

Section 16: Laplace Transforms of Derivatives and IVPs

We can solve a system of ODEs using Laplace transforms. Here, we'll consider systems that are

- ▶ linear,
- ▶ having initial conditions at $t = 0$, and
- ▶ constant coefficient.

Let's see it in action (i.e. with a couple of examples).

Example

Solve the system of equations

$$\frac{dx}{dt} = -2x - 2y + 60, \quad x(0) = 0$$

$$\frac{dy}{dt} = -2x - 5y + 60, \quad y(0) = 0$$

$$\text{Let } X(s) = \mathcal{L}\{x(t)\} \text{ and } Y(s) = \mathcal{L}\{y(t)\}$$

$$\mathcal{L}\{x'\} = \mathcal{L}\{-2x - 2y + 60\}$$

$$\mathcal{L}\{y'\} = \mathcal{L}\{-2x - 5y + 60\}$$

Example Continued...¹

$$sX(s) - x(0) = -2X(s) - 2Y(s) + \frac{60}{s}$$

$$sY(s) - y(0) = -2X(s) - 5Y(s) + \frac{60}{s}$$

Use $x(0)=0$ and $y(0)=0$

$$sX(s) + 2X(s) + 2Y(s) = \frac{60}{s}$$

$$sY(s) + 2X(s) + 5Y(s) = \frac{60}{s}$$

$$(s+2)X(s) + 2Y(s) = \frac{60}{s}$$

$$2X(s) + (s+5)Y(s) = \frac{60}{s}$$

¹ Cramer's Rule will be helpful at some point.

Using Cramer's rule

$$A = \begin{bmatrix} s+2 & 2 \\ 2 & s+5 \end{bmatrix} \quad A_X = \begin{bmatrix} \frac{60}{s} & 2 \\ \frac{60}{s} & s+5 \end{bmatrix}, \quad A_Y = \begin{bmatrix} s+2 & \frac{60}{s} \\ 2 & \frac{60}{s} \end{bmatrix}$$

$$\begin{aligned} \det(A) &= (s+2)(s+5) - 4 = s^2 + 7s + 10 - 4 = s^2 + 7s + 6 \\ &= (s+1)(s+6) \end{aligned}$$

$$\det(A_X) = \frac{60}{s}(s+5) - \frac{60}{s}(2) = \frac{60}{s}(s+5-2) = \frac{60}{s}(s+3)$$

$$\det(A_Y) = (s+2)\frac{60}{s} - 2\frac{60}{s} = \frac{60}{s}(s+2-2) = \frac{60}{s}s = 60$$

$$X = \frac{\det(A_X)}{\det(A)} = \frac{\frac{60}{s}(s+3)}{(s+1)(s+6)} = \frac{60(s+3)}{s(s+1)(s+6)}$$

$$\varphi = \frac{\det(A_f)}{\det(A)} = \frac{60}{(s+1)(s+6)}$$

We have to do partial fraction decomps to take the inverse transform.

$$X(s) = \frac{60(s+3)}{s(s+1)(s+6)} = \frac{A}{s} + \frac{B}{s+1} + \frac{C}{s+6}$$

$$\varphi(s) = \frac{60}{(s+1)(s+6)} = \frac{D}{s+1} + \frac{E}{s+6}$$

For X $60(s+3) = A(s+1)(s+6) + Bs(s+6) + Cs(s+1)$

set $s=0$ $60(3) = A(1)(6) \Rightarrow A = \frac{60(3)}{6} = 30$

$s=-1$ $60(2) = B(-1)(5) \Rightarrow B = \frac{60(2)}{-5} = -24$

$$s = -6 \quad 60(-3) = C(-6)(-5) \Rightarrow C = \frac{60(-3)}{30} = -6$$

The Ψ is done similarly. we get

$$X(s) = \frac{30}{s} - \frac{24}{s+1} - \frac{6}{s+6}$$

$$\Psi(s) = \frac{12}{s+1} - \frac{12}{s+6}$$

The solution to the system

$$x(t) = \mathcal{L}^{-1}\{X(s)\}$$

$$y(t) = \mathcal{L}^{-1}\{\Psi(s)\}$$

$$x(t) = 30 - 24e^{-t} - 6e^{-6t}$$

$$y(t) = 12e^{-t} - 12e^{-6t}$$

Example

Use the Laplace transform to solve the system of equations

$$\begin{aligned}x''(t) &= y, & x(0) &= 1, & x'(0) &= 0 \\y'(t) &= x, & y(0) &= 1\end{aligned}$$

$$\text{Let } X = \mathcal{L}\{x\} \text{ and } Y = \mathcal{L}\{y\}$$

$$\mathcal{L}\{x''\} = \mathcal{L}\{y\}$$

$$\mathcal{L}\{y'\} = \mathcal{L}\{x\}$$

$$s^2 X - sX(0) - x'(0) = Y$$

$$sY - y(0) = X$$

$$\text{Use } X(0) = 1, x'(0) = 0 \\ y(0) = 1$$

$$\begin{aligned} s^2 X - s &= Y \\ s Y - 1 &= X \end{aligned} \Rightarrow$$

$$\begin{aligned} s^2 X - Y &= s \\ -X + s Y &= 1 \end{aligned}$$

Using Cramer's rule

$$A = \begin{bmatrix} s^2 & -1 \\ -1 & s \end{bmatrix}, \quad A_x = \begin{bmatrix} s & -1 \\ 1 & s \end{bmatrix}, \quad A_y = \begin{bmatrix} s^2 & s \\ -1 & 1 \end{bmatrix}$$

$$\det(A) = s^3 - 1, \quad \det(A_x) = s^2 + 1, \quad \det(A_y) = s^2 + s$$

$$X(s) = \frac{s^2 + 1}{s^3 - 1} = \frac{s^2 + 1}{(s-1)(s^2 + s + 1)}$$

$$Y(s) = \frac{s^2 + s}{s^3 - 1} = \frac{s(s+1)}{(s-1)(s^2 + s + 1)}$$

Note s^2+s+1 is irreducible

The partial fraction decomp looks like

$$X = \frac{s^2+1}{(s-1)(s^2+s+1)} = \frac{A}{s-1} + \frac{Bs+C}{s^2+s+1}$$

$$Y = \frac{s(s+1)}{(s-1)(s^2+s+1)} = \frac{D}{s-1} + \frac{Es+F}{s^2+s+1}$$

After some effort, we get

$$X = \frac{\frac{2}{3}}{s-1} + \frac{\frac{1}{3}(s-1)}{s^2+s+1}$$

$$Y = \frac{\frac{2}{3}}{s-1} + \frac{\frac{1}{3}(s+2)}{s^2+s+1}$$

We need to complete the square.

$$\begin{aligned} s^2 + s + 1 &= s^2 + s + \frac{1}{4} - \frac{1}{4} + 1 = \left(s + \frac{1}{2}\right)^2 + \frac{3}{4} \\ &= \left(s + \frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2 \end{aligned}$$

We need $s + \frac{1}{2}$ every where that s appears

$$s - 1 = s + \frac{1}{2} - \frac{1}{2} - 1 = s + \frac{1}{2} - \frac{3}{2}$$

$$s + 2 = s + \frac{1}{2} - \frac{1}{2} + 2 = s + \frac{1}{2} + \frac{3}{2}$$

$$X = \frac{2/3}{s-1} + \frac{1}{3} \frac{s + \frac{1}{2}}{\left(s + \frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2} - \frac{1}{3} \frac{3/2}{\left(s + \frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2}$$

$$Y = \frac{2/3}{s-1} + \frac{1}{3} \frac{s + \frac{1}{2}}{\left(s + \frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2} + \frac{1}{3} \frac{3/2}{\left(s + \frac{1}{2}\right)^2 + \left(\frac{\sqrt{3}}{2}\right)^2}$$

We'll Finish Next Time.

Cramer's Rule

Cramer's Rule is a method to solve an algebraic linear system of the form

$$\begin{array}{rcrcrcrcrcrl} ax & + & by & = & e \\ cx & + & dy & = & f \end{array}$$

Define the following matrices

$$A = \begin{bmatrix} a & b \\ c & d \end{bmatrix}, \quad A_x = \begin{bmatrix} e & b \\ f & d \end{bmatrix}, \quad \text{and} \quad A_y = \begin{bmatrix} a & e \\ c & f \end{bmatrix}.$$

If $\det(A) \neq 0$, then the system is uniquely solvable and the solution

$$x = \frac{\det(A_x)}{\det(A)} \quad \text{and} \quad y = \frac{\det(A_y)}{\det(A)}.$$

Cramer's Rule 3×3 case

$$\begin{aligned}a_{11}x + a_{12}y + a_{13}z &= b_1 \\a_{21}x + a_{22}y + a_{23}z &= b_2 \\a_{31}x + a_{32}y + a_{33}z &= b_3\end{aligned}$$

Let

$$A = \begin{bmatrix} a_{11} & a_{12} & a_{13} \\ a_{21} & a_{22} & a_{23} \\ a_{31} & a_{32} & a_{33} \end{bmatrix}, \quad A_x = \begin{bmatrix} b_1 & a_{12} & a_{13} \\ b_2 & a_{22} & a_{23} \\ b_3 & a_{32} & a_{33} \end{bmatrix}$$
$$A_y = \begin{bmatrix} a_{11} & b_1 & a_{13} \\ a_{21} & b_2 & a_{23} \\ a_{31} & b_3 & a_{33} \end{bmatrix}, \quad A_z = \begin{bmatrix} a_{11} & a_{12} & b_1 \\ a_{21} & a_{22} & b_2 \\ a_{31} & a_{32} & b_3 \end{bmatrix}$$

If $\det(A) \neq 0$, then the solution to the system

$$x = \frac{\det(A_x)}{\det(A)}, \quad y = \frac{\det(A_y)}{\det(A)}, \quad \text{and} \quad z = \frac{\det(A_z)}{\det(A)}.$$