

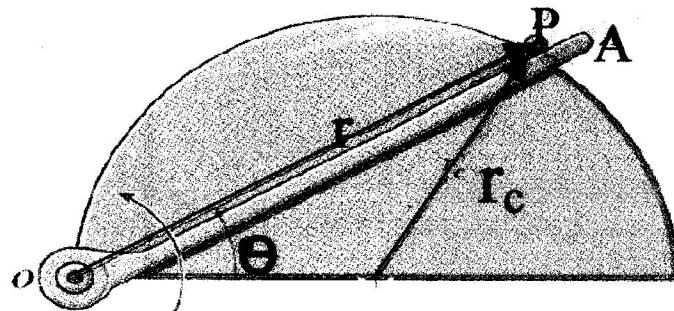
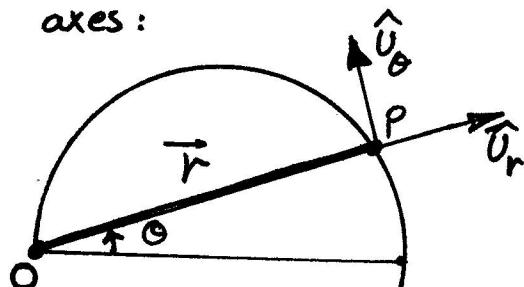
Given: The ball (P) is guided along the vertical circular path.

$$W = 0.5 \text{ lb}, \dot{\theta} = 0.4 \text{ rad/s}, \ddot{\theta} = 0.8 \text{ rad/s}^2, r_c = 0.4 \text{ ft}$$

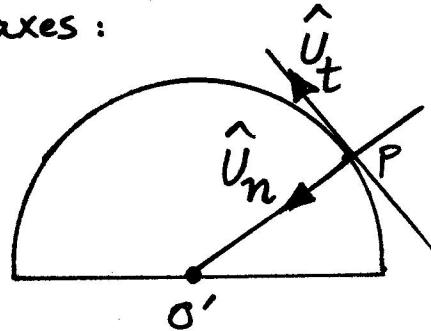
Find: Force of the arm OA on the ball when $\theta = 30^\circ$.

Solution :

- 1- Lets show the positive directions of radial and transverse axes:



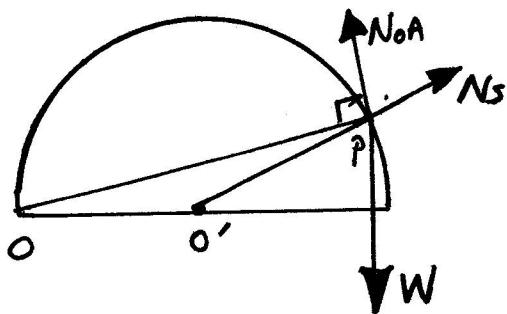
- 2- Lets show the positive directions of normal and tangential axes:



\hat{u}_t is the unit vector along t , which is tangent to the path and in the direction of motion.

\hat{u}_n is \perp to the tangent to the path pointing toward the center of curvature.

- 3- Now lets show all the forces we have here:

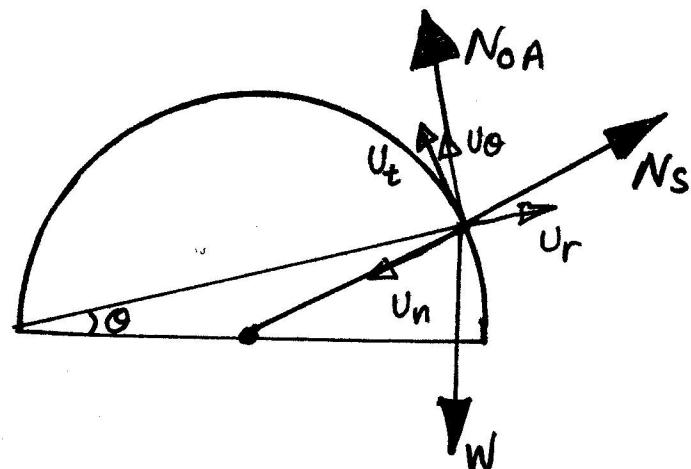


N_s = Normal force \perp Path or in the direction of n_2 and outside of the circular surface.

N_{oA} is \perp OP (\perp to the \hat{u}_r)

W is weight and is downward.

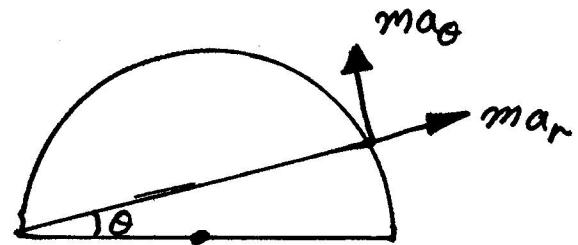
4- Now lets combine the FBD and the coordinates systems:



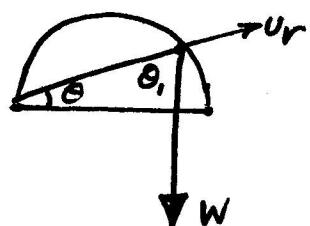
So only NoA is along \hat{U}_θ and other forces make angles with \hat{U}_r or \hat{U}_θ .

5- Lets show the kinetic diagram.

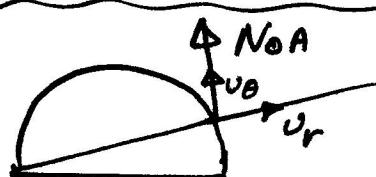
They are along \hat{U}_r and \hat{U}_θ as shown.



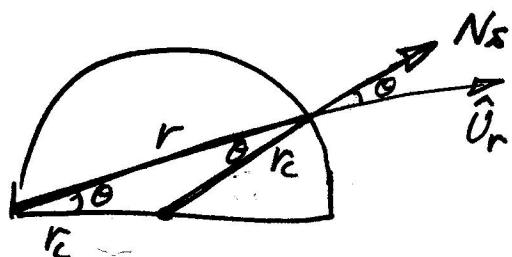
Now the task is finding the angles between the forces we have and \hat{U}_r and \hat{U}_θ :



The angle that W makes with U_r is θ_1 , and it is the complementary angle:
 $\theta + \theta_1 = 90$ $\theta_1 = 90 - 30 = 60$



NoA is along \hat{U}_θ so it has no component along U_r .



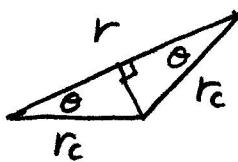
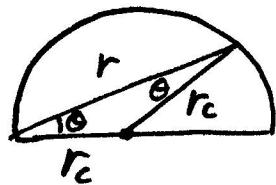
N_s makes an angle α with \hat{U}_r as shown.

Let's solve for the unknowns after writing the equations of motion:

$$\sum F_r = m a_r = m(r\ddot{\theta}^2)$$

$$\sum F_\theta = m a_\theta = m(r\ddot{\theta} + 2r\dot{\theta}^2)$$

How do we write an equation describing r in terms of θ ?



$$r = 2r_c \cos\theta$$

$$r_c = 0.4 \Rightarrow$$

$$r = 0.8 \cos\theta$$

General Eqs for all θ s	$\theta = 30^\circ, \dot{\theta} = 0.4, \ddot{\theta} = 0.8$
$r = 0.8 \cos\theta$	$r = 0.693 \text{ ft } (\text{at } \theta = 30^\circ)$
$\dot{r} = -0.8 \sin\theta \cdot \dot{\theta}$	$\dot{r} = -0.16 \text{ ft/s}$
$\ddot{r} = -0.8 [\cos\theta \dot{\theta}^2 + \sin\theta \ddot{\theta}]$	$\ddot{r} = -0.431 \text{ ft/s}^2$
$a_r = \ddot{r} - r\dot{\theta}^2$	$a_r = -0.542 \text{ ft/s}^2$
$a_\theta = r\ddot{\theta} + 2\dot{r}\dot{\theta}$	$a_\theta = 0.426 \text{ ft/s}^2$
	$m = \frac{W}{g} = \frac{0.5}{32.2} = 0.0155 \text{ slug}$

Eqs of motion:

$$\sum F_r = m a_r = N_s \underbrace{\cos\theta}_{} - W \underbrace{\cos\theta}_{} = m a_r \rightarrow \text{find } N_s$$

$$\sum F_\theta = m a_\theta = N_o A + N_s \sin\theta - W \cos\theta = m a_\theta \rightarrow \text{find } N_o A$$

$$N_s = 0.279 \text{ lb}$$

$$N_o A = 0.3 \text{ lb}$$

ψ is not required here. But it is 120° . See if you can verify this!