

Section 10: Variation of Parameters

Variation of Parameters

$$y'' + P(x)y' + Q(x)y = g(x)$$

If  $\{y_1, y_2\}$  is a fundamental solution set for the associated homogeneous equation, then the general solution is

$$y = y_c + y_p \quad \text{where}$$

$$y_c = c_1 y_1(x) + c_2 y_2(x), \quad \text{and} \quad y_p = u_1(x)y_1(x) + u_2(x)y_2(x).$$

Letting  $W$  denote the Wronskian of  $y_1$  and  $y_2$ , the functions  $u_1$  and  $u_2$  are given by the formulas

$$u_1 = \int \frac{-y_2 g}{W} dx, \quad \text{and} \quad u_2 = \int \frac{y_1 g}{W} dx.$$

## Solve the IVP

$$x^2 y'' + xy' - 4y = 8x^2, \quad y(1) = 1, \quad y'(1) = 1$$

The complementary solution of the ODE is  $y_c = c_1 x^2 + c_2 x^{-2}$ .

We found the particular solution using variation of parameters. With  $y_1 = x^2$  and  $y_2 = x^{-2}$ , the Wronskian turned out to be  $W = -4x^{-1}$ . Using  $g(x) = 8$ , we got

$$u_1 = 2 \ln(x), \quad \text{and} \quad u_2 = -\frac{1}{2} x^4.$$

Since  $y_p = u_1 y_1 + u_2 y_2$ , this gave us

$$y_p = 2x^2 \ln(x) - \frac{1}{2} x^2.$$

The general solution  $y = y_c + y_p$

$$y = c_1 x^2 + c_2 x^{-2} + 2x^2 \ln x - \frac{1}{2} x^2$$

We can combine  $c_1 x^2 - \frac{1}{2} x^2 = (c_1 - \frac{1}{2}) x^2 = k_1 x^2$

Letting  $k_2 = c_2$ , we can write

$$y = k_1 x^2 + k_2 x^{-2} + 2x^2 \ln x$$

Apply  $y(1) = 1$ ,  $y'(1) = 1$

$$y' = 2k_1 x - 2k_2 x^{-3} + 4x \ln x + 2x^2 \left(\frac{1}{x}\right)$$

$$y(1) = k_1 (1)^2 + k_2 (1)^{-2} + 2(1)^2 \ln 1 = 1$$

$$k_1 + k_2 = 1$$

$$y'(1) = 2k_1 (1) - 2k_2 (1)^{-3} + 4(1) \ln 1 + 2(1) = 1$$

$$2k_1 - 2k_2 + 2 = 1$$

$$2k_1 - 2k_2 = -1$$

Solve  $k_1 + k_2 = 1$   
 $2k_1 - 2k_2 = -1$

$\Rightarrow$

$$\begin{array}{r} 2k_1 + 2k_2 = 2 \\ 2k_1 - 2k_2 = -1 \end{array}$$

add  
subtract

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$$4k_1 = 1 \Rightarrow k_1 = \frac{1}{4}$$

$$4k_2 = 3 \Rightarrow k_2 = \frac{3}{4}$$

The solution to the IVP is

$$y = \frac{1}{4}x^2 + \frac{3}{4}x^{-2} + 2x^2 \ln x$$

# Method of Undetermined Coefficients (MUC) -vs- Variation of Parameters (VoP)

Determine which method(s) could be used to find a particular solution for each ODE.

(a)  $y'' + 9y = \sec^2(3x)$  VoP is the only option due to the secant on the right side.

(b)  $y'' + 9y = x^2 \cos(3x)$  MUC will work, so will VoP

(c)  $y'' - 2y' + y = \frac{e^x}{x}$  VoP is the only option due to the  $x^{-1}$  factor

(d)  $y'' - 2y' + y = xe^x$  Both methods can be used

## Find a Particular Solution

$$y'' - 2y' + y = \frac{e^x}{x}$$

$$y_1 = e^x, \quad y_2 = xe^x, \quad W = e^{2x}$$

$$u_1 = -x$$

$$u_2 = \ln x$$

$$y_p = u_1 y_1 + u_2 y_2$$

$$y_p = -x e^x + x e^x \ln x$$

Question: Is  $y_p = x e^x \ln x$  also correct?

It is since  $-xe^x$  could be combined  
w/  $c_2xe^x$  from  $y_c$ .

# Section 11: Linear Mechanical Equations

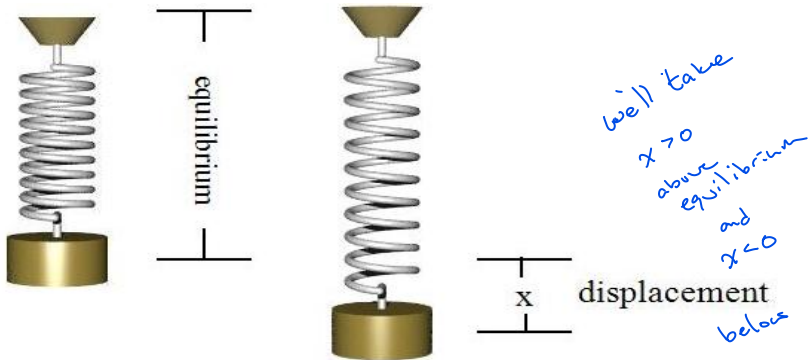
## Simple Harmonic Motion

We consider a flexible spring from which a mass is suspended. In the absence of any damping forces (e.g. friction, a dash pot, etc.), and free of any external driving forces, any initial displacement or velocity imparted will result in **free, undamped motion**—a.k.a. **simple harmonic motion**.

▶ Harmonic Motion gif



## Building an Equation: Hooke's Law



At equilibrium, displacement  $x(t) = 0$ .

$$\text{Hooke's Law: } F_{\text{spring}} = k x$$

**Figure:** In the absence of any displacement, the system is at equilibrium. Displacement  $x(t)$  is measured from equilibrium  $x = 0$ .

# Building an Equation: Hooke's Law

**Newton's Second Law:**  $F = ma$  (mass times acceleration)

$$a = \frac{d^2x}{dt^2} \implies F = m \frac{d^2x}{dt^2}$$

**Hooke's Law:**  $F = kx$  (proportional to displacement)

$$m \frac{d^2x}{dt^2} = -kx \implies m \frac{d^2x}{dt^2} + kx = 0$$

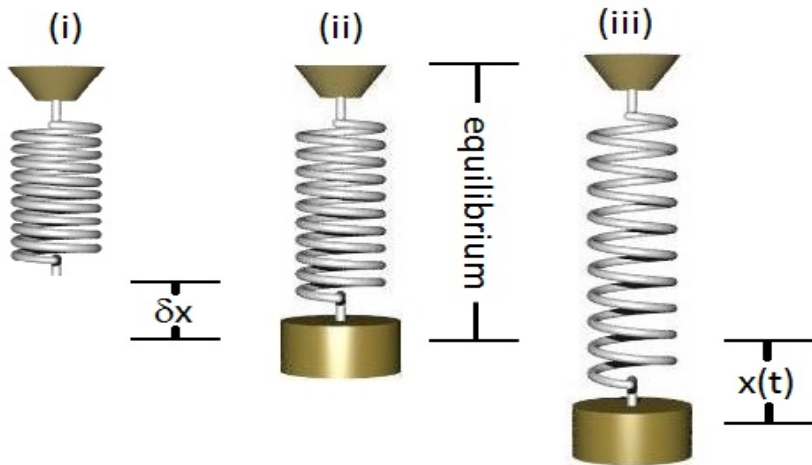
$$\frac{d^2x}{dt^2} + \frac{k}{m}x = 0 \quad \text{let } \omega^2 = \frac{k}{m}$$

$x$  solves  $x'' + \omega^2 x = 0$

A 2<sup>nd</sup> order, linear, homogeneous ODE w/

constant coefficients.

## Displacement in Equilibrium



**Figure:** Spring only, versus spring-mass equilibrium, and spring-mass (nonzero) displacement

## Obtaining the Spring Constant (US Customary Units)

If an object with weight  $W$  pounds stretches a spring  $\delta x$  feet in equilibrium, then by Hooke's law we compute the spring constant via the equation

$$W = k\delta x.$$

The units for  $k$  in this system of measure are lb/ft.

$$k = \frac{W \text{ lb}}{\delta x \text{ ft}}$$

## Obtaining the Mass (US Customary Units)

Note also that Weight = mass  $\times$  acceleration due to gravity. Hence if we know the weight of an object, we can obtain the mass via

$$W = mg.$$

We typically take the approximation  $g = 32 \text{ ft/sec}^2$ . The units for mass are  $\text{lb sec}^2/\text{ft}$  which are called slugs.

$$m = \frac{W}{g} \quad \text{slugs}$$

## Spring Constant and Mass (SI Units)

In SI units,

- ▶ Weight (force) would be in Newtons (N),
- ▶ Length would be in meters (m),
- ▶ Spring constant would be in N/m
- ▶ Mass would be in kilograms (kg)

It is customary to describe an object by its mass in kilograms. When we encounter such a description, we deduce the weight in Newtons

$$W = mg \quad \text{taking the approximation} \quad g = 9.8 \text{ m/sec}^2.$$