

## Section 4.2: Null & Column Spaces, Row Space, Linear Transformations

**Definition:** Let  $A$  be an  $m \times n$  matrix. The **null space** of  $A$ , denoted by  $\text{Nul } A$ , is the set of all solutions of the homogeneous equation  $A\mathbf{x} = \mathbf{0}$ . That is

$$\text{Nul } A = \{\mathbf{x} \in \mathbb{R}^n \mid A\mathbf{x} = \mathbf{0}\}.$$

**Theorem:** If  $A$  is an  $m \times n$  matrix, then  $\text{Nul}(A)$  is a subspace of  $\mathbb{R}^n$ .

# Column Space

**Definition:** The **column space** of an  $m \times n$  matrix  $A$ , denoted  $\text{Col } A$ , is the set of all linear combinations of the columns of  $A$ . If  $A = [\mathbf{a}_1 \ \cdots \ \mathbf{a}_n]$ , then

$$\text{Col } A = \text{Span}\{\mathbf{a}_1, \dots, \mathbf{a}_n\}.$$

**Theorem:** The column space of an  $m \times n$  matrix  $A$  is a subspace of  $\mathbb{R}^m$ .

**Corollary:**  $\text{Col } A = \mathbb{R}^m$  if and only if the equation  $A\mathbf{x} = \mathbf{b}$  has a solution for every  $\mathbf{b}$  in  $\mathbb{R}^m$ .

## Example

Find a matrix  $A$  such that  $W = \text{Col } A$  where

$$W = \left\{ \begin{bmatrix} 6a - b \\ a + b \\ -7a \end{bmatrix} \mid a, b \in \mathbb{R} \right\}.$$

We need to recognize elements of  $W$  in the form  $A\vec{x}$  for some matrix  $A$ .

$$\begin{aligned} \begin{bmatrix} 6a - b \\ a + b \\ -7a \end{bmatrix} &= \begin{bmatrix} 6a \\ a \\ -7a \end{bmatrix} + \begin{bmatrix} -b \\ b \\ 0 \end{bmatrix} \\ &= a \begin{bmatrix} 6 \\ 1 \\ -7 \end{bmatrix} + b \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} \end{aligned}$$

$$= \begin{bmatrix} 6 & -1 \\ 1 & 1 \\ -7 & 0 \end{bmatrix} \begin{bmatrix} a \\ b \end{bmatrix}$$

Hence  $W = \text{Col}(A)$  where  $A = \begin{bmatrix} 6 & -1 \\ 1 & 1 \\ -7 & 0 \end{bmatrix}$ .

# Row Space

**Definition:** The **row space**, denoted  $\text{Row } A$ , of an  $m \times n$  matrix  $A$  is the subspace of  $\mathbb{R}^n$  spanned by the rows of  $A$ .

**Theorem** If two matrices  $A$  and  $B$  are row equivalent, then their row spaces are the same.

This says that row operations don't change the row space.

## Example

Find two spanning sets for  $A$  given

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix} \xrightarrow{\text{rref}} \begin{bmatrix} 1 & 0 & 9 & 0 \\ 0 & 1 & -5 & 0 \\ 0 & 0 & 0 & 1 \end{bmatrix}$$

We can take one set from  $A$  and one from the rref

$$\text{Row}(A) = \text{Span} \left\{ \begin{bmatrix} 2 \\ 4 \\ -2 \\ 1 \end{bmatrix}, \begin{bmatrix} -2 \\ -5 \\ 7 \\ 3 \end{bmatrix}, \begin{bmatrix} 3 \\ 7 \\ -8 \\ 6 \end{bmatrix} \right\}$$

and

$$\text{Row}(A) = \text{Span} \left\{ \begin{bmatrix} 1 \\ 0 \\ 9 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 1 \\ -5 \\ 0 \end{bmatrix}, \begin{bmatrix} 0 \\ 0 \\ 0 \\ 1 \end{bmatrix} \right\}.$$

## Example: Comparing $\text{Col}(A)$ and $\text{Nul}(A)$

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}$$

(a) If  $\text{Col } A$  is a subspace of  $\mathbb{R}^k$ , what is  $k$ ?

The columns are in  $\mathbb{R}^3$ , so  $k=3$ .

(b) If  $\text{Nul } A$  is a subspace of  $\mathbb{R}^k$ , what is  $k$ ?

$\vec{x}$  is in  $\text{Nul}(A)$  if  $A\vec{x} = \vec{0}$  this requires  
 $\vec{x}$  to be in  $\mathbb{R}^4$  so  $k=4$ .

## Example Continued...

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}, \quad \text{and} \quad \mathbf{u} = \begin{bmatrix} 3 \\ -2 \\ -1 \\ 0 \end{bmatrix}$$

(c) Is  $\mathbf{u}$  in  $\text{Nul } A$ ? Could  $\mathbf{u}$  be in  $\text{Col } A$ ?

$\vec{u}$  is in  $\text{Nul}(A)$  if  $A\vec{u} = \vec{0}$ .

$$A\vec{u} = \begin{bmatrix} 0 \\ -3 \\ 3 \end{bmatrix} \neq \vec{0} \quad \text{so } \vec{u} \text{ is } \underline{\underline{\text{not}}} \text{ in } \text{Nul}(A).$$

$\vec{u}$  could not be in  $\text{Col}(A)$ .  $\text{Col}(A)$  is a subspace of  $\mathbb{R}^3$ ;  $\vec{u}$  is in  $\mathbb{R}^4$ .



## Example Continued...

$$A = \begin{bmatrix} 2 & 4 & -2 & 1 \\ -2 & -5 & 7 & 3 \\ 3 & 7 & -8 & 6 \end{bmatrix}, \quad \text{and} \quad \mathbf{v} = \begin{bmatrix} 3 \\ -1 \\ 3 \end{bmatrix}$$

(d) Is  $\mathbf{v}$  in  $\text{Col } A$ ? Could  $\mathbf{v}$  be in  $\text{Nul } A$ ?

$\vec{v}$  is in  $\mathbb{R}^3$  so it can't be in  $\text{Nul}(A)$ .

$\vec{v}$  is in  $\text{Col}(A)$  if  $A\vec{x} = \vec{v}$  is

consistent. Using the augmented matrix

$$[A \ \vec{v}], \quad \xrightarrow{\text{rref}} \quad \begin{bmatrix} 1 & 0 & 9 & 0 & 5 \\ 0 & 1 & -5 & 0 & -30/17 \\ 0 & 0 & 0 & 1 & 1/17 \end{bmatrix}$$

The last column is not a pivot column,  
hence  $A\vec{x} = \vec{v}$  is consistent.

So  $\vec{v}$  is in  $\text{Col}(A)$ .

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# Linear Transformation

**Definition:** Let  $V$  and  $W$  be vector spaces. A linear transformation  $T : V \rightarrow W$  is a rule that assigns to each vector  $\mathbf{x}$  in  $V$  a unique vector  $T(\mathbf{x})$  in  $W$  such that

- (i)  $T(\mathbf{u} + \mathbf{v}) = T(\mathbf{u}) + T(\mathbf{v})$  for every  $\mathbf{u}, \mathbf{v}$  in  $V$ , and
- (ii)  $T(c\mathbf{u}) = cT(\mathbf{u})$  for every  $\mathbf{u}$  in  $V$  and scalar  $c$ .

## Example

Let  $C^1(\mathbb{R})$  denote the set of all real valued functions that are differentiable and  $C^0(\mathbb{R})$  the set of all continuous real valued functions. Note that differentiation is a linear transformation. That is

$$D : C^1(\mathbb{R}) \longrightarrow C^0(\mathbb{R}), \quad D(f) = f'$$

satisfies the two conditions in the previous definition.

We know from calculus that if  $f$  and  $g$  are differentiable and  $c$  is a scalar, then

$$\frac{d}{dx}(f(x) + g(x)) = f'(x) + g'(x) \quad \text{and} \quad \frac{d}{dx}(cf(x)) = cf'(x).$$

Characterize the subset of  $C^1(\mathbb{R})$  such that  $Df = 0$ .

This is the set of constant functions.

## Range and Kernel

**Definition:** The **range** of a linear transformation  $T : V \longrightarrow W$  is the set of all vectors in  $W$  of the form  $T(\mathbf{x})$  for some  $\mathbf{x}$  in  $V$ . (The set of all images of elements of  $V$ .)

A column space is a **range**.

**Definition:** The **kernel** of a linear transformation  $T : V \longrightarrow W$  is the set of all vectors  $\mathbf{x}$  in  $V$  such that  $T(\mathbf{x}) = \mathbf{0}$ . (The analog of the null space of a matrix.)

A null space is a **kernel**.

# Range & Kernel as Subspaces

**Theorem:** Given linear transformation  $T : V \longrightarrow W$ ,

- ▶ the range of  $T$  is a subspace of  $W$ ,
- ▶ and the kernel of  $T$  is a subspace of  $V$ .

## Example

Consider  $T : C^1(\mathbb{R}) \longrightarrow C^0(\mathbb{R})$  defined by

$$T(f) = \frac{df}{dx} + \alpha f(x), \quad \alpha \text{ a fixed constant.}$$

(a) Express the equation that a function  $y$  must satisfy if  $y$  is in the kernel of  $T$ .

$y$  is in the kernel of  $T$  if  
 $T(y) = 0$ . Well,  $T(y) = \frac{dy}{dx} + \alpha y$ .

The equation is  $\frac{dy}{dx} + \alpha y = 0$ .

Example:  $T : C^1(\mathbb{R}) \longrightarrow C^0(\mathbb{R})$

(b) Show that for any scalar  $c$ ,  $y = ce^{-\alpha x}$  is in the kernel of  $T$ .

If  $y$  is in the kernel, then

$$\frac{dy}{dx} + \alpha y = 0.$$

If  $y = ce^{-\alpha x}$  then  $\frac{dy}{dx} = c(-\alpha e^{-\alpha x}) = -\alpha c e^{-\alpha x}$

$$\begin{aligned} \frac{dy}{dx} + \alpha y &= -\alpha c e^{-\alpha x} + \alpha (c e^{-\alpha x}) \\ &= -\alpha c e^{-\alpha x} + \alpha c e^{-\alpha x} = 0 \end{aligned}$$

$\Rightarrow y = ce^{-\alpha x}$  is in the kernel of  $T$ .