

Section 2.2: Inverse of a Matrix

Question: Given an $n \times n$ matrix A , is there a matrix A^{-1} that satisfies the condition

$$A^{-1}A = AA^{-1} = I_n.$$

If such matrix A^{-1} exists, we'll say that A is **nonsingular** (a.k.a. *invertible*). Otherwise, we'll say that A is **singular**.

Theorem

An $n \times n$ matrix A is invertible if and only if it is row equivalent to the identity matrix I_n . Moreover, if

$$\text{rref}(A) = E_k \cdots E_2 E_1 A = I_n, \quad \text{then} \quad A = (E_k \cdots E_2 E_1)^{-1} I_n.$$

That is,

$$A^{-1} = \left[(E_k \cdots E_2 E_1)^{-1} \right]^{-1} = E_k \cdots E_2 E_1.$$

The sequence of operations that reduces A to I_n , transforms I_n into A^{-1} .

This last observation—operations that take A to I_n also take I_n to A^{-1} —gives us a method for computing an inverse!

Algorithm for finding A^{-1}

To find the inverse of a given matrix A :

- ▶ Form the $n \times 2n$ augmented matrix $[A \quad I]$.
- ▶ Perform whatever row operations are needed to get the first n columns (the A part) to rref.
- ▶ If $\text{rref}(A)$ is I , then $[A \quad I]$ is row equivalent to $[I \quad A^{-1}]$, and the inverse A^{-1} will be the last n columns of the reduced matrix.
- ▶ If $\text{rref}(A)$ is NOT I , then A is not invertible.

Remarks: We don't need to know ahead of time if A is invertible to use this algorithm.

If A is singular, we can stop as soon as it's clear that $\text{rref}(A) \neq I$.

Examples: Find the Inverse if Possible

$$(b) \begin{bmatrix} 1 & 2 & -1 \\ -4 & -7 & 3 \\ -2 & -6 & 4 \end{bmatrix} = A$$

set up $[A \ I]$

$$\begin{bmatrix} 1 & 2 & -1 & 1 & 0 & 0 \\ -4 & -7 & 3 & 0 & 1 & 0 \\ -2 & -6 & 4 & 0 & 0 & 1 \end{bmatrix}$$

$$4R_1 + R_2 \rightarrow R_2$$

$$2R_1 + R_3 \rightarrow R_3$$

$$\begin{array}{cccccc} 4 & 8 & -4 & 4 & 0 & 0 \\ -4 & -7 & 3 & 0 & 1 & 0 \end{array}$$

$$\begin{array}{cccccc} 2 & 4 & -2 & 2 & 0 & 0 \\ -2 & -6 & 4 & 0 & 0 & 1 \end{array}$$

$$\begin{bmatrix} 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 4 & 1 & 0 \\ 0 & -2 & 2 & 2 & 0 & 1 \end{bmatrix}$$

$$2R_2 + R_3 \rightarrow R_3$$

$$\begin{bmatrix} 0 & 2 & -2 & 8 & 2 & 0 \\ 0 & -2 & 2 & 2 & 0 & 1 \end{bmatrix}$$

$$\begin{bmatrix} 1 & 2 & -1 & 1 & 0 & 0 \\ 0 & 1 & -1 & 4 & 1 & 0 \\ 0 & 0 & 0 & 10 & 2 & 1 \end{bmatrix}$$

The row 3 column 3 position is not a pivot position. Hence A is not row equivalent to I . A is singular.

Try it

Try to find A^{-1} where $A = \begin{bmatrix} 1 & 2 \\ 3 & 4 \end{bmatrix}$ by doing row reduction on the augmented matrix

$$\begin{bmatrix} 1 & 2 & 1 & 0 \\ 3 & 4 & 0 & 1 \end{bmatrix}$$

$$A^{-1} = \begin{bmatrix} -2 & 1 \\ 3/2 & -1/2 \end{bmatrix}$$

Section 2.3: Characterization of Invertible Matrices

Given an $n \times n$ matrix A , we can think of

- ▶ A matrix equation $A\mathbf{x} = \mathbf{b}$;
- ▶ A linear system that has A as its coefficient matrix;
- ▶ A linear transformation $T : \mathbb{R}^n \longrightarrow \mathbb{R}^n$ defined by $T(\mathbf{x}) = A\mathbf{x}$;
- ▶ Not to mention things like its **pivots**, its **rref**, the linear dependence/independence of its columns, blah blah blah...

Question: How is this stuff related, and how does being singular or invertible tie in?

Theorem: Suppose A is $n \times n$. The following are equivalent.¹

- (a) A is invertible.
- (b) A is row equivalent to I_n .
- (c) A has n pivot positions.
- (d) $A\mathbf{x} = \mathbf{0}$ has only the trivial solution.
- (e) The columns of A are linearly independent.
- (f) The transformation $\mathbf{x} \mapsto A\mathbf{x}$ is one to one.
- (g) $A\mathbf{x} = \mathbf{b}$ is consistent for every \mathbf{b} in \mathbb{R}^n .
- (h) The columns of A span \mathbb{R}^n .
- (i) The transformation $\mathbf{x} \mapsto A\mathbf{x}$ is onto.
- (j) There exists an $n \times n$ matrix C such that $CA = I$.
- (k) There exists an $n \times n$ matrix D such that $AD = I$.
- (l) A^T is invertible.

¹Meaning all are true or none are true.

Theorem: (An inverse matrix is unique.)

Let A and B be $n \times n$ matrices. If $AB = I$, then A and B are both invertible with $A^{-1} = B$ and $B^{-1} = A$.

To show this, suppose $AB = I$ and consider the homogeneous equation

$$B\vec{x} = \vec{0}.$$

Multiply on the left by A .

$$AB\vec{x} = A\vec{0}$$

$$I\vec{x} = \vec{0} \quad \Rightarrow \quad \vec{x} = \vec{0}$$

Hence $B\vec{x} = \vec{0}$ has only the trivial solution meaning B is invertible. $(d) \Rightarrow (a)$

Now the matrix B^{-1} exists. From

$$AB = I$$

Multiply on the right by B^{-1}

$$AB B^{-1} = I B^{-1}$$

$$\Rightarrow AI = I B^{-1} \Rightarrow A = B^{-1}$$

It follows that A is invertible and

$$A^{-1} = (B^{-1})^{-1} = B.$$