 \\ 1 \end{pmatrix}, \begin{pmatrix} 0 \\ -2 \\ 0 \\ 3 \end{pmatrix}, \begin{pmatrix} 0 \\ 0 \\ -2 \\ 0 \\ 1 \\ 5 \end{pmatrix} \end{cases}$ dim(Rovi(A)) = 3

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Example continued ...

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & -2 & 0 & 3 \\ 0 & 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(b) Find a basis for Col A and state dim Col A.

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Example continued ...

$$A = \begin{bmatrix} -2 & -5 & 8 & 0 & -17 \\ 1 & 3 & -5 & 1 & 5 \\ 3 & 11 & -19 & 7 & 1 \\ 1 & 7 & -13 & 5 & -3 \end{bmatrix} \sim \begin{bmatrix} 1 & 0 & 1 & 0 & 1 \\ 0 & 1 & -2 & 0 & 3 \\ 0 & 0 & 0 & 1 & -5 \\ 0 & 0 & 0 & 0 & 0 \end{bmatrix}$$

(c) Find a basis for Nul A and state dim Nul A.

From the rref,
$$A\dot{x} = \vec{0}$$

 $X_1 = -X_3 - X_5$
 $X_2 = 2X_3 - 3X_5$
 $\chi_3 - \hbar u$
 $X_4 = 5X_5$
 $\chi_5 - \hbar u$
 $X_5 - \hbar u$

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A basis for Nul (A) is



dim (Nul (AI) = 2

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Remarks

- Row operations preserve row space, but change linear dependence relations of rows.
- Row operations change column space, but preserve linear dependence relations of columns.
- Another way to obtain a basis for Row A is to take the transpose A^T and do row operations. We have the following relationships:

Row
$$A = \text{Col } A^T$$
 and $\text{Col } A = \text{Row } A^T$

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Rank & Nullity

Definition:

The **rank** of a matrix A, denoted rank(A), is the dimension of the column space of A.

Definition:

The **nullity** of a matrix *A* is the dimension of the null space.

Remark: Since the dimension of the column space is the number of pivot positions, the dimensions of the column and row spaces are the same. That is,

 $rank(A) = \dim Col(A) = \dim Row(A).$

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The Rank-Nullity Theorem

Theorem:

For $m \times n$ matrix A, dim Col(A) = dim Row(A) = rank(A). Moreover

 $\operatorname{rank} A + \operatorname{dim} \operatorname{Nul} A = n.$

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The Rank-Nullity Theorem

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 $\operatorname{rank} A + \operatorname{dim} \operatorname{Nul} A = n.$

Note: This theorem states the rather obvious fact that

 $\left\{\begin{array}{c} number of \\ pivot columns \end{array}\right\} + \left\{\begin{array}{c} number of \\ non-pivot columns \end{array}\right\} = \left\{\begin{array}{c} total number \\ of columns \end{array}\right\}.$

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Examples ronk + nullity = n.

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(1) *A* is a 5×4 matrix and rank(*A*) = 4. What is dim Nul *A*?

Here,
$$n=4$$
, and the rank is 4.
 $4 + nullity = 4 \implies nullity = 0$,
 $dim(Nul(A)) = 0$.
This means that Nucl(A) = $\{\vec{0}\}$.

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Examples reak + nullity = n

(2) Suppose A is 7×5 and dim Col A = 2. Determine

1. the nullity of A n=5, conce (A) = dim l Col(A) = 2

2. the rank of A^T rank $(A^T) = \dim(\operatorname{Gl} A^T) = \dim(\operatorname{Row} A)$ rank $(A^T) = 2$ = $\dim(\operatorname{Gl} A) = 2$

3. the nullity of A^T A^T is 5×7 so A^T hes n = 7.

2+ nullity = 7 => nullity = 5.

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Addendum to Invertible Matrix Theorem

Theorem:

Let *A* be an $n \times n$ matrix. The following are equivalent to the statement that *A* is invertible.

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(m) The columns of A form a basis for \mathbb{R}^n

(n) Col
$$A = \mathbb{R}^n$$

(o) dim Col
$$A = n$$

(p) rank
$$A = n$$

(q) Nul
$$A = \{0\}$$

(r) dim Nul A = 0