

Section 5: First Order Equations Models and Applications

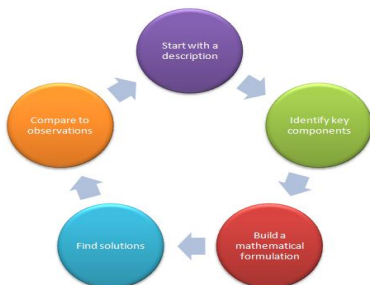


Figure: We've seen exponential growth/decay and simple linear circuits (RC or LR)

Logistic Differential Equation

The equation

$$\frac{dP}{dt} = kP(M - P), \quad k, M > 0$$

is called a **logistic growth equation**.

Solve this equation and show that for any initial population $P(0) \neq 0$, $P \rightarrow M$ as $t \rightarrow \infty$.

The ODE is a Bernoulli eqn.

$$\frac{dP}{dt} - kMP = -kP^2, \quad n=2$$

$$\frac{dy}{dx} + Q(x)y = f(x)y^n, \quad u = y^{1-n}$$

uses $\frac{du}{dx} + (1-n)Q(x)u = (1-n)f(x)$

$$\text{let } u = P^{-2} = P^{-1}$$

$$Q(t) = -kM \quad 1-n = -1$$

$$f(t) = -k$$

$$\text{so } \frac{du}{dt} + (-1)(-kM)u = (-1)(-k)$$

$$\frac{du}{dt} + kMu = k$$

$$Q_1(t) = kM, \quad \mu = e^{\int Q_1(t) dt} = e^{\int kM dt} = e^{kMt}$$

$$e^{kMt} (u' + kMu) = k e^{kMt}$$

$$\frac{d}{dt} [e^{kmt} u] = k e^{kmt}$$

$$\int \frac{d}{dt} [e^{kmt} u] dt = \int k e^{kmt} dt$$

$$e^{kmt} u = \frac{1}{m} e^{kmt} + C$$

$$u = \frac{1}{m} + C e^{-kmt}$$

$$u = P^{-1} \Rightarrow P = u^{-1}$$

$$P = \frac{1}{\frac{1}{m} + C e^{-kmt}} \cdot \frac{m}{m} = \frac{m}{1 + CM e^{-kmt}}$$

Let $P(0) = P_0$

$$P(0) = \frac{M}{1 + CM e^0} = P_0$$

$$M = P_0(1 + CM) = P_0 + P_0 MC$$

$$P_0 MC = M - P_0$$

$$C = \frac{M - P_0}{MP_0}$$

$$P(t) = \frac{M}{1 + \left(\frac{M - P_0}{MP_0}\right) M e^{-kMt}} \quad \frac{P_0}{P_0}$$

$$P(t) = \frac{MP_0}{P_0 + (M - P_0) e^{-kMt}}$$

We can look at the long term population taking $t \rightarrow \infty$.

$$\begin{aligned}\lim_{t \rightarrow \infty} P(t) &= \lim_{t \rightarrow \infty} \frac{M P_0}{P_0 + (M - P_0) e^{-k M t}} \\ &= \frac{M P_0}{P_0 + 0} = \frac{M P_0}{P_0} = M\end{aligned}$$

Section 6: Linear Equations Theory and Terminology

Recall that an n^{th} order linear IVP consists of an equation

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = g(x)$$

to solve subject to conditions

$$y(x_0) = y_0, \quad y'(x_0) = y_1, \quad \dots, \quad y^{(n-1)}(x_0) = y_{n-1}.$$

The problem is called **homogeneous** if $g(x) \equiv 0$. Otherwise it is called **nonhomogeneous**.

Theorem: Existence & Uniqueness

Theorem: If a_0, \dots, a_n and g are continuous on an interval I , $a_n(x) \neq 0$ for each x in I , and x_0 is any point in I , then for any choice of constants y_0, \dots, y_{n-1} , the IVP has a unique solution $y(x)$ on I .

Put differently, we're guaranteed to have a solution exist, and it is the only one there is!

Homogeneous Equations

We'll consider the equation

$$a_n(x) \frac{d^n y}{dx^n} + a_{n-1}(x) \frac{d^{n-1} y}{dx^{n-1}} + \cdots + a_1(x) \frac{dy}{dx} + a_0(x)y = 0$$

and assume that each a_i is continuous and a_n is never zero on the interval of interest.

Theorem: If y_1, y_2, \dots, y_k are all solutions of this homogeneous equation on an interval I , then the *linear combination*

$$y(x) = c_1 y_1(x) + c_2 y_2(x) + \cdots + c_k y_k(x)$$

is also a solution on I for any choice of constants c_1, \dots, c_k .

This is called the **principle of superposition**.

Corollaries

- (i) If y_1 solves the homogeneous equation, then any constant multiple $y = cy_1$ is also a solution.
- (ii) The solution $y = 0$ (called the trivial solution) is always a solution to a homogeneous equation.

Big Questions:

- ▶ Does an equation have any **nontrivial** solution(s), and
- ▶ since y_1 and cy_1 aren't truly *different* solutions, what criteria will be used to call solutions distinct?

Linear Dependence

Definition: A set of functions $f_1(x), f_2(x), \dots, f_n(x)$ are said to be **linearly dependent** on an interval I if there exists a set of constants c_1, c_2, \dots, c_n with at least one of them being nonzero such that

$$c_1 f_1(x) + c_2 f_2(x) + \dots + c_n f_n(x) = 0 \quad \text{for all } x \text{ in } I. \quad (1)$$

A set of functions that is not linearly dependent on I is said to be **linearly independent** on I .

NOTE: Taking all of the c 's to be zero will **always** satisfy equation (1). The set of functions is linearly **independent** if taking all of the c 's equal to zero is the **only** way to make the equation true.

Example: A linearly Independent Set

The functions $f_1(x) = \sin x$ and $f_2(x) = \cos x$ are linearly independent on $I = (-\infty, \infty)$.

We want to show that $c_1 f_1(x) + c_2 f_2(x) = 0$
for all x is only true if $c_1 = c_2 = 0$.

Suppose $c_1 \sin x + c_2 \cos x = 0$ for
all real x .

The equation has to hold when $x=0$.

We get $c_1 \sin(0) + c_2 \cos(0) = 0$

$\underset{0 \nearrow}{\sin(0)} \quad \quad \quad \underset{1 \nearrow}{\cos(0)}$

This equation is $c_1(0) + c_2(1) = 0 \Rightarrow c_2 = 0$

Now the equation becomes

$$C_1 \sin x = 0 \quad \text{for all } x.$$

This holds when $x = \frac{\pi}{2}$. That is

$$C_1 \sin \frac{\pi}{2} = 0$$

1 ↗

$$\text{Hence } C_1 = 0.$$

Thus $C_1 f_1(x) + C_2 f_2(x) = 0$ for all x
only if $C_1 = C_2 = 0$.

We conclude that $f_1(x) = \sin x$ and
 $f_2(x) = \cos x$ are linearly independent.