February 13 Math 2306 sec. 51 Spring 2023

Section 6: Linear Equations Theory and Terminology

Consider the second order, linear ODE

$$x^2y''-xy'+y=1.$$

It is easy to show that y = x + 1 is a solution.

$$y' = 1$$
, $y'' = 0$
 $x^2y'' - xy' + y = x^2(0) - x(1) + (x+1) = 1$
 $-x + x + 1 = 1$

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$$x^2y''-xy'+y=1$$

Here are 10 more solutions to this ODE!

$$y = 1$$
 $y = x \ln x + 1$
 $y = 3x - x \ln x + 1$ $y = 7x \ln x + 8x + 1$
 $y = 1 - 4x \ln \sqrt{x}$ $y = 5x \ln \left(\frac{1}{x}\right) + 1 - x$
 $y = 16x + x \ln x + 1$ $y = 1 - x \ln x^3$
 $y = 16x \ln x^2 + \frac{2}{7}x + 1$ $y = \frac{x}{3} + x \ln x^7 + 1$

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An IVP

Consider the IVP

$$x^2y'' - xy' + y = 1$$
, $y(1) = 1$, $y'(1) = -1$

Not one of the eleven solutions that I showed solve this IVP!

This raises some questions.

- What do mean when we talk about solving an ODE or an IVP?
- How do we know when we're done solving an ODE?
- Is there something we would call THE solution?



Section 6: Linear Equations Theory and Terminology

Recall that an *n*th order linear IVP consists of an equation

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \cdots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$

to solve subject to conditions

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

The problem is called **homogeneous** if $g(x) \equiv 0$. Otherwise it is called **nonhomogeneous**.



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Theorem: Existence & Uniqueness

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = g(x)$$
$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

Theorem: If a_0, \ldots, a_n and g are continuous on an interval I, $a_n(x) \neq 0$ for each x in I, and x_0 is any point in I, then for any choice of constants y_0, \ldots, y_{n-1} , the IVP has a unique solution y(x) on I.

Put differently, we're guaranteed to have a solution exist, and it is the only one there is!

The Principle of Superposition (homogeneous ode)

$$a_n(x)\frac{d^ny}{dx^n} + a_{n-1}(x)\frac{d^{n-1}y}{dx^{n-1}} + \dots + a_1(x)\frac{dy}{dx} + a_0(x)y = 0$$

Assume a_i are continuous and $a_n(x) \neq 0$ for all x in I.

Theorem: If $y_1, y_2, ..., y_k$ are all solutions of this homogeneous equation on an interval I, then the *linear combination*

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + \cdots + c_k y_k(x)$$

is also a solution on I for any choice of constants c_1, \ldots, c_k .

Corollaries

- (i) If y_1 solves the homogeneous equation, the any constant multiple $y = cy_1$ is also a solution.
- (ii) The solution y = 0 (called the trivial solution) is always a solution to a homogeneous equation.

Big Questions:

- Does an equation have any nontrivial solution(s), and
- \blacktriangleright since y_1 and cy_1 aren't truly different solutions, what criteria will be used to call solutions distinct?

Linear Dependence

Definition: A set of functions $f_1(x)$, $f_2(x)$, ..., $f_n(x)$ are said to be **linearly dependent** on an interval I if there exists a set of constants c_1, c_2, \ldots, c_n with at least one of them being nonzero such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0$$
 for all x in I . (1)

A set of functions that is not linearly dependent on *I* is said to be **linearly independent** on *I*.

NOTE: Taking all of the c's to be zero will **always** satisfy equation (1). The set of functions is linearly **independent** if taking all of the c's equal to zero is the **only** way to make the equation true.



Example: A linearly Independent Set

The functions $f_1(x) = \sin x$ and $f_2(x) = \cos x$ are linearly independent on $I = (-\infty, \infty)$.

$$C_1$$
 Sin \times + C_2 Cos \times = 0

We'll assume this is true, we need to Show that $C_1 = 0$ and $C_2 = r$. The equation is true

for all X, so it's true when X=0. When X=0,

the equation is C. Sin O + C2 Gos O = O

Sin 0=0, Cos 0=1

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$$C_1(0) + C_2(1) = 0 \implies C_2 = 0$$

The equation is al, true when $X = \frac{TT}{2}$.

$$C_1 \sin \frac{\pi}{2} + C_2 \cos \frac{\pi}{2} = 0$$

$$C_1 \sin \frac{\pi}{2} = 0$$
 $\sin \frac{\pi}{2} = 1$

$$C_1(1) = 0$$

$$C_1 = D$$

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Determine if the set is Linearly Dependent or Independent on $(-\infty, \infty)$

$$f_1(x) = x^2$$
, $f_2(x) = 4x$, $f_3(x) = x - x^2$

Let's consider the equation
$$c_1 f_1(x) + c_2 f_2(x) + c_3 f_3(x) = 0$$
 for all
$$c_1 x^2 + c_2 (4x) + c_3 (x-x^2) = 0$$
 The x^2 will concel if $c_1 = c_3$ The x_1 will concel if $c_2 = \frac{1}{4} c_3$

Try
$$C_3 = 1$$
. Then told $C_1 = 1$ and $C_2 = \frac{1}{4}$

$$C_1 \times^2 + C_2 (4 \times) + C_3 (X - X^2) = 0$$

$$1 \times^2 + (\frac{1}{4}) (4 \times) + 1 (X - X^2) = 0$$

$$X^2 - X + X - X^2 = 0$$

$$0 = 0$$

We found a set of numbers (c's) with at least one being nonzero that made the equation $c_1, f_1(x) + c_2, f_2(x) + c_3, f_3(x) = 0$ true.

This set of functions is linearly dependent.

Linear Dependence Relation

An equation with at least one *c* nonzero, such as

$$f_1(x) - \frac{1}{4}f_2(x) + f_3(x) = 0$$

from this last example is called a **linear dependence relation** for the functions $\{f_1, f_2, f_3\}$.

Definition of Wronskian

Definition: Let f_1, f_2, \ldots, f_n posses at least n-1 continuous derivatives on an interval I. The Wronskian of this set of functions is the determinant

$$W(f_1, f_2, \ldots, f_n)(x) = \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f'_1 & f'_2 & \cdots & f'_n \\ \vdots & \vdots & \vdots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}.$$

(Note that, in general, this Wronskian is a function of the independent variable x.)

Determinants

If
$$A$$
 is a 2 × 2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then its determinant
$$\det(A) = ad - bc.$$

If A is a 3 × 3 matrix
$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$$
, then its determinant

$$\det(A) = a_{11}\det\begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12}\det\begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13}\det\begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$$

Determine the Wronskian of the Functions

$$f_1(x) = \sin x, \quad f_2(x) = \cos x$$

$$2 \text{ functions} \implies 2 \times 2 \text{ matrix}$$

$$W(f_1, f_2)(x) = \begin{vmatrix} f_1 & f_2 \\ f_1' & f_2' \end{vmatrix}$$

$$= \begin{vmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{vmatrix}$$

$$= S_{m} \times (-S_{i} \wedge \times) - G_{s} \times (G_{s} \times)$$

$$= -S_{i} \wedge^{2} \times - G_{s}^{2} \times$$

$$= -(S_{i} \wedge^{2} \times + C_{s}^{2} \times)$$

$$= -($$

W(Sinx, Csx)(x) = -1