

Section 6: Linear Equations Theory and Terminology

Consider the second order, linear ODE

$$x^2 y'' - xy' + y = 1.$$

It is easy to show that $y = x + 1$ is a solution.

$$y' = 1, \quad y'' = 0$$

$$\begin{aligned} x^2 y'' - xy' + y &= x^2(0) - x(1) + (x+1) && \stackrel{?}{=} 1 \\ &= -x + x + 1 && \stackrel{?}{=} 1 \\ &= 1 && \end{aligned}$$

$$x^2 y'' - xy' + y = 1$$

Here are 10 more solutions to this ODE!

$$y = 1$$

$$y = x \ln x + 1$$

$$y = 3x - x \ln x + 1$$

$$y = 7x \ln x + 8x + 1$$

$$y = 1 - 4x \ln \sqrt{x}$$

$$y = 5x \ln \left(\frac{1}{x}\right) + 1 - x$$

$$y = 16x + x \ln x + 1$$

$$y = 1 - x \ln x^3$$

$$y = 16x \ln x^2 + \frac{2}{7}x + 1$$

$$y = \frac{x}{3} + x \ln x^7 + 1$$

An IVP

Consider the IVP

$$x^2 y'' - xy' + y = 1, \quad y(1) = 1, \quad y'(1) = -1$$

Not one of the eleven solutions that I showed solve this IVP!

This raises some questions.

- ▶ What do mean when we talk about **solving** an ODE or an IVP?
- ▶ How do we know when we're done **solving** an ODE?
- ▶ Is there something we would call **THE solution**?

Section 6: Linear Equations Theory and Terminology

Recall that an n^{th} order linear IVP consists of an equation

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$$

to solve subject to conditions

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

The problem is called **homogeneous** if $g(x) \equiv 0$. Otherwise it is called **nonhomogeneous**.

Theorem: Existence & Uniqueness

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$$

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

Theorem: If a_0, \dots, a_n and g are continuous on an interval I , $a_n(x) \neq 0$ for each x in I , and x_0 is any point in I , then for any choice of constants y_0, \dots, y_{n-1} , the IVP has a unique solution $y(x)$ on I .

Put differently, we're guaranteed to have a solution exist, and it is the only one there is!

The Principle of Superposition (homogeneous ode)

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = 0$$

Assume a_i are continuous and $a_n(x) \neq 0$ for all x in I .

Theorem: If y_1, y_2, \dots, y_k are all solutions of this homogeneous equation on an interval I , then the *linear combination*

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + \cdots + c_k y_k(x)$$

is also a solution on I for any choice of constants c_1, \dots, c_k .

Corollaries

- (i) If y_1 solves the homogeneous equation, then any constant multiple $y = cy_1$ is also a solution.
- (ii) The solution $y = 0$ (called the trivial solution) is always a solution to a homogeneous equation.

Big Questions:

- ▶ Does an equation have any **nontrivial** solution(s), and
- ▶ since y_1 and cy_1 aren't truly *different* solutions, what criteria will be used to call solutions distinct?

Linear Dependence

Definition: A set of functions $f_1(x), f_2(x), \dots, f_n(x)$ are said to be **linearly dependent** on an interval I if there exists a set of constants c_1, c_2, \dots, c_n with at least one of them being nonzero such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0 \quad \text{for all } x \text{ in } I. \quad (1)$$

A set of functions that is not linearly dependent on I is said to be **linearly independent** on I .

NOTE: Taking all of the c 's to be zero will **always** satisfy equation (1). The set of functions is linearly **independent** if taking all of the c 's equal to zero is the **only** way to make the equation true.

Example: A linearly Independent Set

The functions $f_1(x) = \sin x$ and $f_2(x) = \cos x$ are linearly independent on $I = (-\infty, \infty)$.

Suppose we have numbers c_1 and c_2 such that

$$c_1 f_1(x) + c_2 f_2(x) = 0 \quad \text{for all } x \text{ in } \mathbb{R}.$$

we're assuming that

$$c_1 \sin x + c_2 \cos x = 0 \quad \text{for all } x$$

is true. Let's show that $c_1 = 0$ and $c_2 = 0$.

The equation is true for all x , so it's

true if $x=0$. When $x=0$, the equation is

$$c_1 \sin 0 + c_2 \cos 0 = 0$$

$$\sin 0 = 0 \text{ and } \cos 0 = 1$$

$$c_1(0) + c_2(1) = 0 \Rightarrow c_2 = 0$$

The equation is also true when $x = \frac{\pi}{2}$. The equation when $x = \frac{\pi}{2}$ is

$$c_1 \sin\left(\frac{\pi}{2}\right) + c_2 \cos\left(\frac{\pi}{2}\right) = 0$$

$$\sin \frac{\pi}{2} = 1 \text{ and } c_2 = 0 \text{ from before}$$

$$c_1(1) = 0 \Rightarrow c_1 = 0$$

We've shown that $c_1 = 0$ and $c_2 = 0$ necessarily.

Hence f_1, f_2 are linearly
independent.

Determine if the set is Linearly Dependent or Independent on $(-\infty, \infty)$

$$f_1(x) = x^2, \quad f_2(x) = 4x, \quad f_3(x) = x - x^2$$

Suppose

$$c_1 f_1(x) + c_2 f_2(x) + c_3 f_3(x) = 0 \quad \text{for all } x$$

$$c_1 x^2 + c_2 (4x) + c_3 (x - x^2) = 0$$

The x^2 terms will cancel if $c_1 = c_3$.

The x terms will cancel if $c_2 = -\frac{1}{4}c_3$

For example, if we set $c_3 = 1$, $c_1 = 1$
and $c_2 = -\frac{1}{4}$

$$c_1 x^2 + c_2 (4x) + c_3 (x - x^2) = 0$$

$$1 x^2 + \left(-\frac{1}{4}\right)(4x) + 1 (x - x^2) \stackrel{?}{=} 0$$

$$x^2 - x + x - x^2 \stackrel{?}{=} 0$$
$$0 = 0$$

We found a set of coefficients, not all zero, that make the sum $c_1 f_1 + c_2 f_2 + c_3 f_3 = 0$. The set of functions is linearly dependent.

Linear Dependence Relation

An equation with at least one c nonzero, such as

$$f_1(x) - \frac{1}{4}f_2(x) + f_3(x) = 0$$

from this last example is called a **linear dependence relation** for the functions $\{f_1, f_2, f_3\}$.

Definition of Wronskian

Definition: Let f_1, f_2, \dots, f_n possess at least $n - 1$ continuous derivatives on an interval I . The **Wronskian** of this set of functions is the determinant

$$W(f_1, f_2, \dots, f_n)(x) = \begin{vmatrix} f_1 & f_2 & \cdots & f_n \\ f_1' & f_2' & \cdots & f_n' \\ \vdots & \vdots & \vdots & \vdots \\ f_1^{(n-1)} & f_2^{(n-1)} & \cdots & f_n^{(n-1)} \end{vmatrix}.$$

(Note that, in general, this Wronskian is a function of the independent variable x .)

Determinants

If A is a 2×2 matrix $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$, then its determinant

$$\det(A) = ad - bc.$$

If A is a 3×3 matrix $A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}$, then its determinant

$$\det(A) = a_{11} \det \begin{bmatrix} a_{22} & a_{23} \\ a_{32} & a_{33} \end{bmatrix} - a_{12} \det \begin{bmatrix} a_{21} & a_{23} \\ a_{31} & a_{33} \end{bmatrix} + a_{13} \det \begin{bmatrix} a_{21} & a_{22} \\ a_{31} & a_{32} \end{bmatrix}$$

Determine the Wronskian of the Functions

$$f_1(x) = \sin x, \quad f_2(x) = \cos x$$

2 functions \Rightarrow 2×2 matrix

$$W(f_1, f_2)(x) = \begin{vmatrix} f_1 & f_2 \\ f_1' & f_2' \end{vmatrix}$$

$$= \begin{vmatrix} \sin x & \cos x \\ \cos x & -\sin x \end{vmatrix}$$

$$= \sin x (-\sin x) - \cos x (\cos x)$$

$$= -\sin^2 x - \cos^2 x$$

$$= -(\sin^2 x + \cos^2 x)$$

$$= -1$$

$$W(f_1, f_2)(x) = -1$$