## November 19 Math 3260 sec. 53 Fall 2025

## Chapter 6 Eigenstuff

Consider the linear transformation  $T: R^2 \to R^2$  defined by  $T(\vec{x}) = A\vec{x}$  with  $A = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix}$ .

1. Evaluate 
$$T(\langle -1, 1 \rangle) = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \langle -1, 1 \rangle = \langle -6, -2 \rangle$$

2. Evaluate 
$$T(\langle 1,3\rangle) = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix} \langle 1,3\rangle = \langle 2,6\rangle$$

3. Evaluate 
$$T(\langle 1, -2 \rangle) = \begin{pmatrix} 5 & -1 \\ 3 & 1 \end{pmatrix} \langle 1, -2 \rangle = \langle 7, 1 \rangle$$



Note that T seems to rotate and stretch the input vectors. <-1.1>  $x_2$ T((1,3))gets stretched and rotated as does <1,-2>. But 6 = (2,6) 15 they aren't stretched by the same factor  $T(\langle 1,3\rangle) = \langle 2,6\rangle$ in Span {<1,3>}. or rotated through the same angle. But  $T(\langle -1, 1 \rangle) = \langle -6, 2 \rangle$ T doesn't rotate  $T(\langle 1, -2 \rangle) = \langle 7, 1 \rangle$ the input <1,3>  $\langle -1, 1 \rangle$  $\langle 1, 3 \rangle$ at all. It just T(<1.3>)= 2<1.3>scales it by a -6 \_4 factor of 2.  $x_1^{8}$  $\sqrt{\langle 1, -2 \rangle}$  $T(\langle -1, 1 \rangle) = \langle -6, -2 \rangle$ -6

Figure: Plot of standard representations of  $\langle -1, 1 \rangle$ ,  $\mathcal{T}(\langle -1, 1 \rangle)$ ,  $\langle 1, 3 \rangle$ ,  $\mathcal{T}(\langle 1, 3 \rangle)$ ,  $\langle 1, -2 \rangle$ , and  $\mathcal{T}(\langle 1, -2 \rangle)$  together.

Example Continued... 
$$A = \begin{bmatrix} 5 & -1 \\ 3 & 1 \end{bmatrix}$$

Show that there is a special set of nonzero vectors in  $\mathbb{R}^2$  with the property  $A\vec{x} = 2\vec{x}$ .

Let 
$$\vec{X} = (X_1, X_2)$$
.  

$$A\vec{X} = \begin{bmatrix} S & 1 \\ 3 & 1 \end{bmatrix}(X_1, X_2) = (SX_1 - X_2, 3X_1 + X_2)$$

$$2\vec{X} = (ZX_1, 2X_2) \quad \text{set} \quad (SX_1 - X_2, 3X_1 + X_2) = (ZX_1, 2X_2)$$

$$\Rightarrow (ZX_1 - X_2) = (ZX_1 - X_2) \quad (ZX_1 - X_2) = (ZX_1, 2X_2)$$

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$$\begin{bmatrix} 3 & -1 & | & 0 \\ 3 & -1 & | & 0 \end{bmatrix} \xrightarrow{\text{cref}} \begin{bmatrix} 1 & -\frac{1}{3} & | & 0 \\ 0 & 0 & | & 0 \end{bmatrix} \times_{1} = \frac{1}{3} \times_{2} \times_{2} - \frac{1}{3} \times_{2} \times_{2} - \frac{1}{3} \times_{2} \times_{2} \times_{2} - \frac{1}{3} \times_{2} \times_$$

\* If 
$$x_2=3$$
, we get  $\vec{x}=\langle 1,3\rangle$ .

Note that A doesn't scale every vector by 2, only the ones in Span{<1/3, 1>}.For these special vectors, the matrix-vector product ends up being a scalar-vector product, specifically with the scalar 2.

# What are Eigen things?

We'll focus on linear transformations  $T: \mathbb{R}^n \to \mathbb{R}^n$  with square matrix A such that  $T(\vec{x}) = A\vec{x}$ , and consider equations of the form

$$A\vec{x} = \lambda \vec{x}$$

with  $\lambda$  a scalar and  $\vec{x}$  a nonzero vector. We'll call scalars like  $\lambda$  eigenvalues and vectors like  $\vec{x}$  eigenvectors. We'll also consider things like eigenspaces and eigenbases.

### Questions:

- Does a matrix have such scalars and vectors?
- How would we find them?
- What do the tell us about a matrix?
- What can we do with them?

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## 6.1 The Determinant

The determinant is a scalar valued function on  $M_{n \times n}$ . The determinant is related to various properties of a matrix, most notably invertibility.

### 2 × 2 Determinant

Let  $A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}$ . The **determinant** of A, denoted det(A), is the number

$$\det(A) = ad - bc$$
.

**Remark:**  $1 \times 1$  matrices have limited usefulness. We will define the determinant of the  $1 \times 1$  matrix A = [a] to be det(A) = a.

**Example:** Evaluate the determinant of each matrix.

$$A = \left[ \begin{array}{cc} 5 & -1 \\ 3 & 1 \end{array} \right]$$

$$B = \left[ \begin{array}{cc} 3 & -1 \\ 3 & -1 \end{array} \right]$$



#### **Submatrices**

Let  $A = [a_{ii}]$  be an  $n \times n$  matrix. The notation

 $A_{ij}$ 

will denote the  $(n-1)\times(n-1)$  matrix obtained from A by removing the  $i^{th}$  row and the  $i^{th}$  column.

For example, if  $A = [a_{ij}]$  is a 3 × 3 matrix, we can form nine different 2 × 2 matrices  $A_{ij}$ .

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix} \rightarrow A_{23} = \begin{bmatrix} a_{11} & a_{12} \\ a_{31} & a_{32} \end{bmatrix}.$$

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{21} & a_{22} & a_{23} \end{bmatrix} \rightarrow A_{31} = \begin{bmatrix} a_{12} & a_{13} \\ a_{22} & a_{23} \end{bmatrix}.$$

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### **Minors & Cofactors**

Let A be an  $n \times n$  matrix,  $n \ge 2$ . The *ij*th **minor** of A is the determinant of the  $(n-1) \times (n-1)$  matrix  $A_{ii}$ . That is,  $\det(A_{ii})$  is the *ij*th minor of A. a minor is

Let A be an 
$$n \times n$$
 matrix,  $n \ge 2$ .

*ij*th **cofactor** of 
$$A = (-1)^{i+j} \det(A_{ij})$$
.

## **Cofactor Signs**

The factor  $(-1)^{i+j}$  gives an alternating sign based on the position of  $a_{ij}$ in the matrix.

$$\begin{bmatrix} + & - & + & - & \cdots \\ - & + & - & + & \cdots \\ + & - & + & - & \cdots \\ - & + & - & + & \cdots \\ \vdots & \vdots & \vdots & \vdots & \ddots \end{bmatrix}.$$

#### $n \times n$ Determinant

Let  $A = [a_{ij}]$  be an  $n \times n$  matrix. The determinant of A, denoted det(A) is given by

$$\det(A) = \sum_{j=1}^{n} (-1)^{1+j} a_{1j} \det(A_{1j}). \tag{1}$$

The sum in equation (1) is called a **cofactor expansion** across the first row of *A*.

**Remark:** Note what this sum is. Take each entries in the first row,  $a_{1j}$ , multiply it by its corresponding cofactor  $(-1)^{1+j} \det(A_{1j})$ , and then add them all together:

$$\det(A) = (-1)^2 a_{11} \det(A_{11}) + (-1)^3 a_{12} \det(A_{12}) + \cdots + (-1)^{n+1} a_{1n} \det(A_{1n})$$

$$= a_{11} \det(A_{11}) - a_{12} \det(A_{12}) + \cdots + (-1)^{n+1} a_{1n} \det(A_{1n})$$

# Example

Find det(A) if 
$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 2 \\ 1 & -1 & 0 \end{bmatrix}$$
.

$$A_{11} = \begin{bmatrix} 3 & z \\ -1 & 0 \end{bmatrix} \qquad A_{12} = \begin{bmatrix} 0 & 2 \\ 1 & 0 \end{bmatrix} \qquad A_{13} = \begin{bmatrix} 0 & 3 \\ 1 & -1 \end{bmatrix}$$

$$dx(A_{i1}) = 3(6) - (-1)(7) \qquad dx(A_{i2}) = 0^{2} - 1(2) \qquad dx(A_{i3}) = 0(-1) - (1)(3)$$

$$dt(A) = 1(z) - z(-z) + (-1)(-3)$$
= 2 + 4 + 3 = 9

# **Alternative Cofactor Expansions**

We can actually take a determinant by a cofactor expansion across any row. Fix a number for i (between 1 and n).

$$\det(A) = \sum_{j=1}^{n} (-1)^{i+j} a_{ij} \det(A_{ij}). \tag{2}$$

Similarly, we can compute det(A) using a cofactor expansion down any columns. Fix a number j (between 1 and n).

$$\det(A) = \sum_{i=1}^{n} (-1)^{i+j} a_{ij} \det(A_{ij}). \tag{3}$$

**Remark:** Formulas (2) and (3) look almost identical. But in formula (2), the value if i doesn't change. In the formula (3), the value if j doesn't change.

## Example

Find det(A) if  $A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 2 \\ 1 & -1 & 0 \end{bmatrix}$  by cofactor expansion across the second row and down the third column.

$$det(A) = -a_{21} det(A_{21}) + a_{22} det(A_{22}) - a_{27} det(A_{23})$$

$$= -0 det \begin{pmatrix} 2 & -1 \\ -1 & 0 \end{pmatrix} + 3 det \begin{pmatrix} 1 & -1 \\ 1 & 0 \end{pmatrix} - 2 det \begin{pmatrix} 1 & 2 \\ 1 & -1 \end{pmatrix}$$

$$= 0 + 3 (1 - 0 - (1)(-1)) - 2 ((1)(-1) - 1(2))$$

$$= 0 + 3 (1) - 2 (-1-2)$$

$$= 0 + 3 + 6 = 9$$

$$A = \begin{bmatrix} 1 & 2 & -1 \\ 0 & 3 & 2 \\ 1 & -1 & 0 \end{bmatrix}$$

$$\det(A) = + a_{13} \det(A_{13}) - a_{23} \det(A_{23}) + a_{33} \det(A_{33})$$

$$= + (-1) \det \begin{bmatrix} 0 & 3 \\ 1 & -1 \end{bmatrix} - 2 \det \begin{bmatrix} 1 & 2 \\ 1 & -1 \end{bmatrix} + 0 \det \begin{bmatrix} 1 & 2 \\ 0 & 3 \end{bmatrix}$$

$$= -1 (0-3) - 2(-1-2) + 0$$

$$= 3 + 6 = 9$$

Note that the negative sign is because the entry is -1. The cofactor sign starts with + but the actual number  $a_{13}$  is negative.

# Properties of the Determinant

Evaluate 
$$\det(A)$$
 if  $A = \begin{bmatrix} 2 & 0 & -1 & 4 \\ 4 & 0 & 5 & -3 \\ -6 & 0 & 1 & 1 \\ 2 & 0 & 13 & -1 \end{bmatrix}$ .

We don't have to actually compute any cofactors since each entry in the column is zero. If we did do the expansion across any row or down any other column, we'd still get zero as the final result.

### **Triangular Matrices**

A matrix  $A = [a_{ij}]$  is called **upper triangular** if  $a_{ij} = 0$  for all i > j, and it's called **lower triangular** if  $a_{ij} = 0$  for all i < j. As the names suggest, upper triangular matrices have all their nonzero entries on or above the main diagonal, and lower triangular matrices have all their nonzero entries on or below the main diagonal.

A matrix that is both upper triangular and lower triangular is called a diagonal matrix.

$$\begin{bmatrix} a_{11} & 0 & 0 & \cdots & 0 \\ 0 & a_{22} & 0 & \cdots & 0 \\ 0 & 0 & a_{33} & \cdots & 0 \\ \vdots & \vdots & \vdots & \ddots & \vdots \\ 0 & 0 & 0 & \cdots & a_{nn} \end{bmatrix}$$
diagonal matrix

Since a cofactor expansion is the same across any row or down any column...

## **Theorem**

Let A be an  $n \times n$  matrix.

- 1. If  $\vec{0}_n$  is a row vector or a column vector of A, then det(A) = 0.
- 2.  $det(A^T) = det(A)$ .
- 3. If A is a triangular matrix (upper, lower or diagonal), the det(A) is the product of the diagonal entries

$$\det(A) = a_{11}a_{22}\cdots a_{nn}$$

