October 18 Math 2306 sec. 51 Fall 2024

Section 11: Linear Mechanical Equations

Simple Harmonic Motion

We consider a flexible spring from which a mass is suspended. In the absence of any damping forces (e.g. friction, a dash pot, etc.), and free of any external driving forces, any initial displacement or velocity imparted will result in **free, undamped motion**–a.k.a. **simple harmonic motion**.

[Harmonic Motion gif](http://en.wikipedia.org/wiki/File:Animated-mass-spring.gif)

Building an Equation: Hooke's Law

At equilibrium, displacement $x(t) = 0$.

Hooke's Law: $F_{\text{spring}} = k x$

Figure: In the absence of any displacement, the system is at equilibrium. Displacement $x(t)$ is measured from equilibrium $x = 0$.

Building an Equation: Hooke's Law

Newton's Second Law: $F = ma$ (mass times acceleration)

$$
a = \frac{d^2x}{dt^2} \quad \Longrightarrow \quad F = m \frac{d^2x}{dt^2}
$$

Hooke's Law: $F = kx$ (proportional to displacement)

$$
M \frac{d^{2}x}{dt^{2}} = -k \times 2
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Displacment in Equilibrium

Figure: Spring only, versus spring-mass equilibrium, and spring-mass (nonzero) displacement

Obtaining the Spring Constant (US Customary Units)

We'll use the following basic units when working in US Customary units:

- \blacktriangleright Force, including weight, in pounds (lb)
- Length in feet (ft)
- ▶ Mass in slugs^{*a*} (slug)
- \blacktriangleright Time in seconds (sec)

 a Note that one pound 1 lb = 1 $\frac{\text{slug ft}}{\text{sec}^2}$.

If an object with weight *W* pounds stretches a spring δ*x* feet in equilibrium, then by Hooke's law we compute the spring constant via the equation

$$
W = k\delta x \quad \text{i.e.,} \quad k = \frac{W}{\delta x}.
$$

The units for *k* **in this system of measure are lb/ft.**

Spring Constant and Mass (SI Units)

- \blacktriangleright Force, including weight, in Newtons (N),
- \blacktriangleright Length in meters (m),
- Mass in kilograms (kg)
- \blacktriangleright Time in seconds (sec)

The units for *k* **in this system of measure are N/m.**

Weight & Mass

When dealing with US units, weight is usually given in place of mass. In SI, mass is generally stated as mass. We can deduce mass, *m*, from weight, *W*, and vice versa via

$$
W = mg \quad \text{i.e.,} \quad m = \frac{W}{g},
$$

where *g* is the acceleration due to gravity.

The *Circular Frequency* ω

 $W = mg$ and $W = k\delta x$

Applying Hooke's law with the weight as force, we have
 $mg = k\delta x$. $mg = k\delta x$.

We observe that the value ω can be deduced from δx by

$$
\omega^2=\frac{k}{m}=\frac{g}{\delta x}.
$$

Provided that values for δ*x* and *g* are used in appropriate units, ω is in units of per second.

Simple Harmonic Motion

If x_0 is the initial position of the object (relative to equilibrium) and x_1 is its initial velocity, then the position x satisfies the initial value problem

$$
x'' + \omega^2 x = 0, \quad x(0) = x_0, \quad x'(0) = x_1 \tag{1}
$$

Solve this IVP.

The chordeis) c eqsals
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$$
r^{2} + w^{2} = 0 \Rightarrow r^{2} = -w^{2}
$$
\n
$$
r = \pm \sqrt{-w^{2}} = \pm \omega i \qquad d \pm i\sqrt{-w^{2}}
$$
\n
$$
q = 0 \qquad \beta = \omega
$$
\n
$$
\alpha_{1}(k) = C_{1}(w^{k}), \quad \chi_{1}(k) = S_{1}(w^{k})
$$
\n
$$
\chi(k) = C_{1}(w^{k}) + C_{2}S_{1}(w^{k}).
$$

 $x(0) = x_0, \quad x'(0) = x_1$ β PP β the I.C. $x'(k) = -\omega C_1 S_m(\omega k) + \omega C_2 C_3(\omega k)$ $X(\delta) = C_1 C_0 c (\delta) + C_2 S \ln(\delta) = X_0 \implies C_1 = X_0$ $X'(0) = -\omega C_1 \sin(\omega) + \omega C_2 C_3(\omega) = \chi_1 \implies C_2 = \frac{\chi_1}{\omega}$ The displacement at time tis $X(E) = X_0 \cos(\omega t) + \frac{X_1}{\omega} S_m(\omega t)$

Simple Harmonic Motion

The solution to [\(1\)](#page-7-0),

$$
x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t), \qquad (2)
$$

called the **equation of motion**.

Caution: The phrase **equation of motion** is used differently by different authors.

Some use this phrase to refer the IVP [\(1\)](#page-7-0). Others use it to refer to the **solution** to the IVP such as [\(2\)](#page-9-0).

Simple Harmonic Motion

$$
x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t)
$$

Characteristics of the system include

• the period
$$
T = \frac{2\pi}{\omega}
$$
,

- \blacktriangleright the frequency $f = \frac{1}{7} = \frac{\omega}{27}$ $\frac{\omega}{2\pi}$ ¹
- \blacktriangleright the circular (or angular) frequency ω , and
- \blacktriangleright the amplitude or maximum displacement $A = \sqrt{x_0^2 + (x_1/\omega)^2}$

¹ Various authors call *f* the natural frequency and others use this term for ω .

Amplitude and Phase Shift

We can formulate the solution in terms of a single sine (or cosine) function. Letting

$$
x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t) = A \sin(\omega t + \phi)
$$

requires

$$
A=\sqrt{x_0^2+(x_1/\omega)^2},
$$

and the **phase shift** ϕ must be defined by

$$
\sin \phi = \frac{x_0}{A}, \quad \text{with} \quad \cos \phi = \frac{x_1}{\omega A}.
$$

Amplitude and Phase Shift (alternative definition)

We can formulate the solution in terms of a single sine (or cosine) function. Letting

$$
x(t) = x_0 \cos(\omega t) + \frac{x_1}{\omega} \sin(\omega t) = A \cos(\omega t - \hat{\phi})
$$

requires

$$
A=\sqrt{x_0^2+(x_1/\omega)^2},
$$

and this **phase shift** $\hat{\phi}$ must be defined by

$$
\cos \hat{\phi} = \frac{x_0}{A}, \quad \text{with} \quad \sin \hat{\phi} = \frac{x_1}{\omega A}.
$$

Example

An object stretches a spring 6 inches in equilibrium. Assuming no driving force and no damping, set up the differential equation describing this system. $\mathbf{1}$ $\mathbf{1}$ $\mathbf{2}$ $\mathbf{3}$ $\mathbf{4}$

No damping and no driving
$$
\Rightarrow
$$
 \Rightarrow \Rightarrow

 $9 = 32$ $\frac{ft}{sec}$ (U.S. Customary take

Recall $x^2 = \frac{9}{6x}$, here $\delta x = 6m$
= $\frac{1}{2} ft$.

Example

A 4 pound weight stretches a spring 6 inches. The mass is released from a position 4 feet above equilibrium with an initial downward velocity of 24 ft/sec. Find the equation of motion in the form $x = A \sin(\omega t + \phi)$, and identify the period, amplitude, phase shift, and frequency of the motion. (Take $g =$ 32 ft/sec².)

$$
Jx = 6 \text{ in } \frac{1}{2}ft
$$

$$
Lx = 6 \text{ in } \frac{1}{2}ft
$$

$$
Lx = 6 \text{ in } \frac{1}{2}ft
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Lx = \frac{1}{2}gt
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 <math display="</math>

$$
W^2 = \frac{k}{m} = \frac{8 \frac{lb}{ft}}{\frac{16}{8} \frac{lb}{Rt}/s c^2} = 64 \frac{1}{sec^2} \text{ as } -\frac{1}{expt} \text{eVAL}
$$

$$
W^2 + kx = 0 \implies x'' + w^2x = 0
$$

$$
\frac{1}{8}x'' + 8x = 0 \implies x'' + 64x = 0
$$

We knew what the ODE should be because it had the same displacement in equilibrium as the last example.

We'll finish this exercise next time.