

## Section 1.1: Systems of Linear Equations

Recall that a **linear system** of (algebraic) equations in  $n$  variables  $x_1, \dots, x_n$  is one of the form

$$\begin{array}{ccccccccc} E. & \rightarrow & a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ & & a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ & & \vdots & & \vdots & & \vdots & & \vdots & & \vdots \\ & & a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m. \end{array}$$

# Theorem on Solutions

A linear system of equations has exactly one of the following:

- i No solution, or
- ii Exactly one solution, or
- iii Infinitely many solutions.

We said that a system is

- ▶ **inconsistent** if it has no solutions and
- ▶ **consistent** if it has at least one solution.

# Linear Systems & Matrices

Given a linear system, we can identify two matrices corresponding to that system.

$$\begin{array}{cccccc} a_{11}x_1 & + & a_{12}x_2 & + & \cdots & + & a_{1n}x_n & = & b_1 \\ a_{21}x_1 & + & a_{22}x_2 & + & \cdots & + & a_{2n}x_n & = & b_2 \\ & & \vdots & & \vdots & & \vdots & & \vdots \\ a_{m1}x_1 & + & a_{m2}x_2 & + & \cdots & + & a_{mn}x_n & = & b_m. \end{array}$$

The **coefficient matrix** and the **augmented matrix**.

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} \\ a_{21} & a_{22} & \cdots & a_{2n} \\ \vdots & \vdots & \ddots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} \end{bmatrix}$$

$$\begin{bmatrix} a_{11} & a_{12} & \cdots & a_{1n} & b_1 \\ a_{21} & a_{22} & \cdots & a_{2n} & b_2 \\ \vdots & \vdots & \ddots & \vdots & \vdots \\ a_{m1} & a_{m2} & \cdots & a_{mn} & b_m \end{bmatrix}$$

# Elementary Row Operations: On a Matrix

We have three operations we can perform on a matrix that are called **Elementary Row Operations**.

- i Interchange any two rows (**row swap**).
- ii Multiply a row by any nonzero constant (**scaling**).
- iii Replace a row with the sum of itself and a multiple of another row (**replacement**).

**Definition:** If any sequence of elementary row operations are performed on a matrix, the resulting matrix is called **row equivalent**.

*to the original matrix*

# Theorem on Row Equivalent Matrices

**Theorem:** If the augmented matrices of two linear systems are row equivalent, then the systems have the same solution set. That is, the linear systems are equivalent.

# Augmented Matrix

We saw the example

$$\begin{array}{rclcrcl} x_1 & + & 2x_2 & - & x_3 & = & -4 \\ 2x_1 & & & + & x_3 & = & 7 \\ x_1 & + & x_2 & + & x_3 & = & 6 \end{array} \quad \left[ \begin{array}{cccc} 1 & 2 & -1 & -4 \\ 2 & 0 & 1 & 7 \\ 1 & 1 & 1 & 6 \end{array} \right]$$

Through a sequence of operation (swapping equations, scaling equations, and replacing equations), we transformed this system into the **equivalent** system

$$\begin{array}{rcl} x_1 & = & 1 \\ & x_2 & = & 0 \\ & & x_3 & = & 5 \end{array} \quad \left[ \begin{array}{cccc} 1 & 0 & 0 & 1 \\ 0 & 1 & 0 & 0 \\ 0 & 0 & 1 & 5 \end{array} \right]$$

## A key here is *structure!*

Consider the following augmented matrix. Determine if the associated system is consistent or inconsistent. If it is consistent, determine the solution set.

$$(a) \begin{bmatrix} 1 & 0 & 0 & 3 \\ 0 & 1 & 0 & 1 \\ 0 & 0 & 1 & -2 \end{bmatrix}$$

The system is

$$1x_1 + 0x_2 + 0x_3 = 3$$

$$0x_1 + 1x_2 + 0x_3 = 1$$

$$0x_1 + 0x_2 + 1x_3 = -2$$

It's consistent and the solution set

is the one set of values

$$(3, 1, -2) \text{ a.k.a. } \begin{cases} x_1 = 3 \\ x_2 = 1 \\ x_3 = -2 \end{cases}$$

$$(b) \begin{bmatrix} 1 & 2 & 0 & 3 \\ 0 & 1 & -1 & 4 \\ 0 & 0 & 0 & 3 \end{bmatrix}$$

$$\begin{aligned} x_1 + 2x_2 + 0x_3 &= 3 \\ 0x_1 + x_2 - x_3 &= 4 \\ 0x_1 + 0x_2 + 0x_3 &= 3 \end{aligned}$$

This says  $0 = 3$   
which is always false.

The system is inconsistent.



$$(c) \begin{bmatrix} 1 & 0 & -2 & -3 \\ 0 & 1 & 1 & 4 \\ 0 & 0 & 0 & 0 \end{bmatrix}$$

$$x_1 + 0x_2 - 2x_3 = -3$$

$$0x_1 + x_2 + x_3 = 4$$

$$0x_1 + 0x_2 + 0x_3 = 0$$

this last equation is

$$0=0$$

which is always true.

The 1st two equations can be rearranged as

$$x_1 = -3 + 2x_3 \quad \text{with no conditions on } x_3$$

$$x_2 = 4 - x_3$$

This has infinitely many solutions of the form

$$x_1 = -3 + 2x_3 \quad \text{and } x_3 \text{ is any real number}$$

$$x_2 = 4 - x_3$$