

## Section 5: First Order Equations: Models and Applications

We are considering another population model, one that accounts for environmental limitations on a population.

### Logistic Growth Model

The equation  $\frac{dP}{dt} = kP(M - P)$ , where  $k, M > 0$  is called a **logistic growth equation**.

Suppose the initial population  $P(0) = P_0$ . Solve the resulting initial value problem. Show that if  $P_0 > 0$ , the population tends to the carrying capacity  $M$ .

Logistic Growth:  $P'(t) = kP(M - P)$   $P(0) = P_0$

We recognized the equation as being both separable and Bernoulli.

We solved it as a Bernoulli equation and obtained the one-parameter family of solutions

$$P(t) = \frac{M}{1 + Ae^{-kMt}}$$

We need to apply the initial condition.

$$P(0) = \frac{M}{1 + Ae^0} = \frac{M}{1 + A} = P_0$$

$$\Rightarrow M = (1 + A)P_0 = P_0 + P_0 A$$

$$P_0 A = M - P_0 \Rightarrow A = \frac{M - P_0}{P_0}$$

$$P(t) = \frac{M}{1 + \left(\frac{M - P_0}{P_0}\right) e^{-kMt}}$$

$$= \frac{M}{1 + \left(\frac{M-P_0}{P_0}\right) e^{-kMt}} \left(\frac{P_0}{P_0}\right)$$

$$P(t) = \frac{MP_0}{P_0 + (M-P_0)e^{-kMt}}$$

If  $P_0 > 0$ ,

$$\lim_{t \rightarrow \infty} P(t) = \lim_{t \rightarrow \infty} \frac{MP_0}{P_0 + (M-P_0)e^{-kMt}}$$

$$= \frac{MP_0}{P_0 + 0} = \frac{MP_0}{P_0} = M$$

$P \rightarrow M$  as  $t \rightarrow \infty$ .

# Logistic Modeling

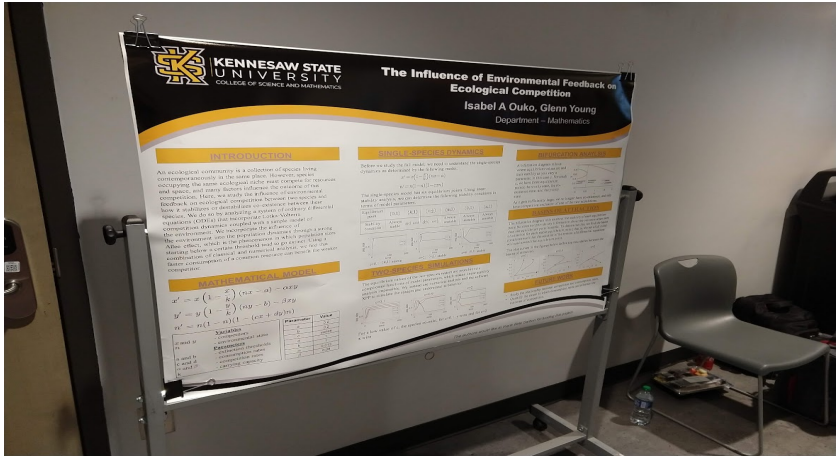


Figure: Poster of recent Birla Carbon scholar

# Logistic Modeling

## MATHEMATICAL MODEL

$$x' = x \left( 1 - \frac{x}{k} \right) (nx - a) - \alpha xy$$

$$y' = y \left( 1 - \frac{y}{k} \right) (ny - b) - \beta xy$$

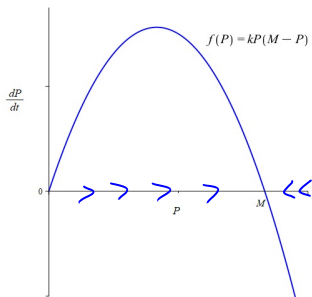
$$n' = n(1 - n)(1 - (cx + dy)n)$$

	<u>Variables</u>	<u>Parameter</u>	<u>Value</u>
$x$ and $y$	- competitors	$a$	0.2
$n$	- environmental state	$b$	0.2
$a$ and $b$	<u>Parameters</u>	$c$	varies
$c$ and $d$	- extinction thresholds	$d$	1
$\alpha$ and $\beta$	- consumption rates	$k$	1
$k$	- competition rates	$\alpha$	0.013
	- carrying capacity	$\beta$	0.08

**Figure:** The species equations include an extended logistic term with threshold and competition.

## Long Time Solution of Logistic Equation

$$\frac{dP}{dt} = kP(M - P) = -kP^2 + kMP.$$



**Figure:** Plot of  $P$  versus  $\frac{dP}{dt}$ . Note that  $\frac{dP}{dt} > 0$  if  $0 < P < M$  and  $\frac{dP}{dt} < 0$  if  $P > M$ .

## Logistic Growth with Breeding Threshold

Suppose we modify the logistic equation based on the assumption that the fish will only breed successfully if the population is above some minimum threshold  $N$  where  $0 < N < M$ . The new model is

$$\frac{dP}{dt} = kP(M - P)(P - N),$$

which is separable. But it is practically impossible to obtain an explicit solution,  $P(t) =$  “some function of  $t$ .”

**Remark:** Even without solving the equation, we can use the equation to predict the long time solution based on the initial population.

Solutions are given implicitly by  $\frac{(M - P)^N}{P^{M-N}(P - N)^M} = Ae^{-kMN(M-N)t}$ .

## Expected Long Time Solutions

$$\frac{dP}{dt} = kP(M - P)(P - N),$$

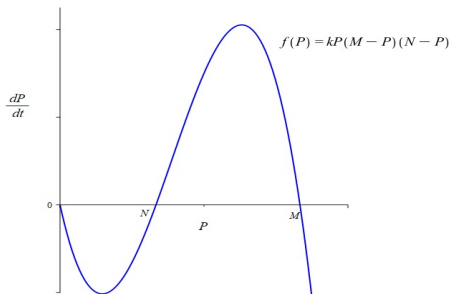
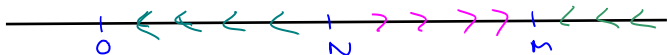


Figure: Plot of  $P$  versus  $\frac{dP}{dt}$  for the modified model.



## Expected Long Time Solutions

Use the given plot of  $F(P) = kP(M - P)(P - N)$  to determine the long time solution of  $\frac{dP}{dt} = F(P)$  if (a)  $0 < P(0) < N$ , (b)  $N < P(0) < M$  or (c)  $P(0) > M$ .



(a)  $0 < P(0) < N$

$\lim_{t \rightarrow \infty} P(t) = 0$

*extinction*

(b)  $N < P(0) < M$

$\lim_{t \rightarrow \infty} P(t) = M$

(c)  $P(0) > M$ ,

$\lim_{t \rightarrow \infty} P(t) = M$

# Qualitative Analysis

## Autonomous Equation

The differential equation  $\frac{dy}{dt} = f(t, y(t))$  is called **autonomous** if the right hand side does not depend explicitly on  $t$ —i.e., an autonomous equation has the form

$$\frac{dy}{dt} = F(y).$$

$$\frac{dy}{dt} = y(2-y)(y+3) \quad \text{autonomous}$$

$$\frac{dy}{dt} = t^2(y-3) \quad \text{non autonomous}$$

## Equilibrium Solutions

### Equilibrium Solutions

If  $y_0$  is a value such that  $F(y_0) = 0$ , then the constant function  $y(t) = y_0$  is called an **equilibrium** solution (or equilibrium point) of the autonomous differential equation  $\frac{dy}{dt} = F(y)$ .

**Note:** If  $y(0) = y_0$  and  $y_0$  is an equilibrium solution, then  $y(t) = y_0$  is a constant solution.

**Question:** What if  $y(0)$  is not an equilibrium value, but is close to an equilibrium value? What can we expect from the solution?

## Stability of Equilibrium Solutions

In general, we may classify an equilibrium solution of a given autonomous ODE as being

- ▶ **unstable**: solutions close, but not exact, will tend away from the equilibrium value,
- ▶ **stable**: solutions close, but not exact, will tend towards the equilibrium value<sup>1</sup>, or
- ▶ **semi-stable**: solutions close, but not exact, may tend towards or away from the equilibrium value depending on whether the solution is greater than or less than the equilibrium value.

**Note:** There are more detailed notions of stability, so there's more to the story. But we'll consider the above definitions here.

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<sup>1</sup>This is more accurately referred to as asymptotically stable

## Determining Stability of an Equilibrium Solution

To determine the nature of an equilibrium solution  $y_0$  for an ODE  $y' = F(y)$ , we can analyze the sign of  $F$  in the neighborhood of  $y_0$ . Suppose  $F$  is continuous on an open interval about  $y_0$ .

- ▶ If  $F$  changes sign from positive (+) to negative (-) as  $y$  passes through  $y_0$  (from left to right), then  $y_0$  is a stable equilibrium.
- ▶ If  $F$  changes signs from negative (-) to positive (+) as  $y$  passes through  $y_0$ , then  $y_0$  is an unstable equilibrium.
- ▶ If  $F$  doesn't change signs, then  $y_0$  is semi-stable.

If this reminds you of a *derivative test*, there's a good reason for that. Fortunately, it's easy to visualize the cases if you can obtain even a crude drawing of the graph of  $F$ .

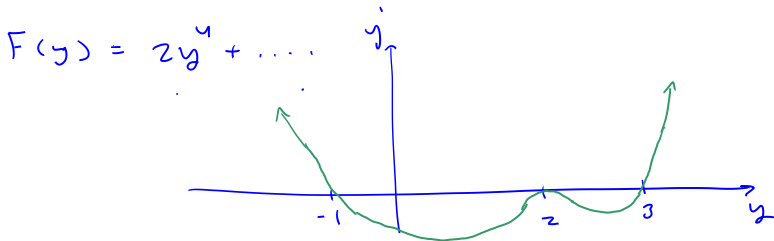
## Example

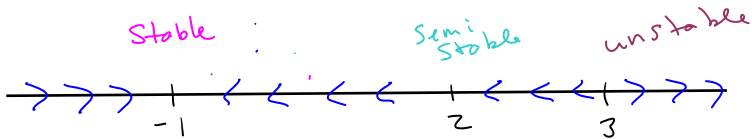
Consider the IVP

$$y' = 2(y + 1)(2 - y)^2(y - 3), \quad y(0) = k.$$

Determine the long time behavior,  $\lim_{t \rightarrow \infty} y(t)$ , if

- (a)  $k = -2$ ,      (b)  $k = 0$ ,      (c)  $k = 1$ ,  
(d)  $k = 2$ ,      (e)  $k = 2.5$ ,      (f)  $k = 4$ .





(a)  $k = -2,$

(b)  $k = 0,$

(c)  $k = 1,$

(d)  $k = 2,$

(e)  $k = 2.5,$

(f)  $k = 4.$

a)  $y(0) = -2$        $\lim_{t \rightarrow \infty} y(t) = -1$

b)  $y(0) = 0$        $\lim_{t \rightarrow \infty} y(t) = -1$

c)  $y(0) = 1$        $\lim_{t \rightarrow \infty} y(t) = -1$

d)  $y(0) = 2$        $\lim_{t \rightarrow \infty} y(t) = 2$

$y(t) = 2$

$$e) \quad y(0) = 2.5 \quad , \quad \lim_{t \rightarrow \infty} y(t) = 2$$

$$f) \quad y(0) = 4 \quad \lim_{t \rightarrow \infty} y(t) = \infty$$



## Models Derived in this Section

We have several models involving first order ODEs.

**Exponential Growth/Decay**

$$\frac{dP}{dt} = kP$$

**RC-Series Circuit**

$$R \frac{dq}{dt} + \frac{1}{C}q = E(t)$$

**LR-Series Circuit**

$$L \frac{di}{dt} + Ri = E(t)$$

**Classical Mixing**

$$\frac{dA}{dt} = r_i \cdot c_i - r_o \frac{A(t)}{V(0) + (r_i - r_o)t}$$

**Logistic Growth**

$$\frac{dP}{dt} = kP(M - P)$$